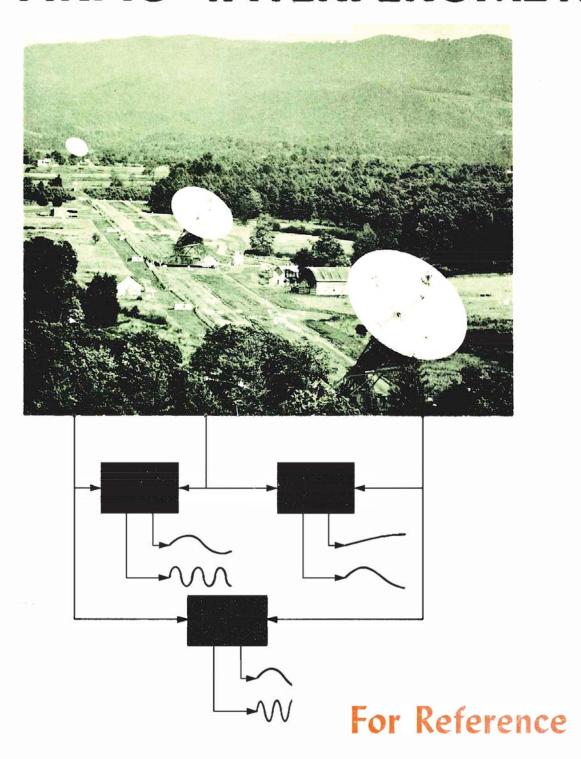
# AN INTRODUCTION TO THE NRAO INTERFEROMETER



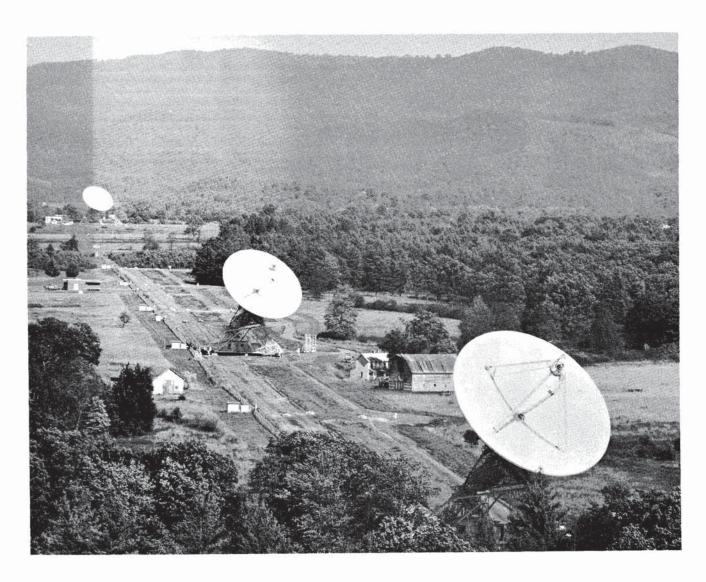
## AN INTRODUCTION TO THE NRAO INTERFEROMETER

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February 1973 Edition\*\*

- \* Operated by Associated Universities, Inc., under contract with the National Science Foundation.
- \*\* Chapters in the Introduction will be updated at different times with a reissue title page to identify the latest updates included.



The NRAO Interferometer

#### SPECIAL NOTE TO READERS OF FEBRUARY 1973 EDITION

The user should be warned that the February 1973 edition of this Introduction to the NRAO Interferometer must be used with four limitations in mind.

- 1. Numerous errors may still infest its pages even though they have been put to considerable scrutiny.
- 2. The "standard" package of interferometer data reduction programs is still in a state of flux as we attempt to shift from a mode where the package consists of a miscellany written by many individuals to a set of programs written, consistently maintained, and documented by a combination of one programmer and one scientific project director.
- 3. Nothing in this documentation sheds light on the 4-element interferometer system (using the portable 45 foot) that is currently being put into operation and will be an integral part of the system by the summer of 1973.
- 4. Although the next edition will contain an extensive chapter on the programs to be used to extract scientific results from fully calibrated interferometric data, e.g., the mapping programs—this is not covered in the February 1973 edition. This is done so that the introduction to the more fundamental things can be distributed without further delay.

Another edition is planned for completion by September 1973. In this edition the errors in the present work can be removed if the readers will take the trouble to inform the author. Also, the system as described in the next edition will be a 4-element system. Furthermore, the chapter dealing with the analysis and interpretation of interferometric data will be included.

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# **PREFACE**

The purpose of this introduction is to blend together a discussion of the basic principles of interferometry, a discussion of the particular characteristics of the NRAO interferometer, and an explicit discussion of most of the practical details that must be dealt with to do science with the NRAO interferometer. The level of this introduction is aimed at the astronomer who has never done radio interferometry and who is interested only in the technical details that must be grasped in order to do science with the instrument. For this reason we will spend less time on certain technical areas than some people would like. Further, we will deal mainly with the simplest and most straightforward methods of doing science with an interferometer. We assume that if the reader already has the expertise to want to do things differently, or if experience with the interferometer brings him to that stage of expertise, then he need not pay much attention to the procedures discussed here.

The virtually automatic operation of the interferometer in Green Bank makes life deceptively easy during the initial stages of an observing program. This paves the way for a number of possible mistakes to be made. After the observing is completed and the data reduction is under way, one can find out insufficient calibration was made or that the planning of observing time for program sources was insufficient to accomplish desired scientific objectives. Even more importantly, failure to monitor the behavior of at least the calibrators, while observing is under way, can cause failure to detect subtle malfunctions in the system. Because it is simple to pay attention to a few important things, it is almost entirely the observer's fault when, a few days or months later, he discovers that "something was wrong with the equipment" and large amounts of data are partially or completely useless. Early de-

tection of anomalies will allow many problems to be fixed long before an observing session is ended.

It is also common for the observer to fail to plan to spend enough time reducing data in Charlottesville. The complexities of interferometry make it necessary for almost everyone to rely upon standard reduction and analysis programs. The observer must plan to spend enough time reducing his data with these programs. Despite considerable effort to make such reductions as automatic and faultless as possible, unusual problems frequently occur that take more time to solve than expected.

This introduction will deal only with the NRAO interferometer as a dual-channel, continuum instrument operating at 2695 and 8085 MHz. The interferometer also has the capability, when used with the 412-channel autocorrelator, of doing 21-cm line interferometry. This system is considerably more complicated to use than the dual-frequency continuum system. Those interested in line interferometry should read the documentation written by M. C. H. Wright and C. Moore.

Finally, the goal of this introduction and the reduction and analysis programs described therein is to cover only about 90% of the problems that might arise or the procedures and programs an observer might want to use. For those who wish to employ procedures beyond the scope of this introduction, we assume that a combination of the observer's own expertise and discussions with the appropriate NRAO staff will be needed.

Many members of the NRAO staff and a number of others familiar with the NRAO interferometer have contributed ideas, criticisms, and suggestions for this introduction. Particular thanks are due to B. Balick, R. Brown, E. Fomalont, P. Kronberg, J. Spencer, and C. Wade.

There is no upper limit to the amount of thanks due to Phyllis Jackson for typing this book.

## CHAPTER I

#### THEORETICAL BASIS OF INTERFEROMETRY

#### 1. Introduction

A thorough knowledge of the theory of interferometry is essential before one can do science with an interferometer. The main problem is not that an observer need understand the inner workings of the complex electronics, but rather one must master a large number of new concepts and a complicated terminology. In this chapter we discuss the theoretical basis of interferometry.

Since all interferometers are made up of different numbers of pairs of antennas, we will develop most of the theory in terms of a simple two-telescope interferometer which we can think of as one of the pairs in the NRAO interferometer.

In observing with an interferometer we are making measurements enormously more complicated than simply measuring the amount of radio power received by the antennas. The cross-correlation of signals from two antennas produces partial information not only about the intensity of all sources in the beams of the antennas but also information about their position in the sky relative to the position at which the interferometer is being pointed. Because of the position information being obtained, we will be very concerned with the geometry and coordinate systems involved in observing. Because an interferometer only obtains partial information about radiation sources in the antenna beams, for reasons we will discuss later, the observer must be very careful about interpreting his partial data. As will hopefully be clear later, one has almost completely summarized the essential characteristics of an interferometer

when one says it measures the Fourier components of the apparent intensity distribution of sources in the antenna beams.

Before describing the behavior of an interferometer, a few fundamental concepts must be defined. In observing with an interferometer, we point the antennas at a particular point\* in the sky with a specified right ascension and declination  $(\alpha, \delta)$ . We will call this position the reference position. It is best thought of as the position at which we are attempting to point the antennas, since it always turns out that due to errors in instrumental parameters, the actual position of observation will differ by a small amount from the actual reference position. We define the position of an arbitrary point in the field of view of the antennas in terms of a vector displacement ( $\Delta\alpha$ ,  $\Delta\delta$ ) from the reference position. Note that we have used the phrase "field of view" to describe the primary region of the sky to which the antennas are sensitive; this is important because we are not just collecting information about the total radiation in an antenna beam, rather we are collecting information about the properties and positions of all radiation sources in the field of view. When we discuss a source position, we are referring to the location of a radio source at some position in the field of view, and this will frequently differ from the reference position being observed.

Finally, the NRAO interferometer is a tracking interferometer, so all observing consists of following a particular right ascension and declination as a function of sidereal time (or hour angle). This will be assumed when we speak of observing a particular source or mapping a particular field of view.

#### 2. Response to a Strong Point Source

#### (a) Definitions.

We begin with a discussion of the special case where we observe

<sup>\*</sup> As any radio astronomer will realize, we assume that pointing errors for each antenna have been determined and corrected for.

and track a region of the sky containing a strong point source which completely dominates the radiation received by the antennas.

Let us define:

 $s_{0}$  = unit vector pointing from each telescope to the reference position  $(\alpha, \delta)$ .

s = unit vector pointing to the source position

 $\Delta s = s - s = \begin{pmatrix} \Delta \alpha \\ \Delta \delta \end{pmatrix} = \text{vector displacement}$ 

from reference position to source position

 $\nu, \lambda, \omega$  = frequency, wavelength, and angular frequency of wave front under consideration

 $v_0, \omega_0$  = frequency and angular frequency of local oscillator

 $\mathbb{R}$  = baseline vector extending from telescope 2 to telescope 1

B = |B| = number of wavelengths that make up the base-line length

 $\lambda B$  = physical length of baseline in same units as  $\lambda$ 

In Figure I-1 we show a schematic representation of two elements of an interferometer. The fundamental basis of interferometry is the fact that wave fronts representing radiation which left a point source at the same time\* arrive at slightly different times at telescopes 1 and 2. In particular, a wave front reaches antenna 1 (cf. Figure I-1) at a time

$$\Delta t = \lambda \frac{B \cdot s}{c}$$

later than at antenna 2. This corresponds to a phase difference of

<sup>\*</sup> Since all radio sources are sufficiently distant, we can assume that all wave fronts from the point source are parallel when reaching the antennas.

# POINT SOURCE

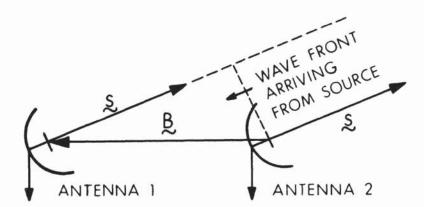


Fig. I-1. Geometry in which two antennas separated by a baseline vector  $\beta$  receive a wave front arriving from a source, where the direction to the source is defined by the unit vector  $\varsigma$ .

$$\omega \Delta t = \frac{2\pi \nu \lambda}{2} \frac{B \cdot s}{2}$$

and using  $c = \lambda v$ , we get

$$\omega \Delta t = 2\pi \mathcal{B} \cdot \mathcal{S}$$
 I-(1)

# (b) How Incoming Signals Are Converted to Fringe Amplitude and Fringe Phase.

We now wish to discuss what happens to the information about the incoming wave front in the interferometer. From now until we arrive at Equation I-(2), we must suffer through a discussion of what happens in the innards of the electronics of the interferometer. The reader is warned that the discussion will be too sketchy and simplified to satisfy those with a technical turn of mind and too extensive for those who feel that they don't want to get bogged down in technical details. Those who are willing to accept Equation I-(2) on faith can skip the following discussion which precedes that equation.

Let E be the electric field strength of the incoming wave front and  $G_1(\nu)$  and  $G_2(\nu)$  be the amplifier gains for frequencies between  $\nu$  and  $\nu + d\nu$  for telescopes 1 and 2. In the end, these gains will represent the effects of all the amplification stages in the system. The output voltages for telescopes 1 and 2, due to radiation in the frequency range  $\nu$  to  $\nu + d\nu$ , when the same wave front arrives, are:

$$V_2(t) = \left[\frac{1}{2} G_2(v) E dv\right]^{1/2} \cos \omega t$$

and

$$V_1(t + \Delta t) = \left[\frac{1}{2} G_1(v) E dv\right]^{1/2} \cos \omega(t + \Delta t)$$

where the factors of one-half represent the fraction of the assumed unpolarized signal received by a single circular feed.

As shown in the schematic in Figure I-2, the signals are then "mixed" with the local oscillator (LO) with angular frequency  $\omega_{0}$ . The equations in Figure I-2 deal only with the changes in the time-dependent factors of the signal voltages. The mathematical equivalent of the mixing process is multiplication of  $V_1(t + \Delta t)$  and  $V_2(t)$  by cos  $\omega_0 t$ . After this process the signal consists of high and low-frequency terms. The IF (intermediate frequency) bandpass filter rejects the high-frequency terms. Next a compensating time delay  $\Delta \tau$  is inserted in the lines from telescope 2 so that, despite the geometrical delay At, the time difference in arrival at the multiplier is only  $(\Delta \tau - \Delta t)$ , a quantity that we must make as small as possible for reasons that will be obvious in a moment. Multiplication of the signals from the two telescopes, which is the basic process by which one "correlates" the information about the wave front as seen by the two telescopes, once again results in a highfrequency and a low-frequency term, the latter being the only one to survive a low-pass filter. We then get the final result that radiation in the frequency range v to v + dv, from the point source in the field being tracked, produces a response in the interferometer proportional to

$$\cos \left[ (\omega - \omega_{0}) (\Delta \tau - \Delta t) - \omega_{0} \Delta t \right]$$

and this factor represents the time-dependent part of the correlated signal produced by the wave front. If we could assume that all sources were monochromatic, with frequency  $\nu_o$ , or, if it were technically possible to make  $(\Delta\tau-\Delta t)$  small enough, then the response of the interferometer would be

$$R(\Delta t) \propto \cos \omega_0 \Delta t$$
.

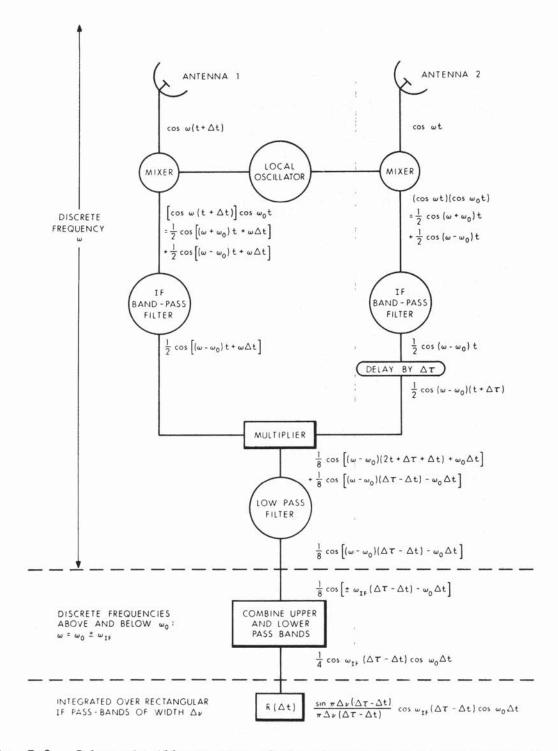


Fig. I-2. Schematic illustration of the changes in the time dependent part of the information about a single wave front, as received by two antennas, as this information is processed by interferometer electronics.

However, no source is monochromatic, and it is not possible to keep ( $\Delta\tau$ -  $\Delta t$ ) small enough; therefore the best we can do is to deal with sharply defined IF passbands. The NRAO interferometer is a so-called double sideband system. Frequencies in the upper and lower sidebands are denoted by  $\omega = \omega_0 \pm \omega_{\rm IF}$ . The range of IF frequencies is 5 to 35 MHz and the bandwidth is therefore 30 MHz. Useful properties are obtained by always combining upper and lower sidebands. Thus the signal out of the low pass filter is the sum of two terms, the combination of the upper and lower passbands:

$$\begin{split} \frac{1}{8} \cos \left[ \pm \ \omega_{\text{IF}}(\Delta \tau - \Delta t) - \omega_{\text{O}} \Delta t \right] \\ &= \frac{1}{8} \left\{ \cos \left[ \omega_{\text{IF}}(\Delta \tau - \Delta t) - \omega_{\text{O}} \Delta t \right] + \cos \left[ -\omega_{\text{IF}}(\Delta \tau - \Delta t) - \omega_{\text{O}} \Delta t \right] \right\} \\ &= \frac{1}{4} \cos \ \omega_{\text{IF}}(\Delta \tau - \Delta t) \cos \ \omega_{\text{O}} \Delta t. \end{split}$$

This, however, represents only the effects of wave fronts with frequencies  $\omega_{_{\scriptsize O}}$  +  $\omega_{_{\scriptsize IF}}$  and  $\omega_{_{\scriptsize O}}$  -  $\omega_{_{\scriptsize IF}}$ , whereas one must include all of the upper and lower sidebands. If we assume  $G_1(\nu)$  and  $G_2(\nu)$  are perfect rectangular passbands with widths  $\Delta\nu$  and with centers  $\pm$   $\omega_{_{\scriptsize IF}}$  from  $\omega_{_{\scriptsize O}}$ , then integration over the bandpasses gives the following integral:

$$\int_{G_1(v_{IF})} G_2(v_{IF}) E^2 \cos 2\pi v_{IF}(\Delta \tau - \Delta t) dv_{IF}$$

$$\approx \overline{G_1 G_2 E^2} \frac{\sin \pi \Delta v (\Delta \tau - \Delta t)}{\pi \Delta v (\Delta \tau - \Delta t)} \cos \omega_{IF}(\Delta \tau - \Delta t).$$

The total response of the interferometer can then be written as

$$R(\Delta \tau, \Delta t) = \frac{1}{2} \frac{1}{G_1 G_2 E^2} \frac{\sin \pi \Delta \nu (\Delta \tau - \Delta t)}{\pi \Delta \nu (\Delta \tau - \Delta t)} \cos \omega_{IF} (\Delta \tau - \Delta t) \cos \omega_{O} \Delta t \qquad I-(2)$$

where  $\overline{G_1G_2E^2}$  represent the mean of a complicated function. We always

assume that we can neglect the effects of frequency dependence of  $E^2$  over the range  $\pm$  15 MHz about 2695 and 8085 MHz. The average  $\overline{G_1G_2}$  then generally reflect the effects of non-rectangular bandpasses. It is never in practice possible to find  $\overline{G_1G_2}$  from a knowledge of  $G_1(\nu)$  and  $G_2(\nu)$ ; therefore all amplitude (or flux) calibration of the interferometer is based upon empirically determining the response of the interferometer to a point source of known flux density.

Equation I-(2) shows that unless ( $\Delta\tau$ - $\Delta t$ ) is very small; that is, the inserted delays compensate very well to the continuous changes in  $\Delta t$ , there will be considerable loss of signal strength. The function

$$F(\Delta \tau - \Delta t) = \frac{\sin \pi \Delta \nu (\Delta \tau - \Delta t)}{\pi \Delta \nu (\Delta \tau - \Delta t)} \cos \omega_{IF}(\Delta \tau - \Delta t)$$

is sometimes called the envelope function. In the NRAO interferometer the goal is to maintain  $F(\Delta\tau-\Delta t)$  at about 0.98 to 1.0; this is done by allowing the computer to control changes in a digital delay system in steps as small as 2 nanosceconds. When all delays are working, we operate on the assumption that

$$R(\Delta t) = (constant) \times cos \omega_0 \Delta t$$

for a point source and lump all of the following under the heading of "noise" in the calibration of the constant in the above equation: (1) variations due to changing finite values of  $(\Delta\tau-\Delta t)^*$ ; (2) changes in  $\overline{G_1G_2}$  due to fluctuations in amplification gains and due to imperfections in the upper and lower sidebands; (3) variations due to real effects of  $E^2$  varying over the bandpasses; and (4) variations due to failure of the factor of one-half to represent the real polarization effects. Only

<sup>\*</sup> Sometimes systematic errors occur which can be corrected for by special calibration of amplitude as a function of delay setting.

part of the latter effects can be eliminated by the proper polarization calibration.

The response function for an interferometer,  $R(\Delta t)$ , always produces sinusoidal variations which are described as <u>fringes</u>. In the special case discussed so far the proportionality constant would describe the <u>fringe</u> <u>amplitude</u> and the product  $\omega_0 \Delta t$  would be the fringe phase.

#### (c) Relation Between Fringe Amplitude and Flux Density

Because the interferometer response is proportional to  $\overline{E^2}$ , we can identify the constant of proportionality (fringe amplitude) in the interferometer response with the flux density, S, of a point source. Therefore, we can write

$$R(\Delta t) = S \cos \omega_0 \Delta t = S \cos 2\pi \beta \cdot g$$
 I-(3)

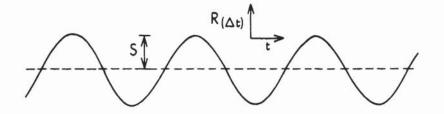
for a properly calibrated interferometer. If the source were too far from the center of the beam, the coefficient in Equation I-(3) would be modified by the antenna sensitivity pattern, but we will neglect this detail for the present time.

Figure I-3a shows the theoretical response to a point source. Figure I-3b shows an example of the actual response to a point source. The effects of noise clearly show up as fluctuations about the mean response.

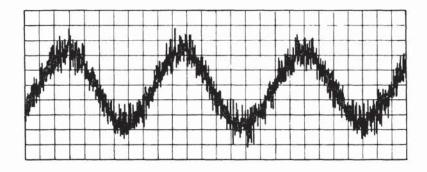
If the delays are not inserted, we get results as shown in Figure I-3c for a point source. The normal response,  $\cos \omega_0 \Delta \tau$ , is modulated by the more slowly varying envelope function.

The responses described by Equation I-(3) and Figure I-3 are frequently called fringes. As the telescopes track a source across the sky  $\omega_{\scriptscriptstyle O} \Delta t = 2\pi \ \, \beta \ \, \cdot \ \, \xi \ \, \text{changes continuously, producing continual sinusoidal}$  variation of R( $\Delta t$ ) which depends only on  $\beta$  and  $\beta$ . This sinusoidal variation is called the "fringe pattern" of the interferometer.

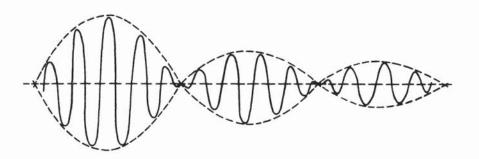
At this point let us emphasize a fundamental point of interferometry: the only flux calibration possible is the comparison of the



a. Theoretical Response
To Point Source



b. Actual Response To Point Source



c. Theoretical Response To Point Source Without Delay Insertion

Fig. I-3. Three different aspects of the interferometer response to a point source.

fringe amplitude of one point source with that of another source. There is no comparison "cal" in the system. One simply observes a point source that you know (or assume) has a particular flux density; then the flux density for all point sources can be determined relative to this standard. In practice, only gain instabilities, telescope pointing errors, and very minor effects of attentuation by the atmosphere can affect these conclusions. The interferometer is amplitude calibrated by doing two things:

(1) observing a number of point sources with known flux densities to determine the coefficient in Equation I-(3); and (2) monitoring point sources once an hour or so throughout the observing program to make it possible to detect changes in gain which result in changes in the calibration constants.

Now that we have established Equation I-(3) as the first basic equation of interferometry, let us consider the geometry of  $\S$  and  $\S$  as related to astronomical coordinate systems.

#### 3. Geometry of Interferometry

## (a) Geometry and Coordinates

In Figure I-4 both right-handed (xyz) and left-handed (x'y'z') coordinate systems are shown. The z (or z') axis points to the equatorial north pole and the other two axes are in the equatorial plane, with the y-axis pointing east and the y'-axis pointing west.

With  $(\theta,\phi)$  = angular coordinates in a spherical right-handed system, and  $(\theta',\phi')$  = angular coordinates in a spherical left-handed system, we see that they relate to the hour angle (H) and the declination  $(\delta)$  by:

$$\theta' = \theta = 90^{\circ} - \delta$$
  
 $\phi' = H = 180^{\circ} - \phi$ ,

hence the use of hour angle forces us to use a left-handed coordinate system. This creates one of the conceptual problems in interferometry, the mixture of right- and left-handed coordinate systems. Depending

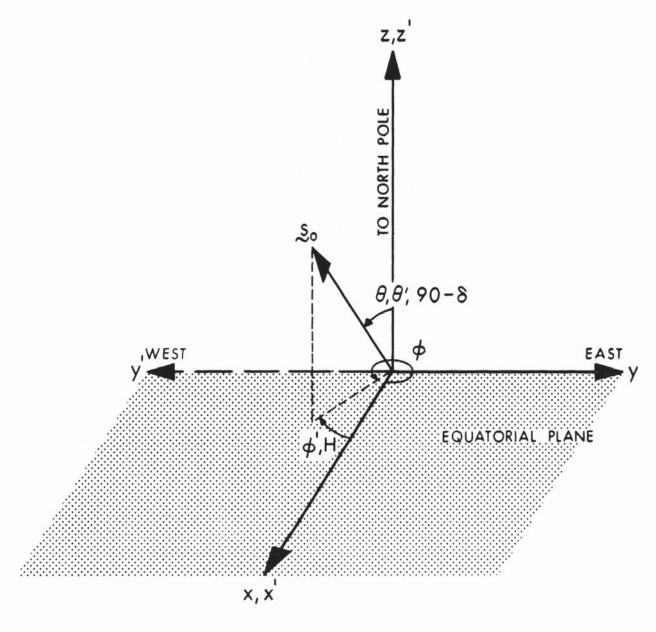


Fig. I-4. Geometry relating a rectangular coordinate system, in which the z-axis towards the North Pole and the y-axis is east, to spherical polar coordinates and hour angle-declination coordinates. The unprimed quantities refer to right-handed coordinates and the primed quantities refer to left-handed coordinates.

upon which coordinate system is used to describe the components of a vector like  $s_0$ , we indicate handedness by LH (left-handed) or RH (right-handed), i.e.,

$$S_{0} = \begin{bmatrix} \sin \theta \cos \phi \\ \sin \theta \sin \phi \\ \cos \theta \end{bmatrix}_{RH} = \begin{bmatrix} \sin \theta' \cos \phi' \\ \sin \theta' \sin \phi' \\ \cos \theta' \end{bmatrix}_{LH} = \begin{bmatrix} \cos \delta \cos H \\ -\cos \delta \sin H \\ \sin \delta \end{bmatrix}_{LH} I-(4)$$

We define h and d to be the hour angle and declination of the baseline vector, hence

$$\frac{B}{\frac{\Delta}{B}} = \begin{pmatrix} \cos d \cos h \\ -\cos d \sin h \\ \sin d \end{pmatrix} \stackrel{\cong}{LH} \begin{pmatrix} -0.280 \\ -0.883 \\ 0.376 \end{pmatrix} LH$$

Virtually all practical uses of radio interferometry are based upon the fact that, to an observer sitting on a radio source in the sky, the interferometer baseline appears to rotate and change length as the earth rotates. In fact, <u>virtually every practical equation of importance in interferometry makes use of the natural coordinate system of an observer sitting on the reference position in the sky.</u>

### (b) Transformation to Coordinate System at Reference Position.

We must therefore derive the equations of transformation from the equatorial system used to describe and track sources to the coordinate system of an observer at the reference position. We will adopt a new coordinate system in which the z" axis is along the direction of  $\xi_0$ , the y" axis is oriented from south to north, and the x" axis then increases to the east. This coordinate system is right-handed and, by definition, its origin is at the reference position. Figure I-5 shows this coordinate system, all the other coordinate systems, and the important vectors defining the source-interferometer geometry.

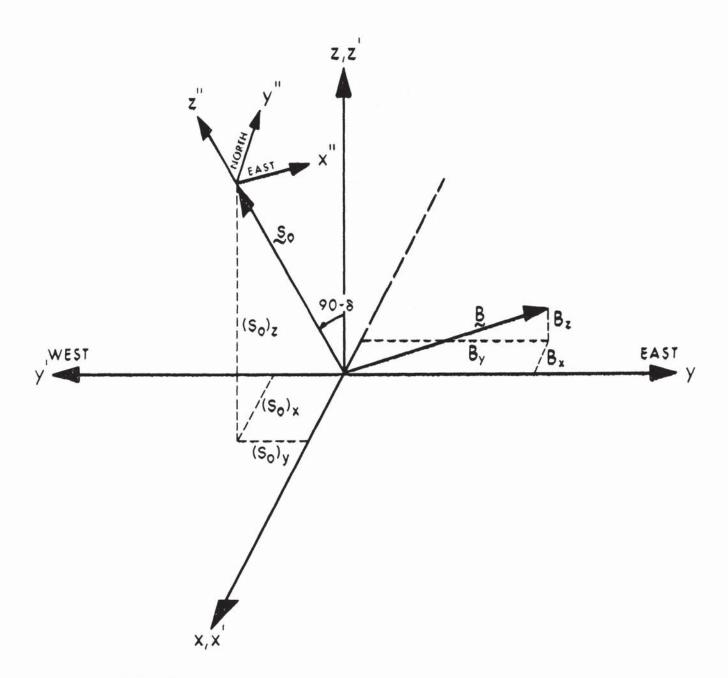


Fig. I-5. Basic geometry of earth-related coordinates systems related to coordinate system (x"y"z") of an observer situated on the sky, for a direction defined by  $s_0$ .

Let us derive the transformation matrices for going from the x'y'z' system to the x''y''z'' system, i.e., from the equatorial (left-handed) coordinate system to the right-handed system of an observer at the reference position. The transformation can be divided into four parts\*:

(2) a clockwise rotation about the y-axis by 
$$90-\delta$$
 
$$\begin{pmatrix} \cos 90-\delta & 0 & -\sin 90-\delta \\ 0 & 1 & 0 \\ \sin 90-\delta & 0 & \cos 90-\delta \end{pmatrix}$$

$$= \begin{pmatrix} \sin \delta & 0 & -\cos \delta \\ 0 & 1 & 0 \\ \cos \delta & 0 & \sin \delta \end{pmatrix}$$

clockwise rotation of  $\theta$  about x-axis 0 co

$$\begin{bmatrix}
1 & 0 & 0 \\
0 & \cos \theta & \sin \theta \\
0 & -\sin \theta & \cos \theta
\end{bmatrix}$$

clockwise rotation of  $\boldsymbol{\theta}$  about y-axis

$$\begin{pmatrix}
\cos \theta & 0 & -\sin \theta \\
0 & 1 & 0 \\
\sin \theta & 0 & \cos \theta
\end{pmatrix}$$

clockwise rotation of  $\theta$  about z-axis

$$\begin{pmatrix}
\cos \theta & \sin \theta & 0 \\
-\sin \theta & \cos \theta & 0 \\
0 & 0 & 0
\end{pmatrix}$$

<sup>\*</sup> Note the following general results:

(4) Reversal of the x-axis, changing the handedness of the system 
$$\begin{pmatrix} -1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

Combining all four transformations into one matrix, any vector specified in the x'y'z' coordinate system is transformed into a vector in the x"y"z" coordinate system by the following matrix:

$$\begin{cases}
sin H & -cos H & 0 \\
-sin \delta cos H & -sin \delta sin H & cos \delta \\
cos \delta cos H & cos \delta sin H & sin \delta
\end{cases}$$

Applying this transformation matrix to the baseline vector, B, we obtain special quantities of great importance:

where the three components of B in the x"y"z" system are denoted u,v, and D. The components u and v represent the projection of the interferometer baseline on the sky. They completely describe the orientation and separation of the two elements of the interferometer as it observes the source-from the point of view of an observer at the reference position. From Equation I-(5), we have:

$$u(H,\delta) = B_{x} \sin H - B_{y} \cos H$$
 I-(6)

and

$$v(H,\delta) = -\sin \delta(B_x \cos H + B_y \sin H) + B_z \cos \delta.$$
 I-(7)

# 4. Relation Between Geometry of Interferometer and Response Function (a) Meaning of Delay Parameter

The parameter D, which is the component of B along the line of sight to the source, is called the "delay" and it simply describes the extra distance a wave front originating from the reference position must travel beyond telescope 2 to get to telescope 1, i.e.,

$$D(H,\delta) = B_x \cos \delta \cos H + B_y \cos \delta \sin H + B_z \sin \delta,$$
 I-(8)

and the corresponding phase difference, which plays an important role in describing the response of an interferometer to a source at the reference position (cf. Equations I-(3)), is

$$\omega \Delta t = 2\pi \beta \cdot \varsigma_0 = 2\pi D.$$
 I-(9)

Another way of describing the delay D is that it is the phase difference in turns (1 turn =  $2\pi$  radians) between the two telescopes. Using equation I-(8), the computer calculates for each (H, $\delta$ ) the delay insertions ( $\Delta \tau = D/v_0$ ) necessary to minimize ( $\Delta \tau - \Delta t$ ).

#### (b) Re-description in Reference Frame on the Sky

Before turning to the most general case where radiation is distributed throughout the antenna beam, let us re-describe in a very useful form the response of a point source displaced by a vector  $\Delta_{\mathcal{S}}$  from  $\mathbf{s}_{o}$ . The projection of  $\Delta_{\mathcal{S}}$  on the x"-y" plane (plane of the sky) is shown in Figure I-6. We will use the following equivalent expression for  $\Delta_{\mathcal{S}}$  where the components are projections on the tangent plane:

$$\Delta_{\mathcal{S}} = \begin{pmatrix} \Delta \alpha \cos \delta \\ \Delta \delta \end{pmatrix}_{RH}$$
 I-(10)

<sup>\*</sup> Note to reader: We are glossing over some minor approximations involving spherical trigonometry to get at the equations of practical interest.

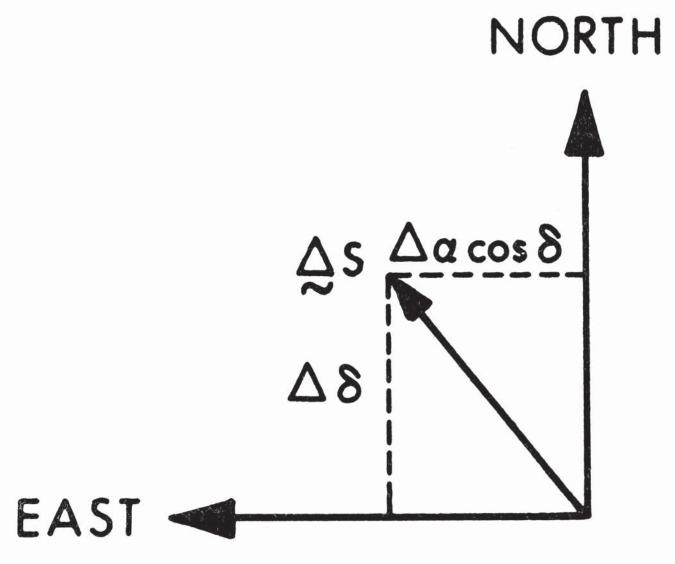


Fig. I-6. The relationship between the geometry of the displacement vector,  $\Delta g$ , and displacements in right ascension and declination appropriate to a point in the sky with a declination  $\delta$ .

where ( $\Delta\alpha$ , $\Delta\delta$ ) denotes the vector displacement from the reference position in right ascension and declination.

We now use Equation I-(3) to describe the response of the interferometer to this point source, but g is replaced by  $g_0 + \Delta g$ , i.e.,

$$R = S \cos \left[2\pi B \cdot (s_0 + \Delta s)\right]. \qquad I-(11)$$

Now we can use Equations I(5) and I-(10), which describe B and  $\Delta s$  in the reference frame at the reference position, to obtain

$$\Phi = 2\pi R \cdot \Delta S = 2 \cdot (u,v)_{RH} \begin{pmatrix} \Delta \alpha \cos \delta \\ \Delta \delta \end{pmatrix}_{RH}$$

$$= 2\pi (u \cdot \Delta \alpha \cos \delta + v \cdot \Delta \delta)$$
I-(12)

or, writing out the full dependence on  $\Delta\alpha$ ,  $\Delta\delta$ , H, and  $\delta$ :

$$\begin{split} \Phi(\Delta\alpha,\Delta\delta;H,\delta) &= 2\pi \ \Delta\alpha(B_{_{\mathbf{X}}} \cos \, \delta \, \sin \, H \, - \, B_{_{\mathbf{Y}}} \cos \, \delta \, \cos \, H) & \qquad \text{I-(13)} \\ &+ \, 2\pi \ \Delta\delta(-B_{_{\mathbf{X}}} \sin \, \delta \, \cos \, H \, - \, B_{_{\mathbf{Y}}} \sin \, \delta \, \sin \, H \, + \, B_{_{\mathbf{Z}}} \cos \, \delta). \end{split}$$

Let us now use the fact that  $B \cdot S = D$  to write the interferometer response to a point source as

$$R = S \cos \left[2\pi(D + u \cdot \Delta\alpha \cos \delta + v \cdot \Delta\delta)\right]. \quad I-(14)$$

Equation I-(14) describes the instantaneous response of the interferometer to a point source displaced ( $\Delta\alpha$ , $\Delta\delta$ ) from the reference position ( $\alpha$ , $\delta$ ).

## (c) Fringe-Fitting.

For the special case of a dominant point source displaced from the reference position, the interferometer response is

$$R = S \cos (2\pi D + \Phi),$$
 I-(15)

where  $\Phi$  is given by Equation I-(12) and S is the flux density of the source. As we shall see later, the more general case of a distribution of radiation sources in the beam produces a response that can be described in an analogous manner with amplitudes and phases that have a more complicated interpretation.

The response of an interferometer, R, which is the final product of the cross-correlation of signals from two antennas, is basically just the amplitude of this cross-correlation as a function of time. However, most of the variation of R has nothing to do with the properties of radiation sources in the sky but is simply due to the variation of D, which produces the intrinsic fringe pattern of the interferometer. For this reason, the <u>output of the interferometer which is actually recorded for later use is not R as a function of time but rather the amplitude and phase of R as a function of time.</u> The meaning of the amplitude and phase of R is best understood by understanding the process of "fringe-fitting".

Fringe-fitting is basically a solution for the fringe amplitude A and the fringe phase  $\phi$  for which one obtains the best fit of the response function data to an equation of the form

$$R(t) = A \cos [2\pi D(t) + \phi].$$
 I-(16)

The fitting process is carried out as follows. The value of D = D(t) is calculated at all times, by the DDP 116 computer which controls the interferometer, using an assumed set of baseline parameters ( $B_x$ ,  $B_y$ ,  $B_z$ ) and Equation I-(8). Every 20 milliseconds the computer takes a 20 millisecond average of the correlated signal (R) being received and this constitutes an amplitude  $R_i$  for a particular  $t_i$ . After 30 seconds during which such samples are gathered, the measured  $R_i$  vs  $t_i$  are fit in a least squares sense to Equation I-(16) to determine the measured fringe amplitude A and fringe phase  $\phi$  for that 30-second period.

For reasons that will be clear in a moment, we separate  $\varphi$  into a variable component  $\Phi$  and a constant component  $\varphi_{\text{S}},$  called the system phase center, so that

$$\phi = \phi_{S} + \Phi. \qquad I-(17)$$

If we denote by R' a sort of modified response function from which the effects of the delay D have been removed,

$$R' = A \cos \phi = A \cos (\phi_S + \Phi).$$
 I-(18)

By comparison of Equations I-(16) and I-(18), we see that after fringe-fitting the phase delay  $2\pi D$  has been replaced by an instrumental constant,  $\phi_{\rm g}$ , which we call the <u>phase center</u>.

Comparison of Equation I-(18) with Equation I-(14), which described the response to a dominant point source displaced from the pointing position, shows that in this case\*

$$R' = S \cos \left[\phi_S + 2\pi(u \cdot \Delta\alpha \cos \delta + v \cdot \Delta\delta)\right].$$
 I-(19)

It follows from this that when the source position coincides with the reference position

$$\Phi = 2\pi(\mathbf{u} \cdot \Delta\alpha \cos \delta + \mathbf{v} \cdot \Delta\delta) = 0$$

and

$$\phi = \phi_s$$

<sup>\*</sup> In real data there are a few other corrections to be applied before the following is strictly true; but since they are in the category of details and not related to the essence of interferometry, we postpone a discussion of them until Chapter III.

so that observations of calibrators at the reference position determine not only the calibration of the amplitudes but also the instrumental phase centers. The calibration problem can, in principle, be described as follows. Let  $S_{\bf i}$  be the flux density of the i-th calibrator, where  ${\bf i}=1,\ldots,N$  have been observed. Observations with the source positioned at the reference position give measurements of amplitudes  $A_{\bf i}$  and  $\phi_{\bf i}$ . Combining a number of measurements, one determines

$$\phi_{s} = \sum_{i=1}^{N} \phi_{i}/N \qquad I-(20)$$

and

$$g_{s} = \sum_{i=1}^{N} S_{i}/(A_{i}N), \qquad I-(21)$$

where  $\textbf{g}_{\textbf{S}}$  is the system gain, so that for any observations of any source we transform A,  $\phi,$  and R' from the raw data form of

$$R' = A \cos \phi$$

to the calibrated form

$$R' = g_S A \cos (\phi - \phi_S). \qquad I-(22)$$

Obviously  $g_s$  is the gain, and for any point source  $S = g_s A$ .

#### (d) Visibility Function for a Point Source

In practice there are a number of reasons why the modified response function R' is inconvenient to work with. It is most convenient to use the fringe amplitude A and fringe phase  $\phi$  to define a complex function, V, called the visibility function:

$$V = A e^{i\phi} = R + iI \qquad I-(23)$$

where R and I are the real and imaginary parts of V. However, we must be careful to distinguish between the uncalibrated visibility function as expressed in Equation I-(23) and the calibrated visibility function:

$$V = g_S A e^{i(\phi - \phi_S)} = g_S A e^{i\phi}.$$
 I-(24)

Obviously, when the field of view is dominated by a single point source, the uncalibrated visibility function will be

$$V = \frac{S}{g_S} \exp \left[i\phi_S + 2\pi i (u \cdot \Delta \alpha \cos \delta + v \cdot \Delta \delta)\right] \qquad I-(25)$$

where  $\delta$  is the declination of the reference position and  $(\Delta\alpha, \Delta\delta)$  is the displacement from the reference position to the point source. After calibration by multiplying Equation I-(25) by  $g_s$  exp  $(-i\phi_s)$ , the calibrated visibility function is

$$V = S \exp \left[2\pi i \left(u \cdot \Delta \alpha \cos \delta + v \cdot \Delta \delta\right)\right] \qquad I-(26)$$

#### 5. Visibility Function for General Distribution of Sources

# (a) Relation Between Visibility Function and Brightness Distribution

We are now in a position to discuss the response of an interferometer to a general distribution of radiation. Our discussion is based upon the principle that any infinitesimal region of the sky behaves as a point source of radiation as far as the interferometer is concerned.

Let

$$x = \Delta \alpha \cdot \cos \delta$$
$$y = \Delta \delta$$

and consider an infinitesimal area dxdy at the position (x,y). Now we know that, by definition, for any source with a brightness (or intensity) distribution B(x,y) the flux density S is given by

$$S = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} B(x,y) dxdy;$$

therefore the infinitesimal area dxdy can be considered to make an infinitesimal contribution to the flux density of B(x,y)dxdy. If we further define f(x,y) to be the normalized antenna pattern, the contribution of the area dxdy to the uncalibrated visibility function is, by generalization of Equation I-(25),

$$dV(x,y; u,v) = \frac{f(x,y)B(x,y)}{g_s} \exp \left[i\phi_s + 2\pi i(ux+vy)\right] dxdy$$

where  $g_s$  is still the gain and  $\phi_s$  the phase center. Integrating over the entire antenna beam, we get the visibility function produced by all the radiation sources in the beam;

$$V(u,v) = \frac{1}{g_s} e^{i\phi} s \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f(x,y) B(x,y) e^{2\pi i (ux + vy)} dxdy$$

Since it is trivial to calibrate the visibility function by determining  $\boldsymbol{g}_S$  and  $\boldsymbol{\varphi}_S$  from calibrators, let us work from now on with the calibrated visibility function

$$V(u,v) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f(x,y)B(x,y) e^{2\pi i(ux + vy)} dxdy.$$
 I-(27)

At this point the reader is advised to sit back and admire the beauty and generality of Equation I-(27). Recognizing that Equation I-(27) is the complex Fourier transform of the apparent brightness distribution f(x,y) B(x,y), we now see that every measurement made by an interferometer is the measurement of a Fourier component of f(x,y) B(x,y).

Recognizing this important fact we can invoke all that is known about Fourier transforms to analyze the meaning of interferometric data. In particular, we know how in principle to determine f(x,y) B(x,y) from our data. In principle

$$f(x,y) B(x,y) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} V(u,v) e^{-2\pi i(ux + vy)} dudv, \qquad I-(28)$$

so we need only determine all we can about V(u,v) and use Equation I-(28) to interpret the data.

#### (b) Single Point Source

To check on whether the general formulation still meshes with our earlier, more simplified discussions, let us begin with Equation I-(27) and discuss the case of a single dominant point source displaced by ( $\Delta\alpha$  cos  $\delta$ ,  $\Delta\delta$ ) = ( $x_s$ ,  $y_s$ ) from the reference position. For this case Equation I-(27) reduces to

$$V(u,v) = e^{2\pi i(ux} s + vy s) f(x_s, y_s) S$$
 I-(29)

which is essentially the same as I-(26) except for a different notation for the displacement from the reference position, and we are now correcting for the antenna sensitivity pattern (which is unity unless the source is far from the beam center).

#### (c) Sampling of Fourier Components

Using the language of the Fourier transform, there is a very simple way to describe the essential operation of an interferometer. One considers u and v to define a particular angular separation and orientation in the sky, which we will call a "spatial frequency". The E-W and N-S components of a spatial frequency are defined by u=1/x and v=1/y, respectively. We can then say that the interferometer at any particular instant samples the Fourier component of the brightness distribution corresponding to that spatial frequency. Because of the

rotation of the Earth, when a source is tracked a range of Fourier components are sampled. Changing telescope separations and/or using many telescope pairs with different separations causes more spatial frequencies to be sampled. In principle Equation I-(28) tells us that all possible (u,v) must be sampled to allow determination of the brightness distribution. In practice an interferometer samples pitifully few spatial frequencies, hence the determination of f(x,y)B(x,y) is incomplete. The effects of this must be clearly understood.

### (d) Coverage of Spatial Frequencies

Let us now discuss in some detail the spatial frequencies the NRAO interferometer can sample and the resulting limitations. From Equations I-(6) and I-(7):

$$u = B_x \sin H - B_y \cos H$$

and

$$v = -\sin \delta(B_x \cos H + B_y \sin H) + B_z \cos \delta.$$

 $\label{eq:continuous} From \ these \ equations \ one \ can \ show \ that \ u \ and \ v \ are \ related \ to \\ each \ other \ by$ 

$$\frac{u^2}{a^2} + \frac{(v - v_0)^2}{b^2} = 1,$$
 I-(30)

which is the equation for an ellipse, where

$$a = \sqrt{B_x + B_y} = \cos d,$$
 I-(31)

$$b = a \sin \delta = B \cos d \sin \delta$$
, I-(32)

and

$$v_0 = B_z \cos \delta = B \sin d \cos \delta$$
. I-(33)

The u-v ellipse for a particular telescope pair has a center located at u=0,  $v=v_0=B_z$  cos  $\delta$  and has a major axis a, a minor axis b, and an eccentricity cos  $\delta$ . As we see from Equations I-(31)-(33), the size of the ellipse is proportional to B, the actual baseline separation of the two telescopes. The NRAO interferometer has three telescopes of which two are movable and can be placed on the stations indicated in Figure I-7. There is a set of possible ellipses for each declination; the possible ellipses for  $\delta=-40$ , -20, 0,  $+20^{\circ}$ ,  $+40^{\circ}$ , and  $+60^{\circ}$  are shown in Figure I-8. As one sees in Figure I-8, only parts of the ellipses are obtainable because of the limitations on possible hour angles for the telescopes. The plots of Figure I-8, it should be remembered, show the possible spatial frequencies that can be sampled when observing a source at a particular declination. It is obvious that many spatial frequencies cannot be sampled, and, further, at low declinations there is very little sampling of N-S orientations.

From Equations I-(30)-(32) it is clear that the maximum values of u and v are:

$$u_{\text{max}} = (B_x^2 + B_y^2)^{1/2}$$
 I-(34)

and

$$v_{\text{max}} = B_z \cos \delta + (B_x^2 + B_y^2)^{1/2} \sin \delta.$$
 I-(35)

The smallest structures resolvable with the NRAO interferometer correspond to angular sizes  $1/u_{max}$  and  $1/v_{max}$  in the N-S and E-W directions, respectively. As a rough rule, all parts of sources with structure smaller than 1.5 at 11.1 cm and 0.5 at 3.7 cm will respond as if each such part were a point source. On the other hand, to detect all of a source confined within angular dimensions  $x_s$  and  $y_s$  (in radians), the spatial frequencies need to be sampled at intervals down to  $\Delta u = 1/x_s$  and  $\Delta v = 1/y_s$ . Also, data must be available no more than

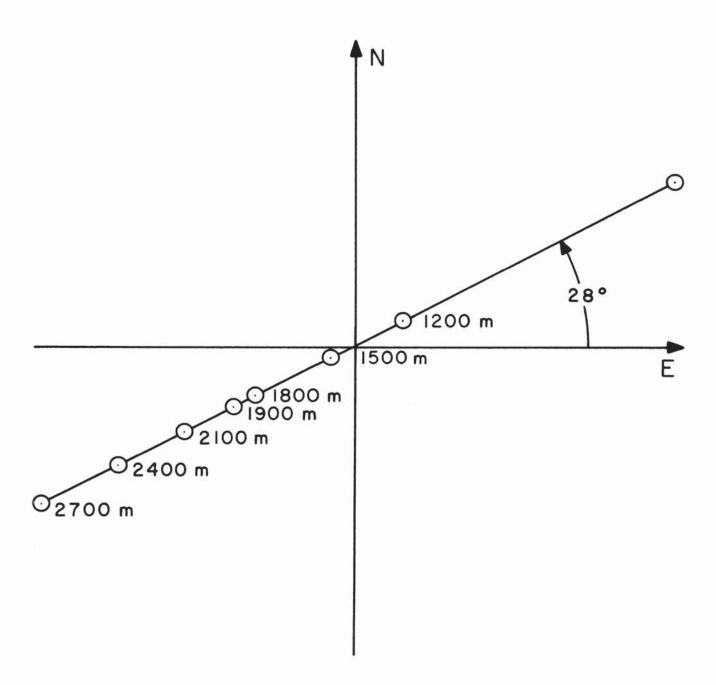


Fig. I-7. The orientation of the NRAO interferometer baselines with respect to the E-W line, with available stations indicated by their distance from 85-1.

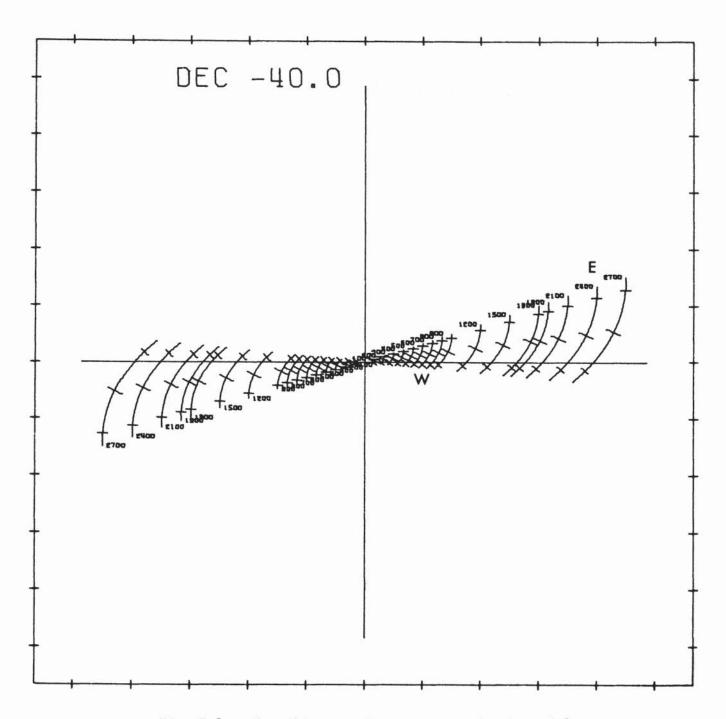


Fig. I-8a. Possible u-v plane coverage for  $\delta$  = -40°

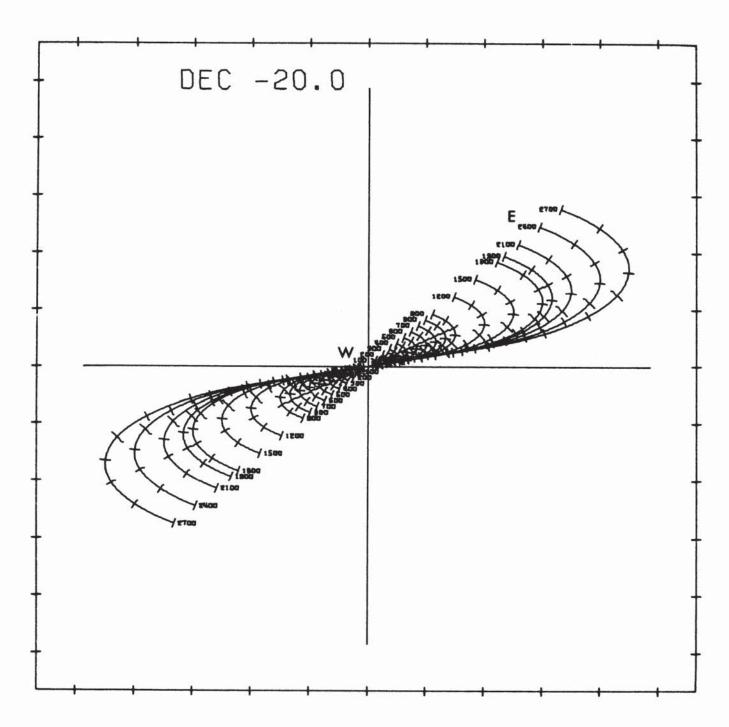


Fig. I-8b. Possible u-v plane coverage for  $\delta$  = -20°

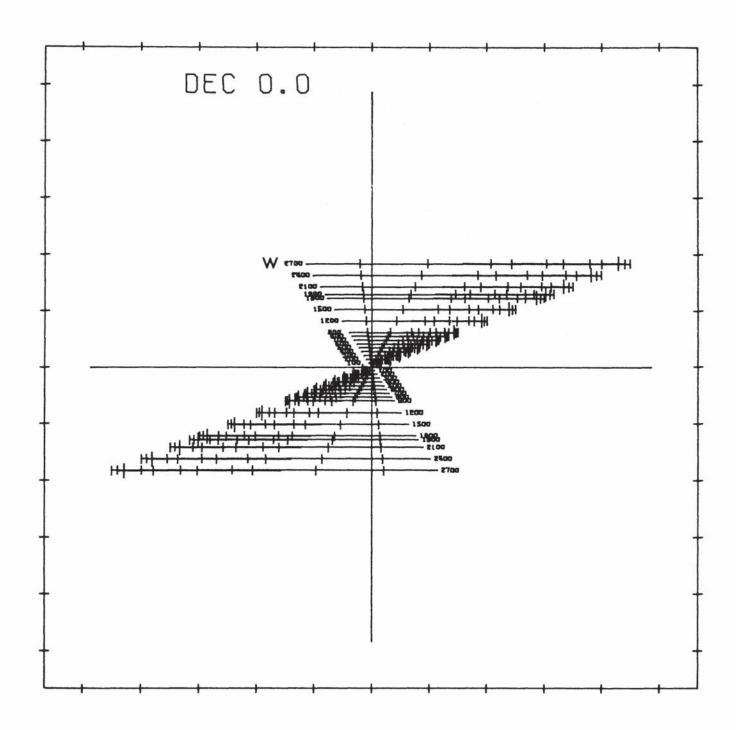


Fig. I-8c. Possible u-v plane coverage for  $\delta$  = 0.

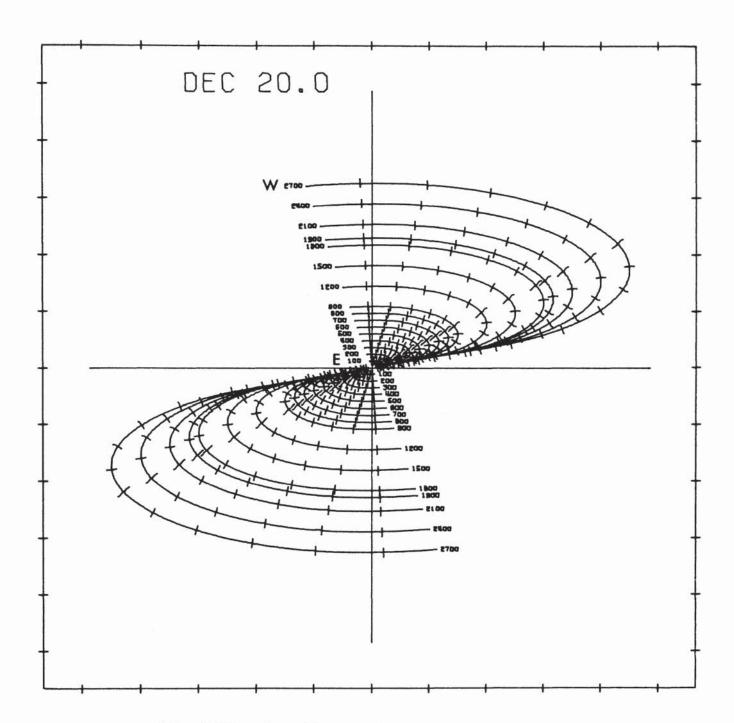


Fig. I-8d. Possible u-v plane coverage for  $\delta$  = 20°.

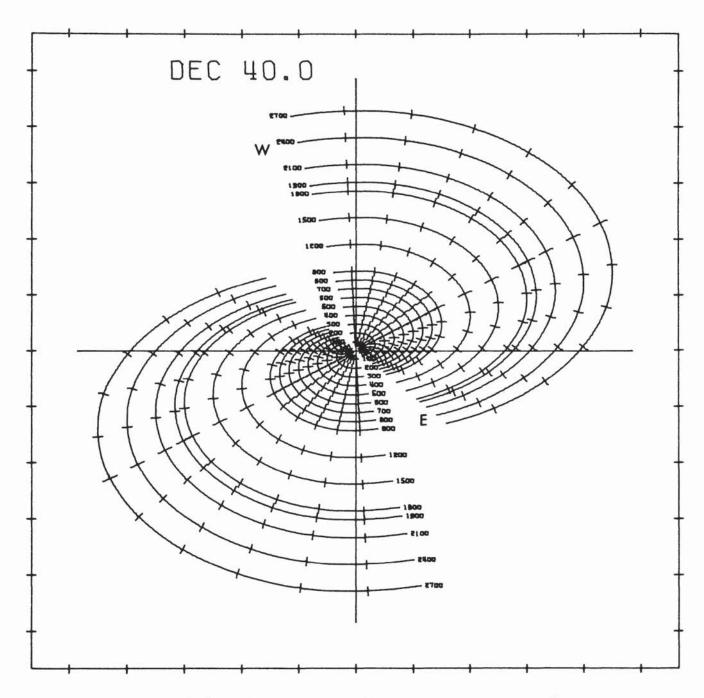


Fig. I-8e. Possible u-v plane coverage for  $\delta$  = 40°.

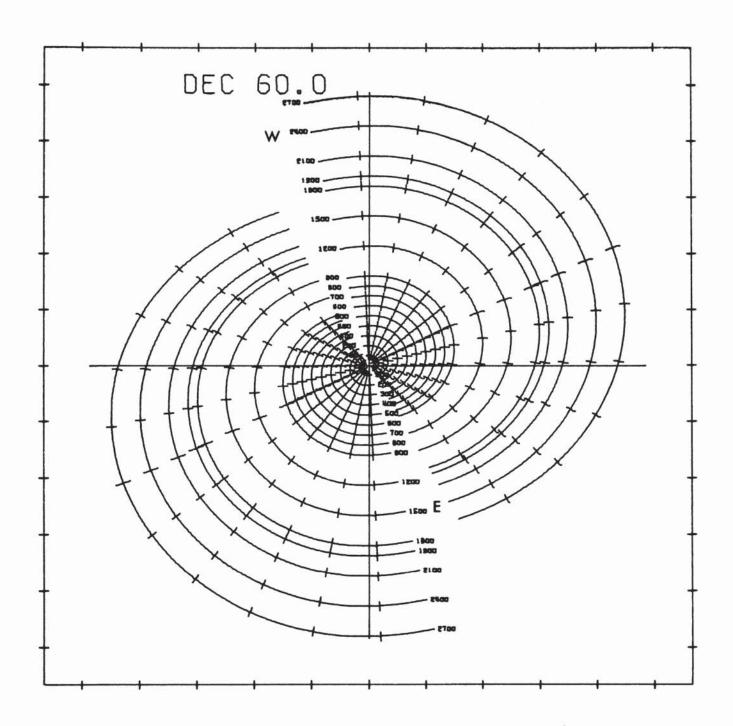


Fig. I-8f. Possible u-v plane coverage for  $\delta$  = 60°.

Au and  $\Delta v$  from the origin in the u-v plane. This means that when the source is too large, the limitations of u-v plane coverage cause the spatial frequencies of the largest structures to not be sampled. This means structures with angular sizes greater than  $\sim 6'$  at 11.1 cm and  $\sim 2'$  at 3.7 cm are undetectable with the NRAO interferometer. This causes a common difficulty when observing sources with structures on size scales ranging from very small to tens of arcminutes or more: Only a small part of the source is detectable—that part corresponding to the spatial frequencies (angular sizes) sampled with the interferometer. When this occurs the observer must be careful because the source he "sees" is not the same as observed with single antennas.

#### (e) Gridding

How does one, in practice, use Equation I-(28) to obtain synthesis maps (solutions for f(x,y)B(x,y))? First the observer selects a "field of view" which we denote by  $x_s$  and  $y_s$ . Later we will discuss the reasons for adopting different fields of view. The data gathered for the visibility function V(u,v) is sorted and averaged by (u,v) into a rectangular grid having spacings  $\Delta u = 1(2x_s)$  and  $\Delta v = 1/(2y_s)$ . One can then make use of the fact that, since f(x,y)B(x,y) is real, the function V(u,v) must be Hermitian\*, therefore

$$V(-u,-v) = V*(u,v)$$

where the asterisk indicates complex conjugation. Samples taken in one-half of the u-v plane then provide data for cells in the other half of the u-v plane. Once the complex visibility function has been measured at all of the accessible grid points, the summation equivalent of the integral in Equation I-(28) gives

<sup>\*</sup> This is valid for total intensity measurements but not for measurements of the other three Stokes parameters.

$$f(x,y)B(x,y) = \sum_{-u_{\text{max}}}^{u_{\text{max}}} \sum_{-v_{\text{max}}}^{v_{\text{max}}} V(u,v) e^{-2\pi i (ux + vy)} \Delta u \Delta v. \qquad I-(34)$$

Maps produced using Equation I-(34) are also gridded and are called "synthesis maps."

## (f) Controversial Assumptions

There are two details in this process that are still subjects of controversy. First, do you assume the observed visibilities for a grid point are equal to the averages for all data sampled in the cell or do you interpolate with the available samples to give a value at the grid point? Secondly, when no data has been sampled in a cell, do you set V(u,v) = 0 for that cell or do you take data for available cells and interpolate by some fancy scheme to obtain values for all grid points? In the latter case, the problem of inserting false data (V(u,v) = 0 when it isn't) is offset by the problem that the way you would perform the interpolation could also give spurious results. As of 1973, the standard NRAO mapping programs follow the practice of setting V(u,v) = 0 for unsampled cells. Similarly, data within a cell is simply averaged to get a value for the grid point. Whether these are the best procedures can be argued. More sophisticated procedures are under development, but are beyond the scope of this introduction.

#### (g) Synthesized Beams

What is the practical effect of limited coverage of the u-v plane when observing a source? This is best illustrated by showing how a point source would look if observed with limited coverage; maps of point sources are referred to as "beam maps" and one can think of such maps as the synthesized beams of the interferometer. The inner portions of synthesized beams for full tracks with  $\delta = -40^{\circ}$ ,  $-20^{\circ}$ , 0,  $+20^{\circ}$ ,  $+40^{\circ}$ , and  $+60^{\circ}$  are shown in Figure I-9, where it is assumed that all available interferometer spacings are used. The effect of partial coverage is shown in Figure

I-10 where only 2700, 1800, and 900 meter spacings are included. Poor u-v plane coverage results in considerably larger sidelobes and more assymetrical synthesized beams. To evaluate the effects of partial coverage on observations of sources with structure, one can consider each point in the source as having a contribution like the beam image; however, all points in the source contribute negative or positive images at every other point, and the combination, which is determined only by the true radiation structure, is what comes out in the synthesis map. As we will discuss later, this makes it virtually impossible to obtain flux densities from interferometer maps of extended sources and makes it difficult to interpret the reality of minor features in these maps.

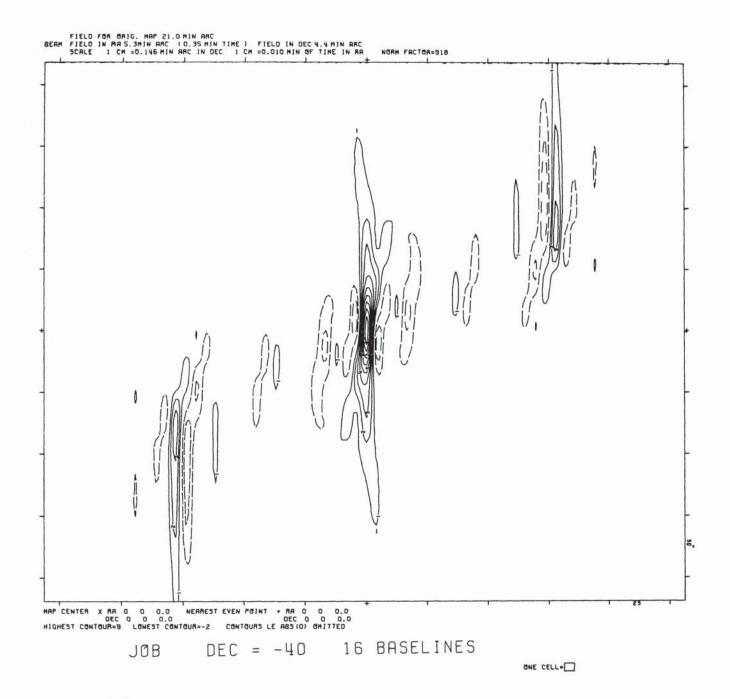


Fig. I-9a. Inner quarter of synthesized beam when  $\delta$  = -40°, assuming data on all 16 baselines and all possible hour angles are used.

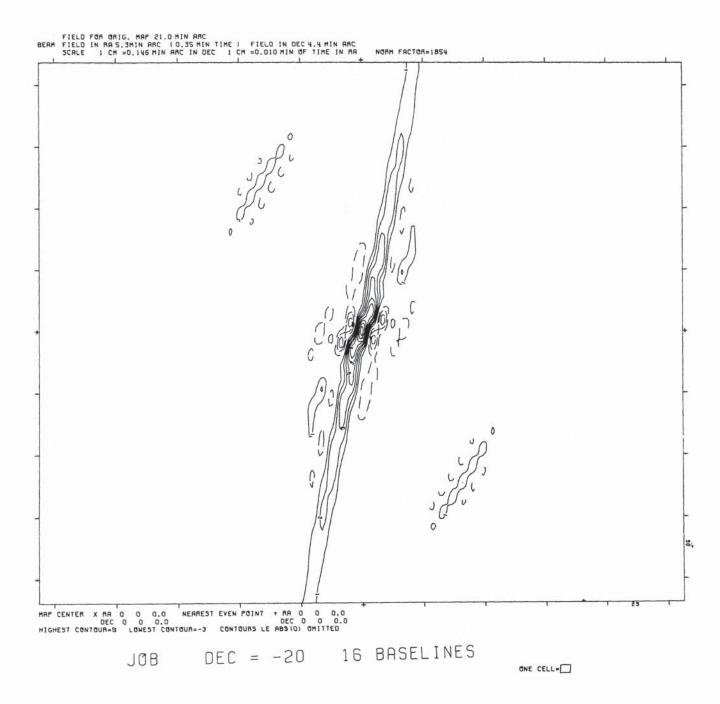


Fig. I-9b. Inner quarter of synthesized beam when  $\delta$  = -20°, assuming data on all 16 baselines and all possible hour angles are used.

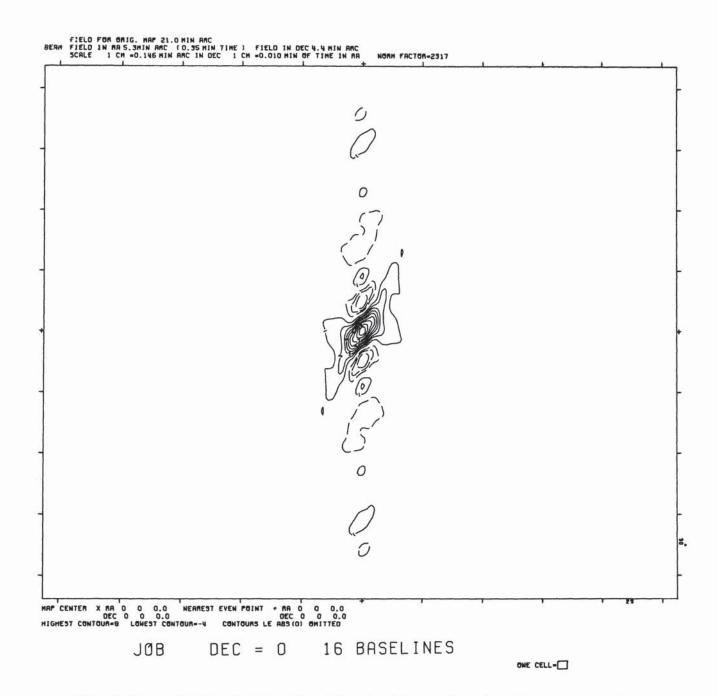


Fig. I-9c. Inner quarter of synthesized beam when  $\delta$  = 0°, assuming data on all 16 baselines and all possible hour angles are used.

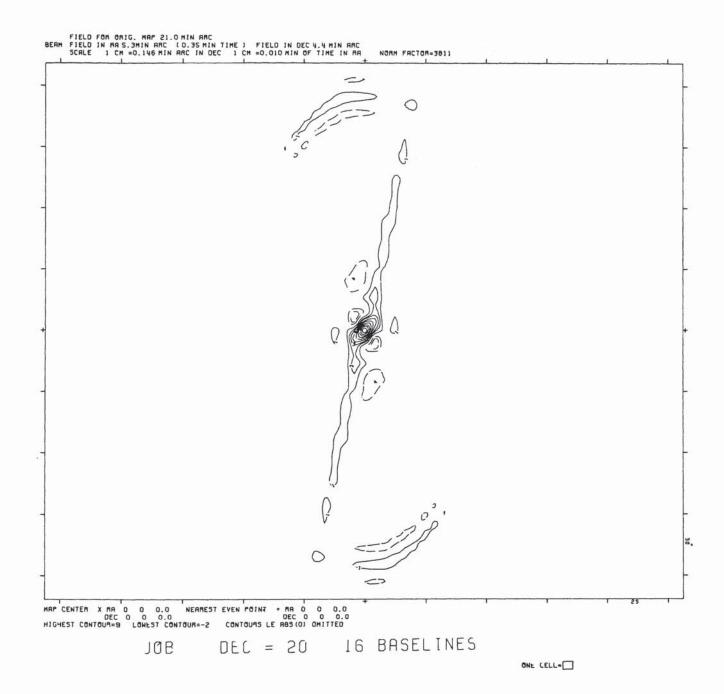


Fig. I-9d. Inner quarter of synthesized beam when  $\delta$  = 20°, assuming data on all 16 baselines and all possible hour angles are used.

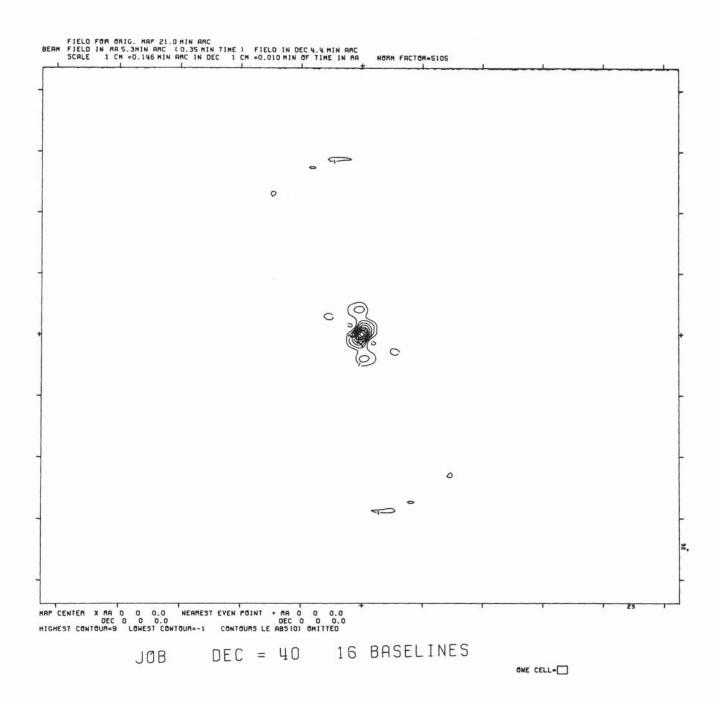


Fig. I-9e. Inner quarter of synthesized beam when  $\delta$  = 40°, assuming data on all 16 baselines and all possible hour angles are used.

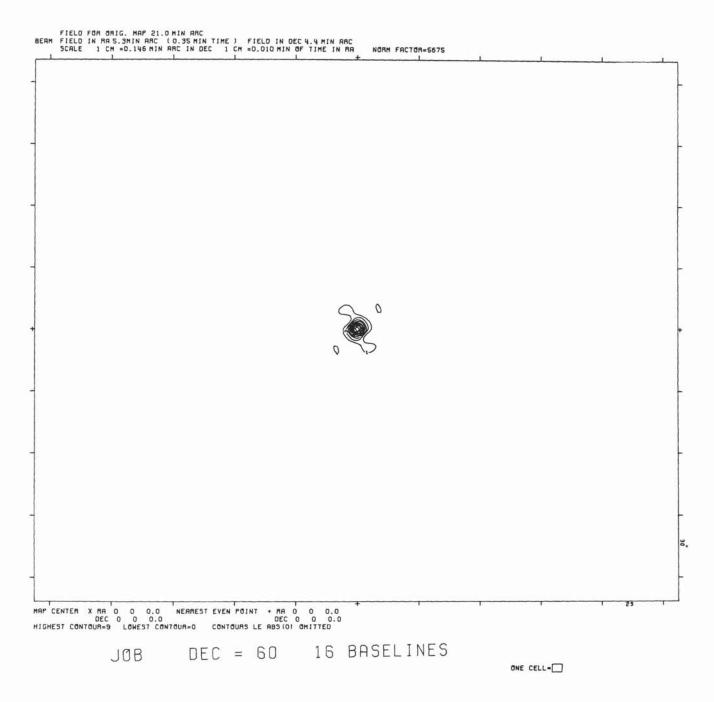


Fig. I-9f. Inner quarter of synthesized beam when  $\delta$  = 60°, assuming data on all 16 baselines and all possible hour angles are used.

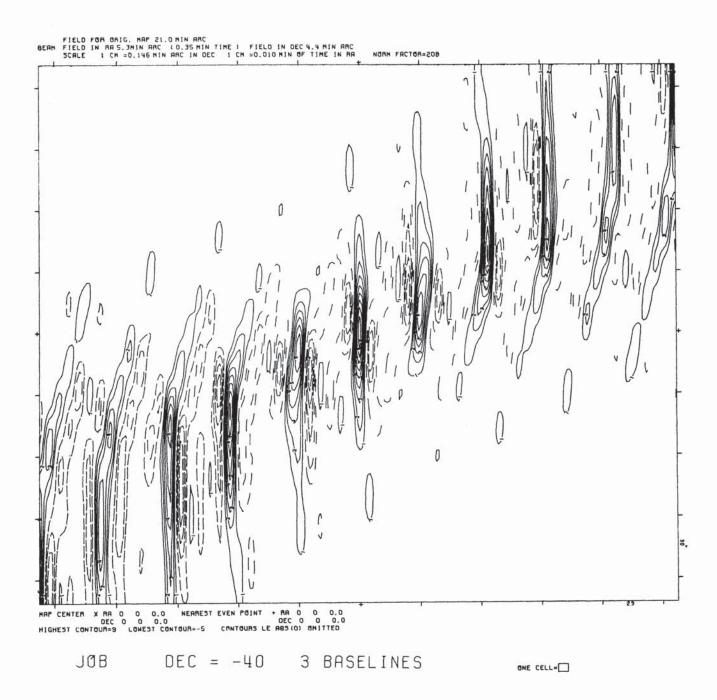


Fig. I-10a. Inner quarter of synthesized beam when  $\delta$  = -40°, assuming data on only 2700, 1800, 900 m baselines, when all possible hour angles are used.

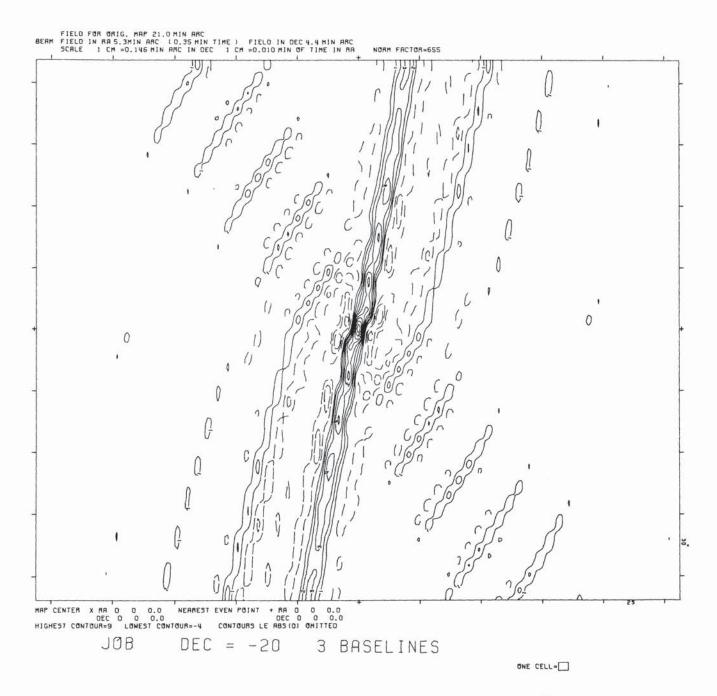


Fig. I-10b. Inner quarter of synthesized beam when  $\delta$  = -20°, assuming data on only 2700, 1800, 900 m baselines, when all possible hour angles are used.

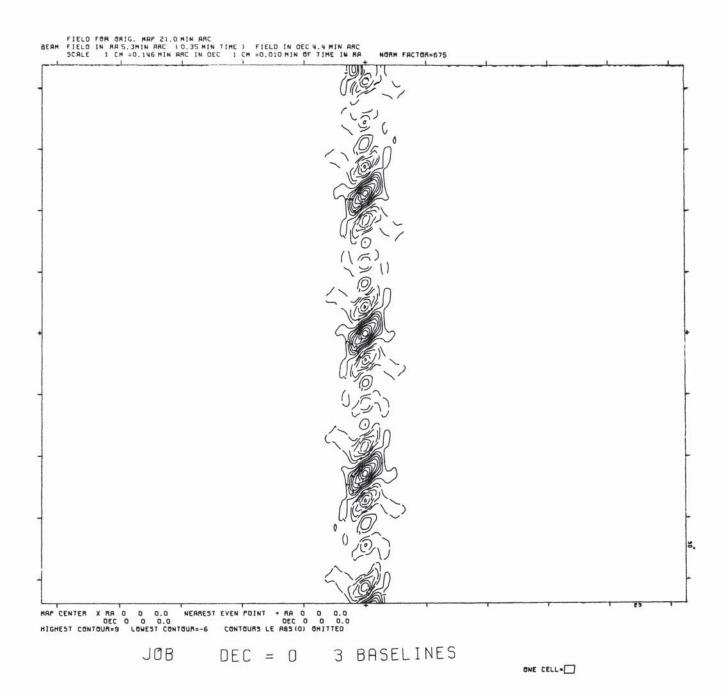


Fig. I-10c. Inner quarter of synthesized beam when  $\delta$  = 0°, assuming data on only 2700, 1800, 900 m baselines, when all possible hour angles are used.

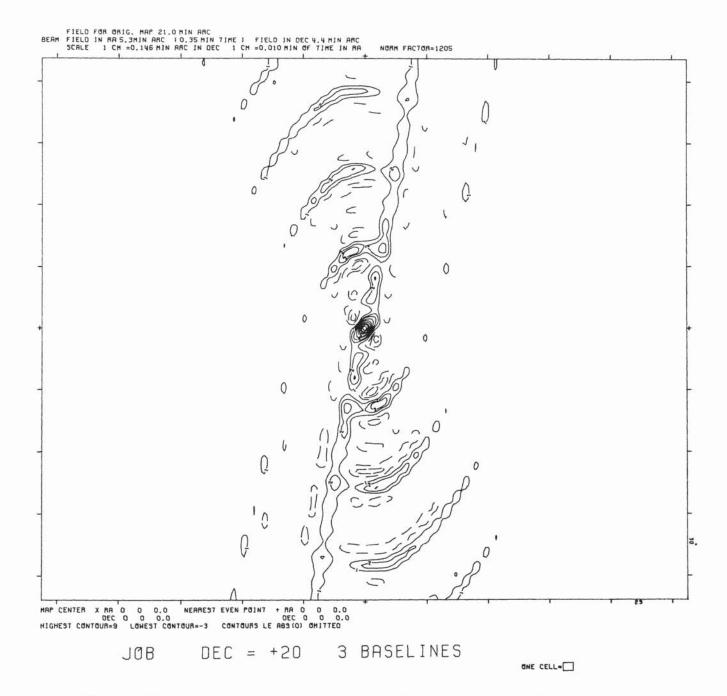


Fig. I-10d. Inner quarter of synthesized beam when  $\delta$  = 20°, assuming data on only 2700, 1800, 900 m baselines, when all possible hour angles are used.

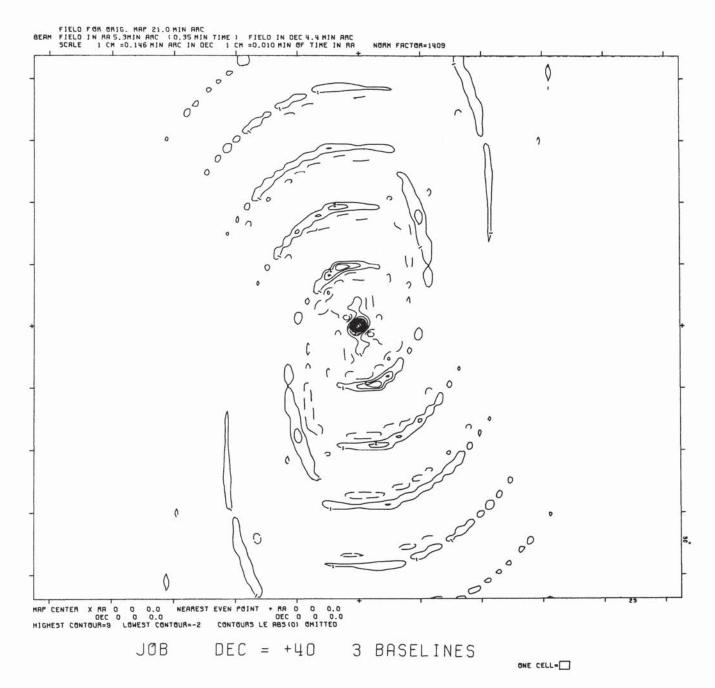


Fig. I-10e. Inner quarter of synthesized beam when  $\delta$  = 40°, assuming data on only 2700, 1800, 900 m baselines, when all possible hour angles are used.

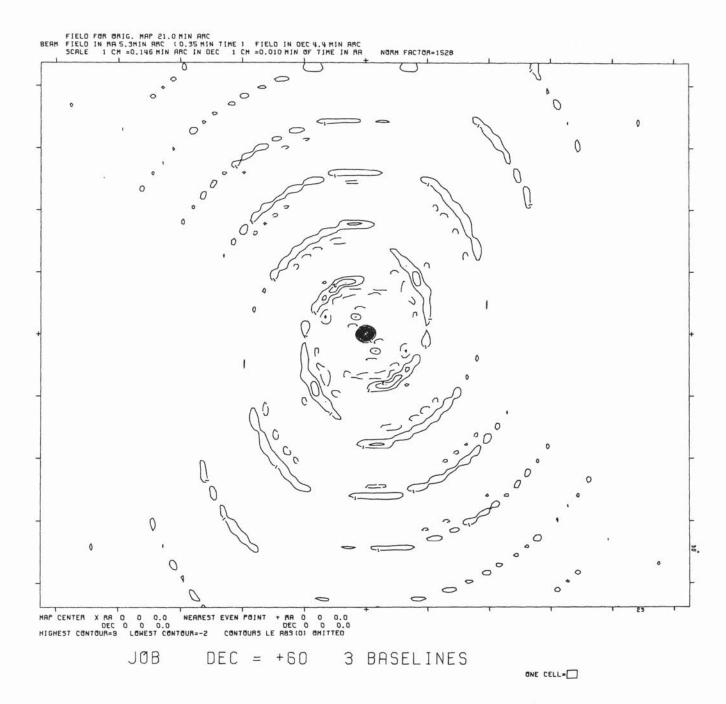


Fig. I-10f. Inner quarter of synthesized beam when  $\delta$  = 60°, assuming data on only 2700, 1800, 900 m baselines, when all possible hour angles are used.

# CHAPTER II

## OBSERVING WITH INTERFEROMETER AT GREEN BANK

### 1. Terminology

As with any instrument, there is a special terminology used to describe the parts and functions of the NRAO interferometer.

The three 85-foot telescopes are identified as 85-1, 85-2, and 85-3. The frontispiece shows a photograph of the three elements of the interferometer and the control building. The fixed telescope, 85-1, is at the northeast end of the baseline, as shown in Figure I-7, and is the furthest telescope in the frontispiece. The second telescope to be constructed, designated 85-2, the nearest telescope in the frontispiece, is movable but always occupies the extreme southwest position. The last telescope constructed, 85-3, is movable and at some intermediate position between 85-1 and 85-2. The telescope pairs are referred to as the 1-2, 1-3, and 2-3 pairs. For example, when 85-2 is on station 27 and 85-3 is on station 18, the 1-2, 1-3, and 2-3 pairs correspond to baseline lengths of 2700, 1800 and 900 meters. The available stations are identified by the first two digits of their distance in meters from 85-1.

The frequency 2695 MHz (wavelength 11.1 cm) is called SBAND and the frequency 8085 MHz (wavelength 3.7 cm) is called XBAND. A particular telescope pair (e.g., 13) observing at a particular frequency (e.g., 8085 MHz) is frequently designated by X or S followed by the pair numbers (e.g., X13).

Each telescope has feeds sensitive to both right (designated R) and left (designated L) circular polarization at both SBAND and XBAND. Thus designation of a particular output pair from the interferometer

involves specifying: frequency, pair, and polarization. For example, the 1-3 pair operating at 8085 MHz observing right circular polarization in both telescopes is designated X1R3R or X13R. If the correlation involved R for 85-1 and L for 85-3, it would be designated X1R3L. All output is identified in terms of identifying a particular correlator.

The interferometer operates in four possible modes, called <u>mixed-mode</u> (M), <u>S-mode</u> (S), <u>X-mode</u> (X), and <u>dual-mode</u> (D). The following table shows the correlators involved in each mode, together with the designations that are meaningful when running in these modes, together with the numbers assigned to each correlator:

Correlator Number	Correlator Designation
0	X1R2R (or X12R or X12)
1	S1L2L (or S12L or S12)
2	X1R2R (or X13R or X13)
	S1L3L (or S13L or S13) X2R3R (or X23R or X23)
5	X2R3R (or X23R or X23) S2L3L (or S23L or S23)
	S1R2R
	S1L2L
2	S1R3R
3	S1L3L
	S2R3R
	S2L3L
6	S1R2L
7	S1L2R
8	S1R3L
9	S1L3R
	S2R3L
11	S2L3R
0	X1R2R
	X1L2L
2	X1R3R
3	X1L3L
4	X2R3R
5	X2L3L
	X1R2L
7	X1L2R
8	X1R3L
9	X1L3R
10	X2R3L
11	X2L3R
	0 1 2 3 4 5 0 1 2 3 4 5 6 7 8 9 10 11 0 1 2 3 4 5 6 7 8 9 10 11 2 3 4 5 6 6 7 8 9

Mode	Correlator Number	Correlator Designation
D	0	S1R2R
	1	S1L2L
	2	S1R3R
	2 3 4 5 6 7	S1L3L
	4	S2R3R
	5	S2L3L
	6	S1R2L
	7	S1L2R
	8	S1R3L
	9	S1L3R
	10	S2R3L
	11	S2L3R
	14	X1R2R
	15	X1L2L
	16	X1R3R
	17	X1L3L
	18	X2R3R
	19	X2L3L
	20	X1R2L
	21	X1L2R
	22	X1R3L
	23	X1R3L
	24	X2R3L
	25	X2L3R

In mixed mode there is no cross-correlation between different polarizations. In both S- and X-mode the crossed-hand correlators are involved and sufficient information is obtained to determine all four Stokes parameters. In dual-mode the interferometer alternates observation in S-mode and X-mode every 30 seconds. When simultaneous operation at both frequencies is desired, it is usually done in mixed mode unless complete polarization information is desired, then dual mode is used.

The interferometer output from each correlator can be recorded in crude form on six available channels of chart recorders. Each correlator being recorded then has the response function  $(R(\Delta t))$  plotted as a function of time at various possible chart speeds. Figure II-1 shows a photograph of four of the possible recording channels in operation. The four channels give the interferometer response for the 1R2R, 1L2L, 1R3R,

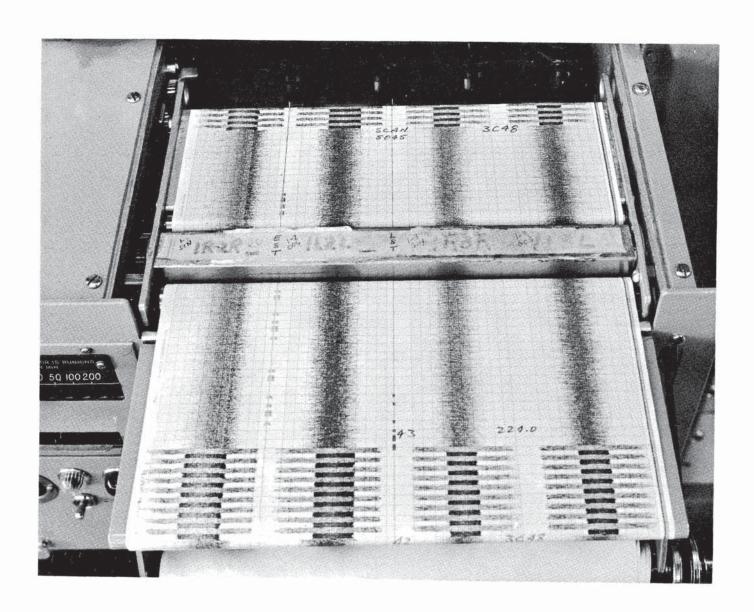


Fig. II-1. Photograph of four-channel chart recorder displaying plots of response functions for four correlators as functions of time.

and 1L3L correlators before the fringe-fitting algorithm has been applied. Scans 5042 and 5043 show the fringes for a strong calibrator, 3C 48, being observed in dual mode with a gain code of 444 (see p. II-13) The pattern for the source "224.0" is characteristic of a pattern indistinguishable from noise, which is also obtained for very weak sources observed with a gain code of 000 (see p. II-13).

The DDP computer, using the "fringe-fitting" algorithm, solves for A(u,v) and  $\phi$ (u,v) (cf. Equations I-(16)-(18) for each 30-second record. To obtain the solution it takes 1500 successive 20 millisecond samples which are used in a least-squares solution for fringe amplitude and fringe phase. All of these data, for all correlators, are recorded on magnetic tape, together with a great deal of information concerning the observed source, time, and the state of important interferometer functions. We will discuss the format and uses of this output in Chapter III. The data measured for each 30 seconds is referred to as a data record.

There are two more ways of examining the on-line output of the interferometer. The teletype output records source name, source position, scan number, and other information concerning the status of the system. Then, once the scan (the period of time the source is tracked continuously) is completed, the vector average of amplitudes and phases for each scan for each correlator are printed out, together with the rms variation of the amplitudes and more information about the state of the system. A photograph of the teletype and its output is shown in Figure II-2. There is also a CRT display which can exhibit, for each 30-second data record, any six of the following: A(u,v),  $\phi(u,v)$ , R(u,v) and I(u,v) for different correlators. None of this data has been phase-centered or calibrated in any way. All values of A(u,v), R(u,v) and I(u,v) are measured in counts. Under normal operation there are roughly 1000 counts per flux unit (frequently abbreviated CPFU); hence one count is roughly one milliflux unit. In practice the appropriate counts per flux unit varies with each correlator, with 1200 being typical for SBAND correlators and 800 being typical for XBAND correlators.

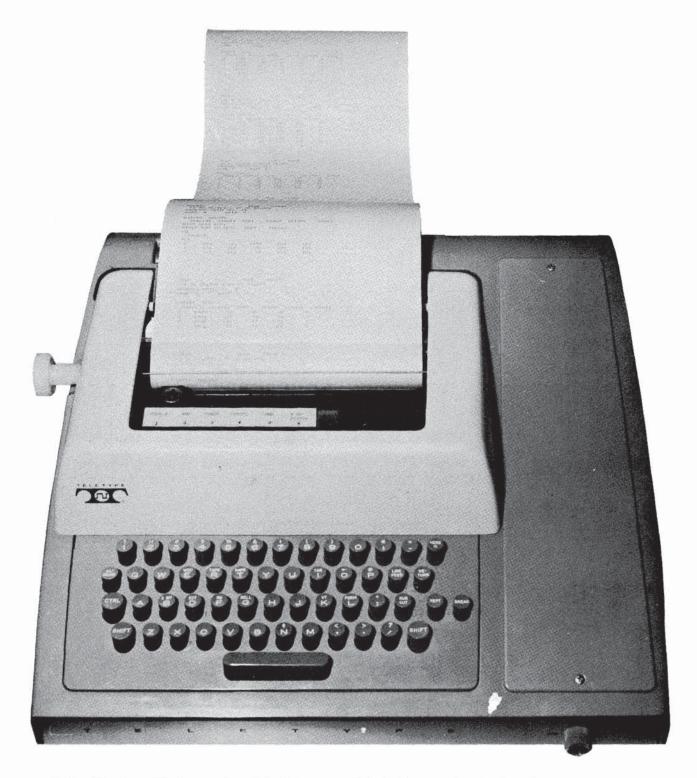


Fig. II-2. Photograph of teletype and teletype output whereby one communicates with DDP116 and in return receives information about system, observation status, scan averages, etc.

#### 2. Pointing Calibration

The first calibration procedure necessary to observe with the NRAO interferometer is pointing calibration of the individual antennas. When one of the telescopes has been moved and placed at a new observing station it cannot be assumed that the pointing properties are the same as before. Therefore, pointing calibration must be carried out after each move. In addition, even though 85-1 does not move, over a long period of time things can change so occasional pointing checks must be made for this antenna also.

Pointing calibration is quite straightforward. The computer is told to run the interferometer in pointing mode and observations are made of a large number of strong sources covering as many hour angles and declinations as possible. The observations on each source consist of the measurement of the total power received at each of four off-set positions plus the "actual" position where the source should be. A simple computer analysis of the results for each set of five observations is interpreted in terms of (true minus apparent) position shift in hour angle and declination. This data, for a complete range of hour angles and declinations, is used to determine the constants in an empirical formula predicting the needed corrections in hour angle and declination for every point in the sky. Once all the data has been obtained, this fit is made (with the DDP and/or the Charlottesville computer). Then the goodness of fit is evaluated in terms of both the fit to each actual observation and the mean rms fit. Good solutions are obtained when (1) the predicted and actual errors agree to less than about 1 arcminute for all points; (2) the total rms is of the order of 0:4 or less; and (3) the fit is uniformly good over the whole sky. Once the pointing constants are determined they are read into the DDP and remain in force until the next move.

In general, NRAO staff will do pointing calibration after each run. However, occasionally circumstance may make it necessary for the observer to do this. In this case the observer should read the special manual discussing the method of obtaining the pointing solution through

use of the DDP and the CRT display. The observer is cautioned to resist all temptations to cut the pointing observations short to get on with the science. Extra observing time is always allotted to do such calibrations and succeeding observers must depend upon the initial calibration. Very poor pointing calibration can result in large, non-random variations of amplitudes.

### 3. Setting Delays

After the pointing calibration has been made and the pointing constants are read into the DDP, the next calibration necessary is the setting of the delays. As shown in Chapter I, when tracking a particular point in the sky, called the reference position, there is a geometrical time delay  $\Delta t$  reflecting the time difference in arrival of the same wave front at two different telescopes. In the electronics a computer controlled digital delay system inserts a compensating delay  $\Delta \tau$  for each pair of telescopes. When  $\Delta \tau - \Delta t$  is kept close to zero, the envelope function, which is, under ideal conditions approximated by

$$F(\Delta t - \Delta \tau) = \frac{\sin \pi \Delta \nu (\Delta \tau - \Delta t)}{\pi \Delta \nu (\Delta \tau - \Delta t)} \cos \omega_{IF} (\Delta \tau - \Delta t), \qquad II-1$$

can be kept near unity. By delay switching with times as short as 2 nanoseconds  $F(\Delta t - \Delta \tau)$  can be kept to between 0.98 and 1.0.

Although the changes in delays are maintained to this accuracy by the computer, each telescope pair, when the cable lengths are altered during a move, has a change in the travel time from telescope to the multiplier. Because of this the cable lengths for each pair must be adjusted so that, when tracking, the observations are made with maximum  $F(\Delta t - \Delta \tau)$ . This can be determined by letting untracked sources drift through the beam. The characteristic "sausage" pattern (see Fig. I-3) observed on all correlators on the analog output is then used to adjust the delays for each pair. In general only NRAO staff or experienced observers will be responsible for carrying out this important calibration.

#### 4. Baseline Calibration

There is another important calibration which will also usually be carried out by NRAO staff or experienced observers after the abovementioned calibrations are finished. This is the determination of the baseline constants,  $B_x$ ,  $B_y$ , and  $B_z$  (cf. Chapter I). Observations of a number of calibrators over a range of hour angles and declinations permit one to determine errors in any assumed set of baseline constants as follows. The interferometer response for a point source at the reference position is

$$R = S \cos 2\pi B \cdot S_0$$

Earlier we discussed the fact that one can determine the displacement vector  $\Delta_S$  from phase data for a point source. It is obvious that if

then the spurious phase shifts due to baseline errors are given by (cf. Equation I-(4)

$$\Delta \phi = \Delta B \cdot g = \Delta B_x \cos \delta \cos H - \Delta B_y \cos \delta \sin H + \Delta B_z \sin \delta$$
. II-(3)

Obviously sufficient data in  $\Delta \phi$  as a function of  $\delta$  and H will permit a least squares solution for  $(\Delta B_x, \Delta B_y, \Delta B_z)$ . A special program called INTBCAL is used to obtain these solutions. Normally NRAO staff will update the baselines read into the DDP 116 after the calibration run for each move.

## 5. Practical Planning of Programs

If we assume that observing requirements of program sources are clearly known, the practical procedures of planning the observing for the interferometer is very straightforward. We assume the observer has in hand the following for all the sources he wishes to observe:

- 1. A name of ten characters or less with no imbedded blanks.
- 2. Right ascension and declination of epoch 1950.0.

The program then can be planned within the following limitations:

#### 1. Mechanical limits:

For sources with  $\delta \geq 0^{\circ}$ , hour angles cannot exceed  $\pm 5^{h}40^{m}$ . For  $\delta < 0^{\circ}$ , hour angles cannot exceed  $\pm 4^{h}40^{m}$ . In addition declinations greater than  $\pm 86^{\circ}$  and less than  $\pm 46^{\circ}$  are inaccessible.

#### 2. Mountain limits:

In the west, at large positive hour angles, the telescopes can begin observing the mountains. Figure II-3 shows an approximate outline of the mountains as seen by 85-2 on station 27. If the observer does observe a source into the mountains, he will see it clearly in the data because, firstly, the total powers increase rapidly and, secondly, the correlated signal begins decreasing in amplitude. When this occurs it is safest to delete all data with excessive total powers.

#### 3. Atmospheric limits:

The amount of atmosphere being observed through can affect the amplitude calibration slightly and the phase data a great deal. At low elevation angle, variations in the atmosphere clearly dominate the phase "noise", and these effects cannot be calibrated out. Therefore, one must adopt a minimum elevation angle below which no sources are observed. Where this limit is put depends upon how conservative the observer is, and how badly the observer needs the extra information at extreme hour angles. A moderately conservative limit is 15°. A less conservative limit is 10° and the observer flirts with trouble with a limit of 5°. Examination of Figure II-3 will allow the observer to translate these elevation limitations into hour angle limits for any declination.

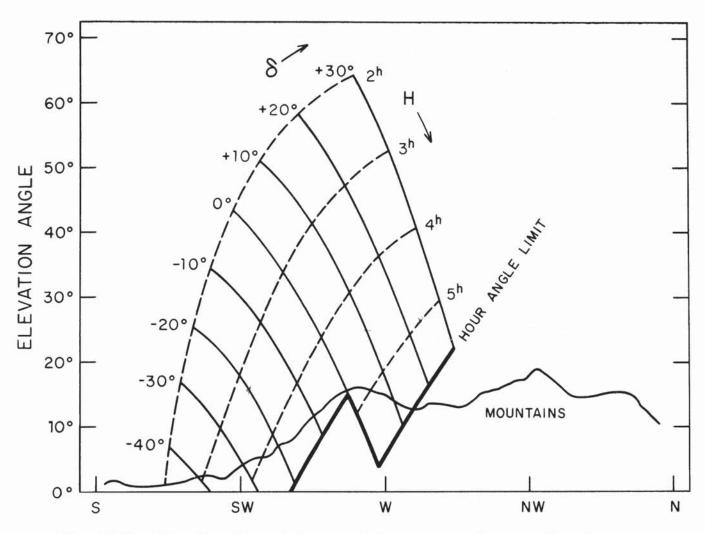


Fig. II-3. The elevation of the mountains, as seen from station 27, as a function of direction, with indication of possible hour angles and declinations for the telescopes.

The next step is to plan the times when program sources are to be observed. For various practical reasons it is useful to divide the observations into a number of 25 to 50 minute scans. Teletype printouts of the raw scan averages for a 2 minute scan will have rms' corresponding to roughly 0.01 f.u. (normally about 10 counts). This is also a convenient division to deal with when processing data in Charlottesville. For some purposes, when strong sources are involved, scan lengths of 10 or 15 minutes will be used. It is also recommended that the observer schedule an observation of a calibrator about once an hour. Some people prefer to observe a calibrator only once every two hours, but this can be inconvenient when system changes need to be monitored. A reasonable procedure is ten minutes per hour on a strong calibrator and 50 minutes per hour observing program sources. An observer may not want to spend this much time on calibrators, but it is wise to do so. Regrets occur when the observing time is used up and calibration is later found to be insufficient.

The two goals sought when monitoring calibrators are: (1) monitoring gain changes in the correlators used in observing the program sources; (2) monitoring for system phase changes ( $\phi_s$  in Chapter II). There are now sufficient numbers of point sources with excellent positions that any of the many sources listed in Appendix 1 will provide good phase calibration. Appendix 1 also gives a list of flux densities of varying dependability. It is recommended that every day some observations of sources like 3C 48 and 3C 286 be included to tie down the flux and gain calibration. Whenever possible pick phase calibrators which are also good flux calibrators. It is important to use the calibrators given in Appendix 1, with exactly the same spelling of names and 1950.0 positions, so the automatic reduction programs will be able to recognize the calibrators.

Choice of calibrators is usually made on the basis of compromising between the best calibrators available and the closest ones to the program source being observed. If the sources and calibrators are too far apart, considerable time is spent just moving telescopes. It takes about one minute to move one hour in right ascension or 15° in declination. The network of calibrators listed in Appendix 1 is extensive enough that a good calibrator can almost always be found within a couple minutes moving time of any program source. The list of excellent flux calibrators is, however, much spottier; and polarization calibration (Appendix 2) suffers even more difficulty. In the last analysis the observer must judge advantages and disadvantages in terms of what he is trying to accomplish.

Finally, once the program is laid out and specified in terms of the LST of the stopping time for each scan on each source, the observer must assign a gain setting to each source. This is because of the basic limitation that the correlators saturate above roughly 5000 counts. Therefore gain steps must bring down the count level when the source is too strong. During operation between June 1970 and January 1971, the counts per flux unit (CPFU) were typically 1000 to 1200 for the SBAND correlators and 600-800 for the XBAND correlators. Therefore, the following table gives rough rules of thumb for assigning gains:

FLUX DE	ENSITY	NUMBER OF GAIN STEPS	
SBAND	XBAND	SBAND XBAND	GAIN CODE
> 4 f.u.	> 4 f.u.	1 1	444
> 4	< 4	1 0	111
< 4	> 4	0 1	333
< 4	< 4	0 0	000

Higher gain codes can be assigned, but there are few sources with Fourier components stronger than 40 f.u. likely to be observed with the interferometer. The final gain is calculated from  $G = G_{\rm g} + 3G_{\rm g}$  where  $G_{\rm g} = 0$ , 1, etc., and  $G_{\rm g} = 0$ , 1, etc. The amplitudes are to be reduced a factor of ten for each gain step. It is possible that under the rare circumstance of a very strong source at short spacing, which is very resolved at long spacings, gain codes like 014 could be used indicating no

gain steps for the 12 correlators, one SBAND gain step for the 13 correlators, and one gain step for both SBAND and XBAND for the 23 correlators.

All of the calibrators in Appendix 1 have at least roughly known densities so that gain codes can be assigned. When cross-hand correlators are included, there are never any gain steps applied. It is not necessary since there are no strong sources that are sufficiently polarized.

The last step is punching the abovementioned information on the cards in the format shown in the example in Figure II-4. A C punched in column 40 indicates a calibrator; columns 66-80 can be used for comments. When column 38 is left blank, an epoch of 1950.0 is assumed for the punched position. If a D is punched in column 38, the precessed position may be punched on the card.

In normal operation the observer provides a deck of program cards covering all of the observations planned during any particular observing period. However, after the observing deck has been made up, there is one further detail that must be taken care of. As the data is collected, it is stored on disk in the DDP 116; however, no more than about 15 hours of data can fit on disk. It is the responsibility of the observer to indicate when the dump from disk to magnetic tape should be made. For 24 hours of data this is essentially twice a day. In addition, the observer must indicate at what point the data should be sent to Charlottesville for processing. Since the data tapes are picked up between about 0800 and 0830 local time in the morning, one usually designates a dump just before this. Normal procedure is to call for the first dump in the early evening by writing DUMP 1 on the observing card preceding the dump time; then the next dump is called for in the early morning by writing DUMP2 and SEND TO CV on an observing card.

#### 6. The Green Bank Staff

With the exception of preparation of program cards and analysis of data output, the interferometer observer does nothing with the interferometer equipment. The observer should realize that dials are not to

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2	3	4	5 6	7	9 9	10	10	2 13	14	15 1	6 17	16 1	9 20	21 2	2 23	1	1 16	27.2	9 20	20.5	1 33	77 1	24 TE	300	12/20	M.	0.41	12 4		E ACE	12.	10 5	13	e 17	Aza.			Eal	Acti		29 61	cal	Ace		0 60	10.1	11 72	77 7	1 75	16 7	1 79	70

Fig. II-4. A sample program card gives the interferometer instructions that the calibrator 3C147 is to be observed in mixed mode, with one SBAND gain step and no XBAND gain steps, until 10:50 LST.

be twiddled and switches are not to be flipped, at least by him. The operation of all equipment is the sole responsibility of the operators who work under the direction of the head operator and in close collaboration with a group of electronic specialists, digital specialists, and programmers. The operators have the responsibility to: (a) See that the observer's program cards are properly loaded into the control system; (b) See that all proper data is being recorded normally; (c) Keep a log (see examples in Figure II-5) of observations carried out; (d) Monitor essential indicators to see that the instrument is functioning normally; (e) Call for the appropriate specialists when malfunctions are found; (f) Shut down part or all of the system in case of equipment problems, excessive snow or ice on dishes, or excessive winds; and (g) keep in close contact with the observer so that program decisions can be made where necessary and so the observer is at all times aware of possible problems with the instrument. The observer can always make requests or ask questions but the operators have final authority on the operation of the instrument. This is necessary because occasionally the safety of operation can conflict with the natural desire of the observer to not lose essential data. In most cases the operator will, if possible, talk over a problem with the observer before taking drastic action. It is strongly recommended that observers take the trouble to develop friendly and courteous relationships with the operators.

The operators are not expected to be able to diagnose subtle malfunctions of the interferometer which can be detected only by examination
of the on-line output, particularly of the calibrators, although they are
familiar with the way normal fringes on strong calibrators should look
on the chart recorders. It is, therefore, the observer's responsibility
to monitor the on-line output to detect subtle malfunctions. The most
serious of these are: (a) A receiver or delay line malfunctions so that
no signal is obtained for the appropriate correlators — the operators
will frequently notice this for the calibrators, but only the observer
can judge how a particular program source should appear on-line;

#### INTERFEROMETER OBSERVING LOGS RCVR. FREQUENCY: 26 85 PAGE NO .: 4815 DATE: 4 MAY 72 OPERATOR: DS LW OBSERVER: J. SPENCER PROGRAM: B73 TAPE NUMBER RCVR. WAVELENGTH + 73.2 ms FAST AT 00:00 EST. L.S.T. CLOCK 132 3.7 cm ERROR COMMENTS I RA I DEC I RA I DEC I RA I DEC HOUR ANGLE 01 36 32 33 00 20 01 36 23 33 03 38 01 36 15 33 00 30 1644 1652 3 C 48 12 27 39 02 10 31 X BAND 1705 1721 12 27 24 02 13 09 12 27 21 02 10 50 1723 1728 12 27 42 02 10 31 12 27 27 02 13 19 12 27 24 02 10 21 S BAND 86 87 NCG 5194 1731 1753 13 28 45 47 18 25 13 28 47 47 20 14 13 28 35 47 18 15 -0525 88 H2NOSISHR 1753 1818 13 28 58 47 17 46 13 29 00 47 19 24 13 28 48 47 17 16 -050 3 89 36286 1819 1828 13 29 52 30 37 27 13 29 49 30 38 46 13 29 38 30 36 48 -0438 45 90 NGC 5194 1829 1853 13 28 45 47 18 25 13 28 49 47 20 14 13 28 37 47 18 35 - 0 42 6 91 H2NOSISSH 1853 1918 13 28 59 47 1736 13 29 02 47 19 24 13 28 50 47 17 16 -0403 92 3C 286 1919 1928 13 29 56 30 37 37 13 29 51 30 38 56 13 29 40 30 36 38 -0338 93 NGC 519 4 1929 1952 13 28 47 47 18 15 13 28 51 47 21 13 13 28 39 47 18 45 -0327 94 HZHOSISHR 1953 2017 13 29 02 47 18 15 13 29 03 47 19 54 13 28 53 47 17 06 -0303 95 36286 2019 2027 13 29 58 30 37 57 13 29 53 30 39 56 13 29 44 30 36 48 -0238 96 NGC 5194 2029 2052 13 28 48 47 19 24 13 28 52 47 21 53 13 28 41 47 19 15 -0227 97 H2NOSISNA 2053 2117 13 29 00 47 17 56 13 29 07 47 20 53 13 28 55 47 18 25 -0203 98 36 286 2119 2127 13 29 57 30 37 27 13 29 56 30 40 06 13 29 46 30 37 08 -0/38 99 NGC5194 2129 2152 13 28 49 47 18 55 13 28 55 47 22 22 13 28 43 47 19 54 -0127 4600 HONOSISHR 2153 2217 13 29 04 47 17 36 13 29 10 4721 03 13 28 56 47 17 56 -0103 01 36 286 2219 2227 13 30 00 30 37 37 13 29 57 30 40 06 13 29 47 30 37 27 -0038 02 NGC 5194 2228 2252 13 28 52 47 19 05 13 28 58 47 22 42 13 28 45 47 20 14 -0027 03 H2NOSIENR 2253 2317 13 29 06 47 17 26 13 29 13 47 21 13 13 28 58 47 17 56 -0003 04 36286 23 18 2327 13 30 04 30 37 37 13 29 54 30 40 35 13 29 51 30 37 57 +0022 05 NGC5194 23282352 132863 471915 132867 472232 132846 471954 +0033 06 HZNOSISNR 2353 0017 1329 09 4718 15 1329 10 4722 13 132859 471915 +0057

Fig. II-5. Sample observing log.

I-0-1

(b) Serious gain drifts on the time scale of hours indicating instabilities in the system; and (c) Serious drifts or discontinuities in phase centers for some or all correlators. All of these mean something happened or is happening in the system. Changes from one stable set of gains or phase centers to another set are not too serious, but the operator should be informed because it does mean that something happened, and this may be a first indication of further problems. Rapid, continuous drifts in gains or phase centers can mean worthless data and the causes must be fixed as soon as possible. In the frequent borderline cases the observer is wise to listen seriously to the advice of the operators and technical specialists. Frequently the observer is asked if he is willing to put up with a marginal situation until a maintenance period or until help presently unavailable arrives. Such decisions are up to the observer but two guidelines should be followed: (1) The honest recommendations of the operators and specialists are to be listened to and (2) it is better to fix a marginal system early before it suffers a massive failure.

#### 7. Use of On-Line Data to Monitor System

The first and simplest use of the on-line interferometer data is monitoring the health of the system and the data. This is done by noticing how well the calibrators, observed exactly at the reference position, match the theoretical ideal response. Let A be the amplitude, in counts, for a particular correlator and  $\phi$  be the phase, where both are obtained from the scan averages printed out by the teletype. Let us assume that we know that 3C 48 is 9.0 f.u. at SBAND and 3.3 f.u. at XBAND. By dividing the raw amplitudes by the known fluxes the appropriate counts per flux unit (CPFU) can be obtained. The raw data for three of the scans, recorded on the teletype output as shown in Figure II-6, can be summarized as follows:

3C48 01 36 06.2 OBSERVE UNT MODE M	47 + 33 01	AN 16880 20.406			
000140 3C4 2448008 0 224 1 1363 2 290 3 1013 4 271 5 1073	001011 -2 -131 173 26	SECT -22 -34 -6 -57 41 24	00125 49 93 47 70 46 77	RETURN  16 16 16 16 16 16 16	00001
3C48 01 36 06.2 OBSERVE UNT MODE M	SC 47 + 33 01 IL 01 10 GAIN 0	하네다면 그는 그는 그를 열리다는 하게 되었다.			
010208 3C4 2448008 0 217 1 1343 2 291 3 906 4 277 5 1178	011011 155 22	SECT -21 -46 -7 -69 45 14	00243 49 85 47 72 47 80	RETURN  15  15  15  15  15  15  15	00001
3C48 01 36 06.2 OBSERVE UNI MODE M		20,406			
020136 30 2448008 UNEXPECTED 0 216 1 1350 2 272 3 771 4 274 5 1087	-24 -136	SECT NE 5 -21 -49 -6 -73 46 13	00362 48 84 45 67 47 80	RETURN  17 17 17 17 17 17 17	00001

Fig. II-6. Three scan averages of observations of 3C48 as typed out by the teletype.

	Band		XBAND			SBAND	
	Corr. Number Pair	0 1R2R	2 1R34	4 2R3R	1 1L2L	3 1L3L	5 2L3L
Raw Scan Average Amplitudes	Scan 16880 Scan 16883 Scan 16886	224 217 216	290 291 272	271 277 274	1363 1343 1350	1013 906 771	1073 1178 1087
Raw Scan Average Phases	Scan 16880 Scan 16883 Scan 16886	- 2 -14 -24	173 155 153	5 9 0	-131 -132 -136	26 22 21	19 22 18
Approx. Syste Phase Center	m	-13	160	5	-133	23	20

For the data in Figure II-6, the scan average phases have been used to determine approximate system phase centers.

Now, dividing the amplitudes in counts by the appropriate flux densities for 3C 48 and multiplying by factors of ten to remove the effect of the gain steps, we obtain

			CPFU			
BAND		XBAND			SBAND	
Pair	1R2R	1R3R	2R3R	1L21	1L3L	2L3L
Scan 16880	679	879	811	1514	1126	1192
Scan 16883	658	882	839	1492	1007	1309
Scan 16886	655	824	830	1500	857	1208
Approx. CPFU	664	862	827	1502	997	1236

As long as the gains are stable, the CPFU remain about the same\*. The CPFU obtained from edited and corrected data usually changes by only a small amount. The major correction to be applied is that for attenuation by the atmosphere. This correction involves multiplication by  $(1+k\ sec\ z)/(1+k)$  to correct to "outside the atmosphere." For SBAND data  $k \cong 0.035$  and for XBAND data  $k \cong 0.11$ , where z is the zenith angle

<sup>\*</sup> The above numbers are fairly typical. There is more variation for the SBAND 1L3L correlator than one would like; this may be due to problems with the delay setting that were not caught earlier.

and sec z is what is frequently called the "air mass." This correction is important only for large sec z, so it can be ignored in the raw data by paying less attention to raw data for calibrators at large zenith angles (extreme hour angles).

The system phase centers from raw data will also be approximately constant for all calibrators if three conditions are met: (1) The calibrators are at the reference position; (2) The baseline constants  $(B_x, B_y, B_z)$  read into the DDP are accurate enough; and (3) Extreme zenith angles are counted as exceptions. The atmosphere induces a phase shift  $(\Delta \phi)$  proportional to sec z, therefore when sec z is large the raw phase can shift from the phase centers by a significant amount. Unfortunately, it is a fact that in the relationship  $\Delta \phi = c$  sec z, the value of c varies so much with the changes in the weather that it cannot be determined as a function of known parameters either theoretically or empirically.

With the rough rules we have outlined, the observer can tell whether the gains and phase centers are remaining roughly stable. It is recommended that the observer pay attention to such monitoring to a reasonable extent.

#### 8. Amplitude and Phase Noise

As for all radio telescope instrumentation there are limitations due to noise that affect the data from the interferometer. The rms noise fluctuations in the amplitudes can be determined either from the parameters of the system or empirically from examination of the variations in determinations of fluxes of very weak sources.

Let

 $\Delta v = I.F.$  bandwidth (= 30 MHz)

T = system noise temperature (~ 125° K)

D = diameter of each antenna (= 2590 cm)

 $\varepsilon_{a}$  = aperture efficiency ( $\geq 0.5$ )

<sup>\*</sup> We limit this discussion to system noise, there will be additional amplitude and phase noise in real data due to atmospheric effects, pointing errors, imperfections in delay tracking etc.

then the theoretical rms noise fluctuation in the amplitudes for a single telescope pair is

$$A = \frac{8(2^{1/2})kT}{\varepsilon_a \pi D^2 \sqrt{\Delta v t}}$$
 II-(4)

where k = Boltzmann constant and t is the length of observing time involved.

Using the abovementioned values for the parameters, the rms for a single 30-second record for a telescope pair is

$$\sigma = (\bar{A}^2)_{\text{theoretical}}^{1/2} \sim 0.062 \text{ flux units.}$$
 II-(5)

Now system-noise temperatures vary and the aperture efficiencies differ slightly at 3.7 and 11.1 cm; therefore a single value of  $(\bar{A}^2)^{1/2}$  is not always applicable to all telescope pairs at both frequencies at all times.

Empirical evaluations of the noise in the amplitudes indicate that on the average

for a 30-second record for a single telescope pair. This is quite consistent with the theoretical result. Therefore, barring circumstances when the noise is unusually low or high, one can use the following formula to predict the amplitude rms for a combination of N different records and correlators:

$$\sigma \sim \frac{0.07}{\sqrt{N}}$$
 f.u. II-(6)

This results in the following table:

(Flux Units)

Time	1	Pair	3	Pairs	6	Pairs
30 sec.	$\sim$	0.07	~	0.04	^	0.03
25 min.	$\sim$	0.01	$\sim$	0.006	$\sim$	0.004

Let us now discuss the probability distributions for both amplitudes and phases. Let

A = true amplitude due to a real signal

A' = a measured amplitude

P(A')dA' = the probability a measured amplitude will
be between A and A' + dA'

 $\phi$  = true phase due to a real signal

P( $\phi$ ')d $\phi$ ' = the probability a measured amplitude will be between  $\phi$ ' and  $\phi$ ' + d $\phi$ '.

Following the discussion by Vinokur (Ann. d'Ap., 28, 412, 1965), the probability distribution for a measured amplitude is given by

$$P(A') = \frac{A'}{\sigma^2} I_o \left( \frac{AA'}{\sigma^2} \right) \exp \left\{ -\frac{[A^2 + (A')^2]}{2\sigma^2} \right\}$$
 II-(7)

where  $I_{o}(x)$  is the modified Bessel function of the first kind, of order zero. This function is unity when the argument is zero, corresponding to A=0, i.e., no real signal is present. In Figure II-7, we show plots of P(A') as a function of  $A'/\sigma$  for several values of signal to noise:  $A/\sigma=0$ , 1, 2, 3, 5, and 10.

The probability distribution for the phases,  $P(\phi'-\phi)$ , is plotted in Figure II-8 as a function of  $\phi'-\phi$  for  $A/\phi=0$ , 1, 2, 3, and 5.

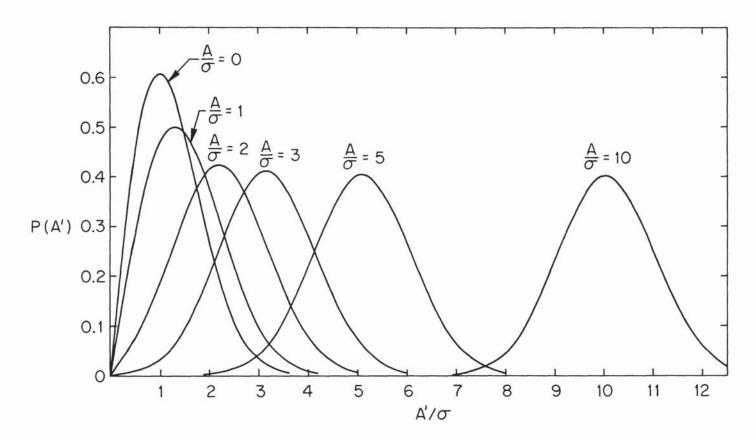


Fig. II-7. For a number of values of real signal to noise (A/ $\sigma$ ), the probability distribution of measured amplitudes (A') is plotted as a function of A'/ $\sigma$ .

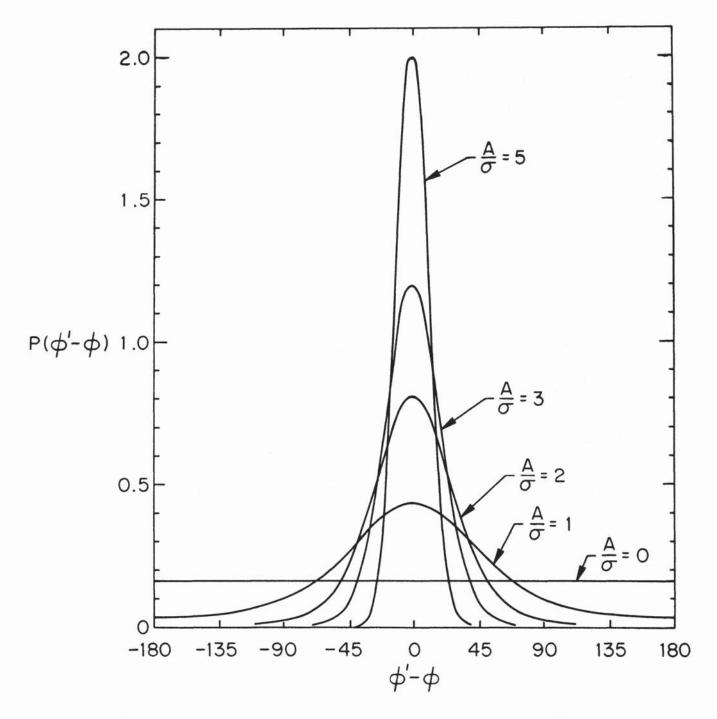


Fig. II-8. For a number of values of real signal to noise (A/ $\sigma$ ), the probability distribution of measured phases ( $\phi$ ') is plotted as a function of  $\phi$ '- $\phi$ .

We see that in the absence of a real signal all phases are in principle equally probable. As the signal-to-noise increases, the probability distribution has less and less deviation from the true phase, as seen from the following table.

A/σ	$(\phi'-\phi_0)P/P_{\text{max}} = 1/2$
	max
1	± 55°
2	± 35°
3	± 22°
5	± 13°

For large values of A/ $\sigma$  ( $^{>}_{\sim}$  2),

$$(\phi' - \phi_{\circ})_{P/P_{\text{max}}} = 1/2 \frac{2 \pm 65^{\circ}}{(A/\sigma)}$$
 II-(8)

Examination of Figures II-7 and II-8 reveals the basic reasons why the presence of a weak source will always show up most easily in the phase information. The difference between the phase distributions for  $A/\sigma=0$  and 1 are much more obvious than the differences between the associated amplitude distributions.

The user should realize that although A and  $\phi$  obey statistics with the properties we have just discussed, the real and imaginary parts of the visibility function, R and I, each separately obey Gaussian statistics.

#### 9. Confusion

We are still far from understanding the effects of confusion at flux levels as low as 10<sup>-2</sup> to 10<sup>-3</sup> flux units. Even less understood are the effects of confusion for an interferometer which has a very complex synthesized beam. However, two effects related to confusion have been fairly well established for the NRAO interferometer, based upon the experience of observers between June 1970 and February 1973. Although a detailed statistical discussion has not been made, it has been estimated that the probability of finding a single dominant point source at the 0.01 f.u. level in a 20' field at 11 cm is about 0.5. This means that detections of sources at or below this level must be

based upon sufficient information to establish position coincidences with other objects.

There is also a clear effect of an apparently spurious "detection" of radio emission in the shorter spacings ( $\stackrel{<}{\sim}$  900 m) at 11.1 cm. Quite frequently a 15-20 minute observation at these short spacings will show an apparent flux of 0.02 to 0.03 f.u. However, repeated observations do not clearly delineate any sources and maps do not clearly reveal the location of the radiation in the field. Possible interpretations range from the common occurrence of radiation sources with size scales of the order of a few arcminutes to it being a completely spurious response. In any case, an observer should, at the present time, be cautious about interpreting apparent detections from short spacing data on just a few observations.

# 10. <u>Use of On-Line Data for Preliminary Evaluation</u> of Scientific Results

In some programs rough scientific results can be obtained from the on-line data. The first questions that can be sometimes answered from the on-line data are: (1) Are there any radiation sources in the field being observed? (2) Is there a single point source in the field and if so what is its strength and rough position offset from the reference position? and (3) Is the radiation in the field more complicated than a single point source?

When the scan averages show amplitudes considerably above the rms noise level for some length of time, the situation is simple. The question of whether the field is dominated by a point source or by a distribution of radiation can be answered first. If, for a number of scans at different hour angles, all correlators give the same flux density, within the noise limits, at all hour angles, then a point source is being observed at that frequency. Significant differences in the indicated flux densities, particularly if there are systematic changes with hour angle or with the different correlators at one frequency, means there is some distribution of sources in the field. Most

of the time further on-line analysis is then not useful except to answer questions concerning what size scales are being resolved out and how much flux is in different Fourier components. When the observer has attained a certain amount of familiarity with the meaning of the fact that every measurement of amplitude and phase is a measurement of the properties of a particular Fourier component of the observed brightness distribution, then a considerable amount can be guessed about the nature of the brightness distribution by examining the amplitudes at different times for different correlators.

If the amplitudes indicate a single point source dominates the field, it can then be asked whether the source is on the reference position or somewhere else. A simple way to evaluate this is to write down the scan average phases alternating the source in question and the calibrator observed in between. The following shows the result for a series of observations of the radio star  $\beta$  Persei and 3C 48:

			Raw F	hases			
Source	LST	XiR2R	X1R3R	X2R3R	21L21	S1L3L	S2L3L
β Persei	2213	-102	152	-79	46	14	-155
β Persei	2238	-119	147	-89	36	-3	-147
3C 48	2256	- 89	167	-73	48	9	-141
β Persei	2213	-121	137	-81	45	2	-140
β Persei	2378	-110	150	-81	49	3	-138
3C 48	2356	- 91	171	-78	50	12	-142
β Persei	0013	-129	139	-85	40	13	-151
β Persei	0038	-113	159	-92	44	11	-147

These data clearly show a point source at the reference position to within a few arcseconds. Remembering that the calibrator gives the status of the phase centers, it is impossible for another source to have this degree of phase agreement with the calibrator without the source being within a few arcseconds of the reference position. It is noteworthy that this method of comparing phase will always be relatively valid if source and calibrator are close to each other, even if there are serious

<u>baseline errors or serious phase drifts</u>. In the latter case the criterion is whether the program source is showing the same drift as a calibrator at the pointing position.

If the observer knows the source is a point source from the amplitude information but the source's raw phases vary considerably, he can verify that it is a point source off position by doing one of the following tricks.

Assume six successive scan averages have been measured with raw amplitudes  $A_i$  and phase  $\phi_i$ , i = 1, ..., 5. Using a protractor with a graphical scale taped to the appropriate spot, make the plot as shown in Figure II-9, which is basically a plot of the real vs the imaginary part of the raw visibility function. The spiral behavior shown in Figure II-9 is characteristic of a point source off-position, and this change in phase is characteristically called phase "wind". For a source on position the vectors, placed head-to-tail, move out in almost a straight line in a direction corresponding to a single angle  $\phi_{\rm S}$  which is the raw system phase center. One feature of this is that the amount of phase wind should be proportional to both the baseline length and the observing frequency. In this case, except for the effects of phase noise, one gets the result, for example, that

$$\Phi_{S23} = \frac{\Phi_{S13}}{2} = \frac{\Phi_{S12}}{3} = \frac{\Phi_{X23}}{3} = \frac{\Phi_{X13}}{6} = \frac{\Phi_{X12}}{9}$$
 II-(9)

if the spacings are 2700, 1800, and 900 meters, where  $\Phi = \phi_1 - \phi_s$ . In this case data on all correlators can be reduced to a common baseline, say  $\Phi_{S23}$ , and averaged together to get mean  $\overline{\Phi} = \overline{\Phi}$  (H). Remember that all phases have 360° ambiguities, hence reduction of phase to a common baseline often involves addition or subtraction of multiples of 360°. A quick and dirty solution for  $\Delta\alpha$  cos  $\delta$  and  $\Delta\delta$  (cf. Eqn. I-(12)) can be obtained from

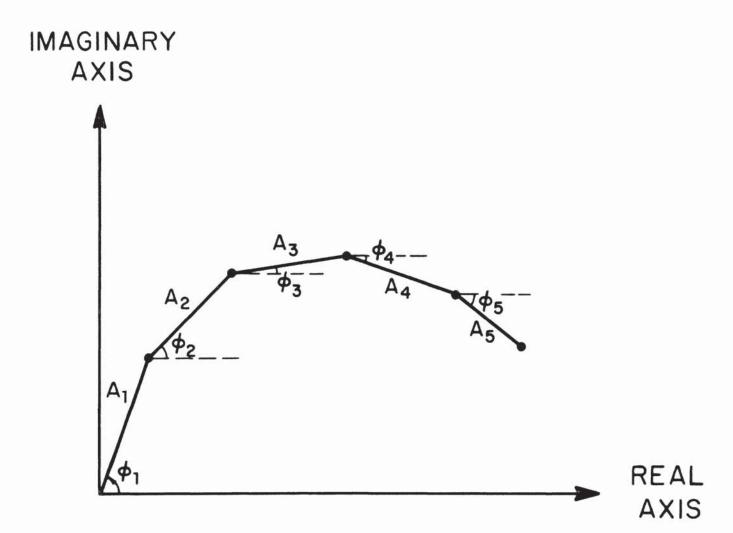


Fig. II-9. Phase and amplitude data for successive records (or scans) are schematically plotted in the real-imaginary plane to show the effects of phase wind for a point source off the reference position when observed.

$$\begin{split} \Phi(H) &= 2\pi [\mathbf{u} \cdot \Delta \alpha \cos \delta + \mathbf{v} \cdot \Delta \delta] \\ &= 2\pi [\mathbf{B}_{\mathbf{x}} \cos \delta \sin \mathbf{H} - \mathbf{B}_{\mathbf{y}} \cos \delta \cos \mathbf{H}] \Delta \alpha \\ &+ 2\pi [\mathbf{B}_{\mathbf{x}} \sin \delta \cos \mathbf{H} - \mathbf{B}_{\mathbf{y}} \sin \delta \sin \mathbf{H} + \mathbf{B}_{\mathbf{z}} \cos \delta] \Delta \delta \end{split}$$
 II-(10)

Note that if a measurement is made where u or v are zero (see typical u-v plane plots in Fig. I-8) then the solution for  $\Delta\alpha$  and  $\Delta\delta$  can be obtained very easily.

The above procedure is a crude version of what is used to obtain accurate positions for point sources from data which has been properly phase calibrated.

Judgment concerning some data with amplitudes typically less than three times the rms noise level can be made using the above-mentioned methods if the observer is conversant with the properties and statistics of Rayleigh noise. The principles are the same, but virtually all reliance is placed upon the phase data only, and some feeling for what is noise and what is not must be developed. For the previous example involving  $\beta$  Persei and 3C 48,  $\beta$  Persei was of the order of 0.16 f.u. at XBAND and 0.1 f.u. at SBAND. The following examples show the case of  $\beta$  Persei when it was 0.012  $\pm$  0.005 f.u. at XBAND but marginally present at 0.006  $\pm$  0.005 f.u. at SBAND.

#### RAW PHASES

Source		XBAND			SBAND	
	X12	X13	X23	S12	S13	S23
β Persei	159	-155	-156	- 81	150	33
β Persei	-110	107	-165	1	-150	-82
NRAO 140	-146	156	-118	-145	32	2
β Persei	-166	- 99	- 87	-157	-146	18
β Persei	-166	-137	149	-106	124	-97
NRAO 140	-133	170	-118	-140	37	2
β Persei	- 45	-154	-151	-153	- 91	43
β Persei	-115	-148	- 62	-161	91	114
NRAO 140	-116	-173	-119	-134	43	2
β Persei	- 83	- 40	- 65	-134	- 31	-97

The phase coherence at XBAND is quite good, but only marginal at SBAND.

Another example showing the difference between the appearance of a source at a mean level of about 0.01 f.u., and when it is below a detection limit of 0.005 f.u., is shown in Figure II-10, where the mean amplitudes and mean phases for the variable radio X-ray star, GX17+2, are shown for two different days. On May 27, 1971, the source was clearly present with a phase drift expected for a source ~16" from the pointing position. The mean amplitudes are typically only one rms above the expected mean noise level, but the phases, reduced to a common baseline, could be produced only by the source being really present. On May 30, 1971 the amplitudes are close to the constant bias level for the Rayleigh statistics of the amplitudes, and the phases scatter randomly.

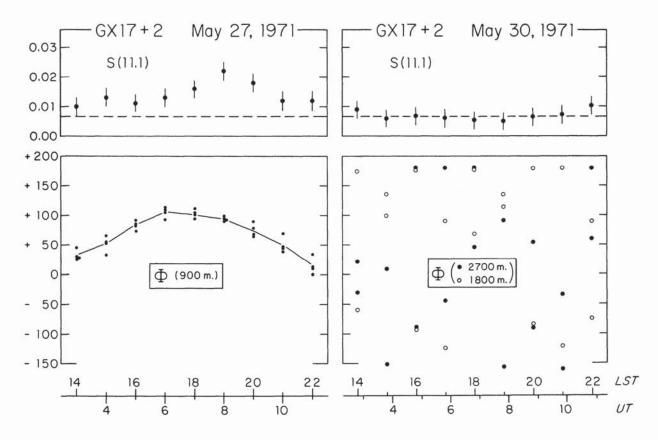


Fig. II-10. Data for the variable radio and X-ray star GX17+2, taken on a day when it was present (May 27, 1971) and a day when it was below the detection limit (May 30, 1971), are plotted as a function of LST and UT to show the difference in apparent amplitude and phase for a very weak source and complete absence of a source.

### CHAPTER III

#### PROCESSING OF INTERFEROMETER DATA

## 1. Theory of Data Processing for LL and RR Correlators

#### (a) Objectives to be Accomplished.

Interferometric data requires a great deal of cleaning, correcting, and calibrating. We will now discuss the theory of what is necessary to obtain fully calibrated visibility functions for all LL and RR correlations; in later sections, where we discuss programming details, we will further discuss how to put these principles to practical use.

It is convenient to identify three distinct stages that the data attains during the whole process of observing, cleaning, correcting, and calibrating. We will identify the uncleaned, uncorrected, and uncalibrated data, as recorded on magnetic tape in Green Bank, by double primed quantities. For example, the raw visibility function will be denoted by  $V'' = A'' \exp (i\phi'')$  where A'' and  $\phi''$  are the raw fringe amplitude and fringe phase, respectively. We will identify the final cleaned, corrected, and calibrated data by unprimed quantities, e.g.,  $V = A \exp (i\phi)$ . We will reserve the single prime to identify a very important stage in the processing where all cleaning and correcting has been carried out, but not amplitude and phase calibration.

For the LL and RR correlators, the process of cleaning, correcting, and calibrating can be described as determination of a single complex function, G, that we will call the <u>complex gain</u> of a correlator, i.e.,

$$V = G V''$$
 . III-(1)

<sup>\*</sup> Note that we will always use the word "calibration" in the strict sense whereby instrumental parameters are determined from observations of point sources with known flux densities located at the reference position.

The complex gain, G, is determined, in practice, partly from cleaning, partly from corrections for known effects, and partly from observations of calibrators. As discussed in Chapter I, in the absence of noise a calibrator observed at the reference position has

$$V = S$$

where S is the flux density. In fact, of course, one can never remove noise from real data, so the objective of calibration is to make the complex visibility function of calibrators observed at the reference position describable by

$$V = (S + \sigma_A) \exp (i\sigma_{\phi})$$

where  $\boldsymbol{\sigma}_{A}$  and  $\boldsymbol{\sigma}_{\varphi}$  describe the amplitude and phase noise, respectively.

Let us further define a quantity g that we will call the gain  $\underline{factor}$  and a phase correction  $\Delta \varphi$  such that

$$G = g \exp (i\Delta \phi)$$
. III-(2)

Obviously g and  $\Delta \phi$  are the amplitude and phase of the complex gain of a correlator. By definition, data have been cleaned, corrected, and calibrated when G has been determined for each correlator and all raw visibility functions have been multiplied by G to give

$$V = g A'' \exp \left[i \phi'' + i\Delta\phi\right] \qquad III-(3)$$

or

$$A = g A'$$

$$\Phi = \phi'' + \Delta \phi.$$

The complex gain, G, may be a time-dependent quantity and the observer should think of it as a slowly varying function.

As we will be discussing in great detail, the last stages in the determination of g and  $\Delta \phi$  are based upon observations of calibrators. We must distinguish between flux (or gain) calibrators, which are point sources with well known flux densities, and phase calibrators, which are point sources with accurately known positions observed at

the reference position. It turns out that all flux calibrators are also phase calibrators, but only a small fraction of the available phase calibrators are good flux calibrators.

#### (b) Steps to Accomplish in LL and RR Data Processing.

The determination of G and its application to the data require four distinct steps to be carried out. The first is what we have referred to as cleaning; the next two involve application of corrections that are either previously known or easily determinable; and the fourth is what we call calibration because it involves empirical determination of instrumental constants from data for sources of known flux density (amplitude calibrators) and sources with known accurate positions observed at the reference position (phase calibrators).

#### (1) Cleaning.

Malfunctions of part or all of the interferometer system require complete deletion of portions of the data. Fortunately, in most cases, only a small part of the data requires major surgery.

At every stage in the processing of data one may discover faults which require cleaning. The causes of bad data are sometimes obvious and sometimes never understood. For example, it is easy to identify bad data if: the LO is out of lock; a receiver suffers a massive failure; a delay bank malfunctions; a telescope is observing part of a mountain; or snow and ice on an antenna attenuate the signal too much. More difficult to identify, and sometimes never traceable to a known cause, are cases where: excessive rms' indicate something was wrong; or there are apparent changes in gain or phase center too erratic to make the determination of g and  $\Delta \phi$  possible. Unfortunately, detection of some problems may depend partly on luck and heavily on whether inconsistent results are blamed more on faulty data than on "things" in the sky. In this category are all sporadic equipment malfunctions, erratic variations of system "constants", brief interference, etc., which occur only during observations of program sources about which you have little idea

of expected behavior. The observer is advised to be very suspicious of the unusual, and to believe interesting results only when independent parts of the system or independent observations tell the same story.

As an aid in describing the steps to be accomplished, we can describe the cleaning process in terms of determining a function  $\mathbf{g}_D$  which is a factor in the general gain factor  $\mathbf{g}$ ; therefore we can say  $\mathbf{g}_D = 0$  for data records that are to be deleted, and  $\mathbf{g}_D = 1$  otherwise. (The subscript D stands for delete.)

Under some circumstances bad data concerning the state of the system or the observing parameters (particularly baseline parameters) can be replaced by the proper data parameters; this is a natural part of the cleaning process.

#### (2) Automatic Corrections.

There are a number of corrections, due to well-understood effects, that can be automatically applied to the data.

Several automatic corrections are lumped together in the so-called PHASE\* correction: diurnal aberration; deviation of the LO from its nominal value; phase and amplitude corrections for the effects of the correlator filters and system time constants; and, the biggest of all, differential retardation of wave fronts due to passage through different path lengths in the atmosphere. The latter effect is dominated by effects that are proportional to the secant of the zenith angle, z, but one also accounts for the effects of sphericity of the earth.

The effects of the PHASE correction are: (1) to provide a factor  $g_p$  to the gain factor  $g_p$  where  $g_p$  is very close to unity; and (2) to provide a substantial correction to the phase that we will denote by  $\Delta \phi_p$ . Because of the dominance of the sec z dependent atmospheric terms,

<sup>\*</sup> Completely capitalized words will be used to identify programs or components of programs that accomplish particular purposes.

to first order  $\Delta\phi_P \propto \sec z$ . The corrections  $g_P$  and  $\Delta\phi_P$  are calculated and applied to the data on the basis of known parameters (hour angle, declination, temperature, dew point, barometric pressure, deviations of the LO, etc.).

Corrections to the amplitudes due to attenuation in the earth's atmosphere are associated with a program component called AMPCOR calculates and applies a component of the gain factor g given by

$$g_A = ((1 + k \sec z)/(1 + k))$$

which effectively corrects the amplitudes to outside the atmosphere. Normally  $k \stackrel{\sim}{=} 0.07$  for SBAND and  $k \stackrel{\sim}{=} 0.19$  for XBAND.

The third automatic correction is associated with a program component called CLOCK. The internal clock in the interferometer system has a small, well-understood error which we will call  $\Delta t$ . This error has the effect of making the hour angle (H) in error by  $\Delta t$ . Therefore, the CLOCK correction applies adjustment to the phases by an amount  $\Delta \phi_{\mathbb{C}}$ , where

$$\Delta \phi_{C} = [(B_{y} \cos H - B_{x} \sin H) \cos \delta] \Delta t.$$

#### (3) Baseline Corrections.

As discussed in Chapter I, a key element in interferometric observing is the correction for the delay, D, which describes the extra time (or extra travel path) it takes for the same wave front to reach the second telescope in a pair after it has reached the first telescope. During the observing process this delay is compensated for based upon the equation

where  $B = (B_x, B_y, B_z)$  is the assumed baseline vector and  $S_0$  is the unit vector pointing at the reference position. Because the assumed baselines

may differ from the true ones, errors in the assumed  $\mbox{\ensuremath{\mathbb{R}}}$  result in sinusoidal phase error terms.

Whenever telescopes are moved, the observing begins with base-line parameters based upon previous experience at the same configuration; hence there are always small errors described by  $\Delta B_{\rm c} = (\Delta B_{\rm x}, \Delta B_{\rm y}, \Delta B_{\rm z})$  resulting in a phase error given by\*

$$\Delta \phi_{\rm B} = 2\pi \Delta B \cdot S_{\rm O}$$
.

Observations of calibrators at the reference position give measurements of the sinusoidal variation in phase due to  $\Delta \phi_B$ ; hence these data can be used to solve, in a least squares sense, for  $\Delta B = (\Delta B_x, \Delta B_y, \Delta B_z)$ . This solution is carried out on data for which PHASE has already been applied. At this stage in the data processing the residual phase variations of the calibrators observed at the reference position should be given by

$$2\pi \Delta B \cdot g_0 + \phi_s + noise,$$

where  $\phi_{\rm S}$  is the system phase center for the correlator in question. One must be careful to use data from calibrators covering a wide range of hour angles and declinations. Furthermore, one must be sure that changes of phase centers and short-term atmospheric fluctuations (which cannot be corrected for as yet) do not invalidate this solution. We will discuss further practical details while describing the usage of the program called INTBCAL.

In general, NRAO staff will determine the true baselines after each move, and the observer need not worry about determining them himself--unless his program requires more accurate determinations than "usual".

<sup>\*</sup> Small corrections due to non-identical telescopes and polar axes not being aligned are to be included in  $\Delta \phi_B$  if unusually great accuracy in phases is desirable, but we will not discuss them (see Wade, C. M., Ap. J., 162, 381, 1970).

#### (4) Summary of (1), (2), and (3).

Let us summarize the effects of the cleaning and automatic correction processing in terms of equations.

The net effect on the gain factor g due to cleaning and correcting can be described as contributing a complex gain factor

$$\mathbf{G''} = \mathbf{g}_{\mathbf{D}} \ \mathbf{g}_{\mathbf{P}} \ \mathbf{g}_{\mathbf{A}} \ \exp \ [\mathbf{i}(\Delta \phi_{\mathbf{P}} + \Delta \phi_{\mathbf{C}} + \Delta \phi_{\mathbf{B}})].$$

The effect of this cleaning and correcting is to produce data which need only gain calibration and phase centering. We denote the visibility function at this stage by

$$V' = A' \exp (i\phi')$$

and it is obtained from V" by

$$V' = G'' \cdot V'' = g_D g_P g_A A'' \exp [i (\phi'' + \Delta \phi_P + \Delta \phi_C + \Delta \phi_B)], \quad III-(4)$$

or

$$A' = g_D g_P g_A A''$$

and

$$\phi' = \phi'' + \Delta \phi_P + \Delta \phi_C + \Delta \phi_B.$$

#### (5) Determination of System Gain Factor and Phase Center.

After all cleaning and correcting have been accomplished, there should be only six effects still marring the data: (i) amplitude and phase variations due to system noise; (ii) phase variations due to atmospheric fluctuations; (iii) amplitude fluctuations due to imperfections in delay compensation; (iv) amplitude variations due to residual pointing errors for individual telescopes; (v) system gain effects; and (vi) non-zero system phase centers.

No one can remove system noise from data, and no one has yet figured out a way to empirically remove the effects of atmospheric fluctuations. In addition one ordinarily considers the amplitude variations due to imperfect delay compensation or pointing error to be part of the "noise" in the amplitudes; but if the effects are too large one can attempt to use observations of calibrators to determine empirical amplitude corrections.

Thus, in most cases we now need only worry about corrections for system gains and phase centers. This can be called calibration because it depends empirically upon the results of known calibration sources observed at the reference position. We must determine from these observations a system gain factor that we will call  ${\bf g}_S$  and a system phase center that we will call  ${\boldsymbol \varphi}_S$ . In principle, then,

$$V = G' V' = g_S A' \exp [i (\phi' - \phi_S)],$$
 III-(5)

so that

$$G' = g_S \exp(-i\phi_S)$$
.

One should consider  $g_S$  and  $\phi_S$  to be system "constants" that may change slowly with time, or may change abruptly due to changes (malfunctions?) in the electronics.

Only now, in discussing the transformation of the data from the V' state to the V state, are we finally at the stage assumed for much of the discussion in Chapter I. One now uses observations of good flux (or amplitude) calibrators (see Appendix 1) with flux densities denoted by S to determine, by a fit to the data,

$$g_S = \overline{S/A'}$$
.

By observations of good phase calibrators (see Appendix 1), one determines, by a fit to the data,

$$\phi_S = \overline{\phi^{\dagger}}$$
.

Once  $g_S$  and  $\phi_S$  have been determined, in principle as a function of time where necessary, all data may be calibrated by using Equation III-(5).

#### (c) Summary of LL and RR Data Processing.

If

$$V'' = A'' \exp (i\phi'')$$

represents the raw visibility function for a particular LL or RR correlator, as recorded on magnetic tape in Green Bank, then the fully cleaned, corrected, and calibrated visibility function,

$$V = A \exp (i\Phi)$$

is obtained from

$$V = G' G'' V''$$

= 
$$g_D g_P g_A g_S A'' \exp \left[i \left(\phi'' + \Delta \phi_P + \Delta \phi_C + \Delta \phi_B - \phi_S\right)\right]$$
 III-(6)

or

$$A = g A'' = g_D g_P g_A g_S A''$$

and

$$\Phi = \phi^{\dagger} + \Delta \phi = \phi^{\dagger\dagger} + \Delta \phi_{P} + \Delta \phi_{C} + \Delta \phi_{B} - \phi_{S} ,$$

where

 $g_{\mathrm{D}}^{}$  = 0 or 1 depending upon whether the item of data is to be deleted or not

 $g_{p}$  = minor contribution to gain factor due to PHASE

 $g_A$  = contribution to gain factor due to AMPCOR

 $g_{S}^{}$  = contribution to gain factor due to instrumental gain of system

 $^{\Delta\varphi}_{P}$  = phase correction due mainly to atmospheric effects, applied by PHASE

 $\Delta \phi_{C}$  = phase correction due to clock error, applied by CLOCK

 $\Delta \phi_{B}$  = phase correction for errors in assumed baseline parameters (applied using a program component called BASELINE)

 $\phi_{S}$  = system phase center.

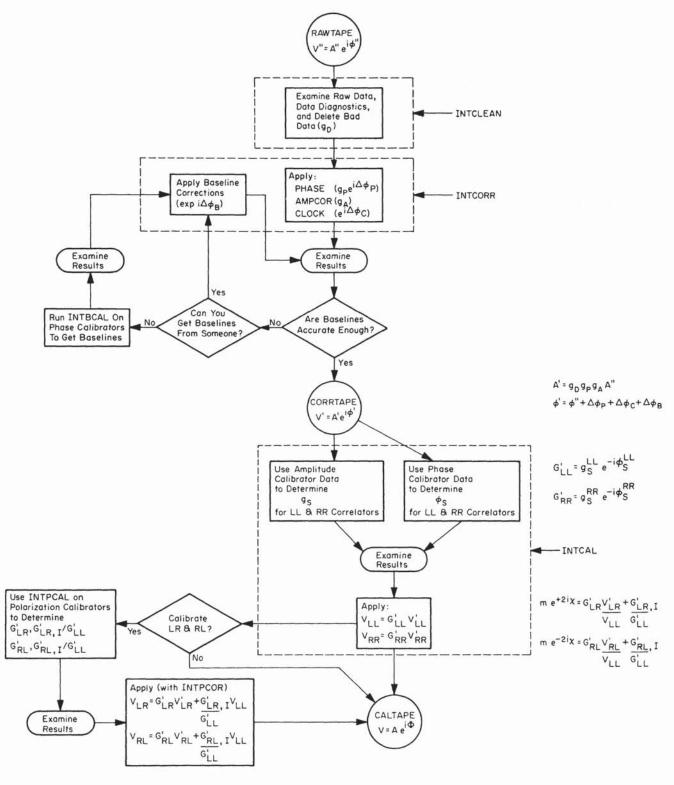


Fig. III-1. A schematic flow diagram showing the successive steps involved in interferometric data processing.

A logical flow chart showing the data processing is presented in Figure III-1. The portions of the flow chart not yet defined will be explained in forthcoming sections.

#### 2. Theory of Data Processing for LR and RL Correlators

# (a) Stokes Parameters from Measurements with Circularly Polarized Feeds.

When the NRAO interferometer operates in D, S, or X mode, one obtains data on not only LL and RR pairs but also data on LR and RL pairs which suffice to determine all four Stokes parameters:

I = total intensity visibility function

Q = linear polarized visibility function for one orientation

U = linearly polarized visibility function for 90° rotation from first orientation

V<sub>circ</sub> = circularly polarized visibility function

assuming the appropriate calibration has been carried out. The user should note that, because interferometric measurements are being discussed, the Stokes parameters take the form of visibility functions rather than just intensities.

When complete polarization information is being obtained for a particular telescope pair at a particular frequency, each of the two circularly polarized feeds, one with a right-hand (R) sense and the other with a left-hand (L) sense, produce signals which are crosscorrelated to obtain the visibility functions

$$V_{LL}$$
,  $V_{RR}$ ,  $V_{LR}$ , and  $V_{RL}$ .

The four Stokes parameters are obtained from

$$I = \frac{1}{2} (V_{LL} + V_{RR})$$

$$V_{circ} = \frac{1}{2} (V_{LL} - V_{RR})$$

$$Q = \frac{1}{2} (V_{LR} + V_{RL})$$

$$U = \frac{1}{2} (V_{LR} - V_{RL})$$

or, turning the problem around,

$$\begin{aligned} \mathbf{V}_{\mathrm{LL}} &=& \mathbf{I} + \mathbf{V}_{\mathrm{circ}} \\ \mathbf{V}_{\mathrm{RR}} &=& \mathbf{I} - \mathbf{V}_{\mathrm{circ}} \\ \\ \mathbf{V}_{\mathrm{LR}} &=& \mathbf{Q} + \mathbf{i} \ \mathbf{U} \\ \end{aligned}$$
 III-(8) 
$$\mathbf{V}_{\mathrm{RL}} &=& \mathbf{Q} - \mathbf{i} \ \mathbf{U} \ .$$

One also commonly uses the notation whereby P is the complex linearly polarized visibility function, m is the degree of linear polarization and  $\chi$  is the position angle, where

$$P = V_{LR} = Q + i U = m I \exp (2i\chi)$$

$$P* = V_{RL} = Q - i U = m I \exp (-2i\chi) \qquad III-(9)$$

$$|P| = (Q^2 + U^2)^{1/2} = m I,$$

and

$$\chi = \frac{1}{2} \tan^{-1} (U/Q) ,$$

where the asterisk denotes complex conjugation. Although m and  $\chi$  are

always definable by Equation III-(9), they will be constants for a particular source only if it is an unresolved point source which does not vary with time; otherwise they would be variable functions of hour angle, baseline separation and/or perhaps time.

#### (b) Measurement of Circular Polarization.

Although most radio sources have little or no circular polarization, it is simple to detect and measure such polarization with the NRAO interferometer if there is a sufficient circularly polarized flux. The normal calibration discussed previously for the LL and RR correlators is sufficient, and one need not have circularly polarized calibrators. Hence

$$V_{circ} = \frac{1}{2} (V_{LL} - V_{RR})$$

gives the circularly polarized visibility function and

$$|V_{circ}/I| = |(V_{LL} - V_{RR})/(V_{LL} + V_{RR})|$$

gives the degree of circular polarization.

#### (c) Causes of Instrumental Polarization.

Unlike the calibration problem for LL and RR correlators, the calibration of LR and RL correlators is dominated by the fact that inherent instrumental polarization is frequently much larger than the true polarized signal—even for the strongest calibrators.

The instrumental polarization arises from the fact that the R and L circularly polarized feeds contain imperfections whereby signals for each polarization sense are contaminated with signals of the opposite polarization sense. For example, Let  $\mathbf{E}_{R}$  and  $\mathbf{E}_{L}$  be the incident right and left circularly polarized components of the electric field, then the voltage outputs from the R and L receivers of telescopes 1 and 2 are

$$e_{1R} \stackrel{\alpha}{\sim} E_R + \epsilon_1 E_L$$
 $e_{1L} \stackrel{\alpha}{\sim} E_L + \epsilon_2 E_R$ 
 $e_{2R} \stackrel{\alpha}{\sim} E_R + \epsilon_3 E_L$ 
 $e_{2L} \stackrel{\alpha}{\sim} E_L + \epsilon_4 E_R$ 

where the  $\epsilon$ 's are small quantities usually of the order of a few percent. The output signals from the 1L2L and 1L2R correlators, for example, are then

$$V_{1L2L} \propto E_L E_L * + \epsilon_2 E_R E_L * + \epsilon_4 * E_L E_R * + \epsilon_2 \epsilon_4 * E_R E_L *$$

and

$$v_{\mathtt{1L2R}} \, \simeq \, \mathbf{E_L} \mathbf{E_R}^{\star} + \, \mathbf{\epsilon_2} \mathbf{E_R} \mathbf{E_R}^{\star} + \, \mathbf{\epsilon_3}^{\star} \mathbf{E_L} \mathbf{E_L}^{\star} + \, \mathbf{\epsilon_2} \mathbf{\epsilon_3}^{\star} \mathbf{E_R} \mathbf{E_L}^{\star}$$

so that, since the  $\epsilon$ 's are of the order of a few percent, and terms like  $E_R E_L */E_L E_L *$  are typically several percent or less, one can drop second order terms to get

and

$$V_{1L2R} \propto E_L E_R * + \epsilon_2 E_R E_R * + \epsilon_3 * E_L E_L *$$
.

Obviously the RR and LL correlators will have contamination of a few percent only when the signals are almost completely linearly polarized; and with typical linear polarizations being a few percent or less, the contamination will amount to no more than a few tenths of a percent. That is why we have not even mentioned these effects before.

However, for the LR and RL correlators, even in the case of a strongly polarized source, the terms involving  $\varepsilon$ 's are of the same order or greater than the true polarized signal. Therefore the  $\varepsilon$ 's must be determined as accurately as possible so that such terms can be subtracted from the data.

#### (d) Linear Polarization Calibration.

To emphasize the nature of the problem, let us define the calibration in terms of complex gains by which raw visibility functions are transformed into calibrated visibility functions.

We assume that all cleaning and correcting has been accomplished, i.e.,

$$V_{LR}^{\prime} = G_{LR}^{\prime\prime} \cdot V_{LR}^{\prime\prime} = g_D^{LR} \cdot g_P^{LR} \cdot g_A^{LR} A_{LR}^{\prime\prime} \exp \left[i(\phi_{LR}^{\prime\prime} + \Delta \phi_P^{LR} + \Delta \phi_C^{LR} + \Delta \phi_B^{LR})\right]$$

and

$$\text{V'}_{RL} = \text{G''}_{RL} \cdot \text{V''}_{RL} = \text{g}_{D}^{RL} \cdot \text{g}_{P}^{RL} \cdot \text{g}_{A}^{RL} \text{ A''}_{RL} \text{ exp [i($\phi''_{RL}$+$\Delta$\phi$_{P}^{RL}$+$\Delta$\phi$_{C}^{RL}$+$\Delta$\phi$_{B}^{RL}$)]}$$

in a manner identical to that for the LL and RR correlators. However, whereas for the LL and RR correlators we calibrate the data by determining  $G_{\rm LL}$  and  $G_{\rm RR}$  such that

$$V_{LL} = G_{LL}^{\dagger} \cdot V_{LL}^{\dagger} = g_{S}^{LL} A_{LL}^{\dagger} \exp [i(\phi_{LL}^{\dagger} - \phi_{S}^{LL})]$$

and

$$V_{RR} = G_{RR}' \cdot V_{RR}' = g_{S}^{RR} A_{RR}' \exp [i(\phi_{RR}' - \phi_{S}^{RR})],$$

because of the terms involving the  $\epsilon$ 's there are contributions to the LR and RL correlators proportional to both  $V'_{LL}$  and  $V'_{RR}$ , therefore we have

$$V_{LR} = G_{LR}^{\dagger} \cdot V_{LR}^{\dagger} + G_{LR,LL}^{\dagger} \cdot V_{LL}^{\dagger} + G_{LR,RR}^{\dagger} \cdot V_{RR}^{\dagger}$$
and
$$V_{RL} = G_{RL}^{\dagger} \cdot V_{RL}^{\dagger} + G_{RL,LL}^{\dagger} \cdot V_{LL}^{\dagger} + G_{RL,RR}^{\dagger} \cdot V_{RR}^{\dagger}$$
III-(10)

We see from Equation III-(10) that in general the calibration of each LR and RL correlator will involve determination of three complex gains. By making one further simplifying assumption the problem can be reduced to more manageable proportions. If we can assume

$$V_{RR}^{\prime} = C \cdot V_{LL}^{\prime}$$
,

which will be true for any source with negligible circular polarization, then we can define

$$G'_{LR,I} = G'_{LR,LL} + C \cdot G'_{LR,RR}$$

and

$$G_{RL,I}^{\dagger} = G_{RL,LL}^{\dagger} + C \cdot G_{RL,RR}^{\dagger}$$

reflecting that  $G'_{LR,I}$  and  $G'_{RL,I}$  are special complex gains describing the contamination of LR and RL correlators by the total intensity.

Equation III-(10) then becomes

$$V_{LR} = G'_{LR} \cdot V'_{LR} + G'_{LR,I} \cdot V'_{LL}$$

and III-(11)

$$V_{RL} = G_{RL}^{\dagger} \cdot V_{RL}^{\dagger} + G_{RL,I}^{\dagger} \cdot V_{LL}^{\dagger}$$

We will assume that Equations III-(11) are applicable from now on; therefore, the user should be forewarned that the reduction procedure, and the programs discussed later, do not apply to the rare cases where circular polarization is important.

Typical strong polarization calibrators (see Appendix 2) show only a few percent linear polarization. This means that even a very strong calibrator at the 10 f.u. level will have only a few tenths of a flux unit polarized flux density. Therefore calibration of LR and RL correlators amounts to determining twice as many instrumental constants as are determined for LL and RR correlators from calibrator data with much poorer signal to noise.

To carry out calibration of LR and RL correlators one uses data from at least two (and preferably more) polarization calibrators that are observed regularly throughout the observing program. To get adequate signal-to-noise for the polarized fluxes the integration time per scan should be a factor of two, three, or more longer than usual for calibrator observations.

For reasons of convenience one does not work directly with Equations III-(11), but with a form of these equations divided by  $V_{\rm LL} = G_{\rm LL}^{\, \rm I} \, \cdot \, V_{\rm LL}^{\, \rm I}, \, \, {\rm i.e.} \, ,$ 

$$V_{LR}/V_{LL} = m \exp(2i\chi) = \frac{G_{LR}^{\prime}}{G_{LL}^{\prime}} \frac{V_{LR}^{\prime}}{V_{LL}^{\prime}} + \frac{G_{LR,I}^{\prime}}{G_{LL}^{\prime}}$$

and III-(12)

$$V_{RL}/V_{LL} = m \exp (-2i\chi) = \frac{G_{RL}'}{G_{LL}'} \frac{V_{RL}'}{V_{LL}'} + \frac{G_{RL}'}{G_{LL}'}$$
.

Knowing the values of m and  $\chi$  for each calibrator, the problem, in principle, is to determine  $G_{LR}^{\prime}/G_{LL}^{\prime}$ ,  $G_{LR}^{\prime}/G_{LL}^{\prime}$ ,  $G_{RL}^{\prime}/G_{LL}^{\prime}$ , and  $G_{RL}^{\prime}/G_{LL}^{\prime}$  from a least square fit to date on  $V_{LR}^{\prime}/V_{LL}^{\prime}$  and  $V_{RL}^{\prime}/V_{LL}^{\prime}$ .

In practice the calibration is most conveniently carried out in a two-stage process where one begins with completely calibrated LL and RR correlators, but with LR and RL correlators in the  $V_{LR}^{\prime}$  and  $V_{RL}^{\prime}$  stages. One then uses Equations III-(12) to solve for  $G_{LR}^{\prime}$ ,  $G_{LR}^{\prime}$ ,  $I_{LL}^{\prime}$ ,  $G_{RL}^{\prime}$ , and  $G_{RL,I}^{\prime}/G_{LL}^{\prime}$  given data on  $V_{LR}^{\prime}/V_{LL} = V_{LR}^{\prime}/(G_{LL}^{\prime} \cdot V_{LL}^{\prime})$  and  $V_{RL}^{\prime}/V_{LL} = V_{RL}^{\prime}/(G_{LL}^{\prime} \cdot V_{LL}^{\prime})$ . The determination of  $V_{LR}$  and  $V_{RL}$  for all sources is made by first applying Equations III-(12) to determine  $V_{LR}^{\prime}/V_{LL}$  and  $V_{RL}^{\prime}/V_{LL}$ ; then one multiplies by  $V_{LL}$  to obtain the final visibility functions.

There are a number of pitfalls involved in applying LL and RR calibration before determining the LR and RL polarization "constants"—all of them related to the difficulty of identifying changes of instrumental parameters with time. We will discuss these details further when we discuss the use of the programs for processing polarization data.

### 3. Programs for Display and Manipulation of Data

In this section, and the subsequent sections of this chapter, we will attempt to introduce the methods by which one can examine the data and the programs with which one edits, corrects, and calibrates the data. For a more comprehensive description of these programs the reader should consult the "Users Guide to the Dual-Frequency Interferometer Programs", hereinafter called the "Users Guide".

### (a) Form of Data on Magnetic Tape or Disk Data Set.

All of the data gathered by the interferometer undergo the fringe-fitting process and are then written on seven-track magnetic tapes by the DDP116 in Green Bank. The data on the seven-track tapes are transferred to nine-track magnetic tapes by the 360/50 in Charlottesville. Once the raw data are available on nine-track tapes, the user, either by his own use of standard programs or by use of certain "automatic" programs, then carries out a process of data display, manipulation, cleaning, correcting, calibrating, etc. In

doing this one frequently takes data off one tape, modifying it as desired, then writes the resulting data onto other magnetic tapes, or occasionally onto disk data sets kept in disk storage by the 360/50. As a result, the basic processing we will be discussing during the remainder of this chapter involves three steps: (i) displaying and examining the data; (ii) taking it off tape or disk, modifying it as desired, and writing it on another tape or disk data set; and (iii) displaying and examining the results.

What type of data are we to display, examine, modify, etc.?

For every data scan, with length and data content chosen by the observer when making up the observing cards, the data format consists of three parts:

- (1) The <u>header</u> in which scan number, source name, right ascension and declination of reference position precessed to date of observation, baselines, date (local sidereal day number), LST (local sidereal time), observing mode, baseline parameters, etc., are recorded;
- (2) The <u>A/D records</u> (analog to digital) which contain information about temperature, dew point, barometric pressure, cable pressure, LO setting, etc.; and
- (3) The <u>data records</u>, containing, for each successive 30-second period during the scan, the real (R") and imaginary (I") parts of the raw visibility function for each correlator, the rms of the fringe-fit for each correlator, the gain settings, LST, total powers, and other diagnostics of the system. For further details the reader should consult the "Users Guide".

### (b) Need for Data-Handling Programs.

The user must become familiar with how to use a large number of standard programs (stored on disk in the 360/50) which give him access to and manipulative control of the data recorded on tape or disk. All extensive details are to be found in the "Users Guide", but we will

attempt to introduce the reader to some aspects of the most important programs. In doing so we will frequently give examples of the needed computer cards and, whenever possible, display the relevant computer output in figures.

### (c) Use of INCLUDE/EXCLUDE/END cards.

The data to be processed by many of the programs are specified by use of input cards called INCLUDE, EXCLUDE, and END cards; therefore before we can begin discussion of programs, we must explain their usage.

By use of these cards one can specify in a very flexible manner what data are to be processed by a particular program. Each card begins, in column one, with one of the three key words INCLUDE, EXCLUDE, or END. Following the key word one then lists, in any order, attributes describing the data to be included, excluded, etc. At least one blank space must occur between each attribute listed.

The attributes that can be specified are of six kinds:\*

### (1) Scan Range.

e.g., INCLUDE 1570 1580

(include all scans from 1570 through 1580)

e.g., EXCLUDE 1570

(exclude scan 1570)

e.g., INCLUDE

(default option whereby all data found on tape or disk data set are to be processed)

### (2) Source Name.

e.g., INCLUDE 3C48

#### (3) Frequency.

e.g., INCLUDE XBAND

e.g., INCLUDE\_SBAND

<sup>\*</sup> Here and in the following sections we will indicate places where at least one blank space must be present by an underline (\_) which, needless to say, is not to be punched on the cards. It is wise to assume that if no space is indicated, then insertion of a space will cause an error.

### (4) Correlator.

e.g., INCLUDE\_1R3R

possible designations: 1R2R 2R3R 1R3L RR

1L2L 2L3L 1L3R LL

1R3R 1R2L 2R3L LR

1L3L LL2R 2L3R RL

### (5) Telescopes.

e.g., EXCLUDE 85-1

possible designations: 85-1

85-2

85-3

### (6) Receivers.

e.g., EXCLUDE\_1R

possible designations: 1R 1L

2R 2L

3R 3L

Any combination of these six types of attributes may be used to describe what data is to be included or excluded; if a particular type of attribute is not specified, then all data possessing that attribute are processed.

e.g., INCLUDE 3C48\_15841\_1580\_XBAND\_1R2R INCLUDE\_15841\_15845\_85-1

The purpose of the END card is to cause the program to begin again under the control of different INCLUDE/EXCLUDE cards that follow afterwards. This is used in two forms:

END\_(Scan Number)

and

END REWIND.

e.g., INCLUDE 1500 1700 SBAND

END\_1700

INCLUDE\_1500\_1700\_XBAND

(first run is executed for scan range 1500 through 1700 on SBAND data, then program is rerun for the same scan range on XBAND data)

e.g., INCLUDE\_SBAND

END REWIND

INCLUDE\_XBAND

(first run processes all SBAND data, then it goes back to beginning of tape (or disk data set) and processes all XBAND data.)

(d) Use of Job Control Language (JCL).

The user controls what programs are to be used, what data are to be processed, and how this is to be done by means of JCL cards—with input data where necessary. We will give a minimal, abbreviated introduction to JCL usage so the user can get started.

To run any program on the 360/50 you must supply:

(1) a JOB card\*

e.g.: //INTDATA\_JOB\_(79,P,6,8,4),MSGLEVEL=1,CLASS=C (note that slashes in columns 1 and 2 are the identifying characteristics of JCL cards).

- (2) An EXEC card which
- (i) names the program to be executed
- (ii) specifies details on input and output data, either in detail or by default
- (iii) specifies parameter options (PARM = '...'), to be used in program, either in detail or by default

e.g.: //\_EXEC\_INTAVG,INTAPE=1817,INNAME=DATA,PARM='ARITH' and, depending upon the nature of the program to be executed, you may need to supply data to data files:

for programs controlled by INCLUDE/EXCLUDE cards

<sup>\*</sup> The number 79 is an example of a <u>user number</u>; every observer should see to it that the computer division has assigned him or her a user number before running on the 360/50.

(3) A card indicating a set of INCLUDE/EXCLUDE cards is to be read

e.g., //SYSIN DD \*

where SYSIN is the name of the data file

(4) The INCLUDE/EXCLUDE cards which specify the contents we wish to read into the data file SYSIN

e.g., INCLUDE SBAND

END REWIND

INCLUDE\_XBAND

## or, for programs requiring special data input

(3) A card identifying a particular data file which is to be supplied with data

e.g., //BASLINES\_DD\_\*

where a data file named BASLINES is to be supplied with data.

(4) The necessary data, usually in a particular format defined by the program being executed.

The only further details the user need be conversant with at the moment concern the EXEC card.

The PARM specification on an EXEC card is simple and straight-forward. Many programs allow the user to specify certain options in executing a program. For example, we will soon describe a program that can average together a specified number of 30-second data records. One can control the length of the average by specifying PARM='LENGTH=(time in minutes)'; and one can average the amplitudes arithmetically rather than vectorially by specifying PARM='ARITH'.

e.g., //\_EXEC\_INTAVG, PARM='ARITH, LENGTH=12'.

The more complicated part of the EXEC card involves specification of properties, numbers, and names for all input and output devices. One can supply:

(1) Information concerning whether data are on tape or disk

### e.g., INUNIT=DISK

if the device name is not specified it is assumed to be TAPE.

(2) A tape number which must be supplied whenever a tape is to be either read or written upon

> e.g., INTAPE=3359 OUTTAPE=1720

(3) The name of the tape or disk data set

e.g., INNAME=RAWTAPE

OUTNAME=CORRTAPE

INNAME='&&TEMP'

Note that each word used for a name can contain no more than 8 letters (or numbers, as long as both alphameric and numeric are present in the name); all names for disk data sets are surrounded by single quotes.

(4) Disposition of the tape or disk data set; usually whether you want to start a new one\* (NEW) at the beginning of the tape or disk data set, add to the end of an old one (MOD), or share a data set on disk with other programs (SHR),

e.g., INDISP=SHR

OUTDISP=MOD

OUTDISP=NEW

Putting it all together for a sample EXEC card:

//\_EXEC\_INTAVG,PARM='ARITH,LENGTH=10',
//\_INUNIT=DISK,INNAME='&&DATA',
//\_INDISP=SHR,OUTTAPE=1137,OUTNAME=AVDATA1,
// OUTDISP=MOD

Note that an EXEC instruction can be continued on as many cards as needed by making the last symbol, on all cards but the last, a comma. Remember also that columns 72-80 cannot be used; and the order in which one indicates PARM or unit specifications is arbitrary.

One special detail concerning disk data sets is very useful. Frequently one wants to write some data on disk for one program, then

<sup>\*</sup> Warning, with DISP=NEW, anything already on a tape or disk data set is written over and destroyed.

call another program which uses these data. One can do this by using temporary disk data sets which are identified by a double amphersand preceding a name (of six or less letters and numbers),

```
e.g., OUTNAME='&&DATA'.
```

An example of such common usage, involving programs we will discuss shortly, is\*

```
//_EXEC_INTAVG, INTAPE=1100, INNAME=SDATA,
//_OUTUNIT=DISK,OUTNAME='&&DATA'
//SYSIN_DD_*
INCLUDE_SBAND
END_REWIND
INCLUDE_XBAND
// EXEC_INTSCRIB,INUNIT=DISK,INNAME='&&DATA'
```

When the job is finished, the data set &&DATA is erased. No OUTDISP specification is necessary when the double amphersand is used.

For many programs, default specifications exist for both input and output so they can be coupled together without specifying details. For example, the default output of INTAVG is the same as the default input to INTSCRIB; therefore the above program may be written in the more compact form:

```
//_EXEC_INTAVG,INTAPE=1100,INNAME=SDATA
//SYSIN_DD_*
INCLUDE_SBAND
END_REWIND
INCLUDE_XBAND
// EXEC_INTSCRIB
```

A list of the input and output default specifications for a number of important programs can be found in Appendix 3.

### (e) Display and Examination of Data

Obviously the first requirement is for programs to allow the user to examine all or part of the data. One examines the data for

<sup>\*</sup> In listing programs we will hereinafter not write out the JOB card.

many reasons at many different stages of processing. There are two utility programs that can be used for direct display of data records: INTLOOK and INTSCRIB.

### (1) INTLOOK

The first display program is called INTLOOK. With INTLOOK one can examine virtually every piece of information written on a tape or disk data set. As a result of this, indiscriminant application of INTLOOK to all data with all possible options gives the user an enormous amount of computer output. For this reason INTLOOK is best used only to diagnose serious problems or to examine details on small amounts of data.

Two examples of the use of INTLOOK are shown in Figure III-2 where the essential outputs for the following programs are shown:

```
//_EXEC_INTLOOK,INTAPE=1547,INNAME=RAWDATA,PARM='RCVR,DELAYS'
//SYSIN_DD_*
INCLUDE_3C48_15954
    (resulting output shown in Figure III-2a)
and
//_EXEC_INTLOOK,INTAPE=1548,INNAME=CALDATA
//SYSIN_DD_*
INCLUDE_3C48_15954
```

(resulting output shown in Figure III-2b).

The first program (see result in Figure III-2a) gives us a display of the raw data for scan 15954 of 3C48, with a request for print-out of receiver parameters (RCVR; total powers, synchronous detector output) and delay setting (DELAYS). The second program (see result in Figure III-2b) displays the final calibrated data for the same scan, but without the extra diagnostic information. For both examples the data between rows of asterisks are the header contents. We see that most of the header contents are the same in Figures III-2a and III-2b, but there are small differences in baseline parameters indicating corrections have been applied. The next line in Figure III-2a tells us that

	******	******	******	*******	*******	*****	******	*****	*****	*****	******	******	*****	*****	*****	****	*****	****
	3C48 RH			1, 033 01 OS AS OPE								A 01 16		00 000	00		C48 CAN 15	954
	BX BY BZ KTERM	-4785. -15086. 6421.	944 -4 510 1 0	4356.770 5260.833 9264.529 0.0	-4533. -14292. 6083. 0.	725 550 0	-13600.0 -42878.1 18250.6 0.0	74 49	-794 337	85-27 2-229 2-220 2-960 3-0	-75 -238 101	66.688 32.659 3.380 0.0	74762 -55965 58	2.689 5.279 3.800	-1678	73.23 288.06 395.83 0.0	8	
	******								*****	*****	******	******	*****	*****	*****	****	****	****
	HOR CLOCK	EKKUK (M2	SECT 12	0.0 EDITI	NG DUNE I	2 (	) WD22=	0000										
	TEMP DEW BARO CABLE LO 750		-8 -8 752 -30131 28959	-12 14752 32 16696 0	12452 -4 12016	-93 75 70	36 -4 24 1	9296 40 7500 2036 4520	70	30 31 32	-16460 6376 -28096 12023 6	40 992 10240 7030 30128		44 6136 1567 7 175	27	36 504 936 751 384		
(a)	LST 02 53 26 02 53 56 02 54 26 02 55 26 02 55 26 02 56 27 02 56 27 02 57 27 02 57 27 02 58 27 02 59 27	666656 557655 666656 557655 666656 557655 666656 557655 666656	S 1398 X 327 S 1451 X 342 S 1365 X 333 S 1100 X 346 S 1473 X 338 S 1455	-22 126 -139 60 -22 89 -142 54 -21 111 -143 60 0 454 -141 55 -22 105 -140 59 -22 100 -140 55	AMP 1384 - 304 1394 - 300 1386 - 300 1079 300 1394 - 295 1393 - 298	174 4 108 7 172 4 107 10 173 5 -85 44 171 4 107 9 173 4 108 7 172 4	1 1188 6 278 2 1215 1 1160 2 276 2 844 5 272 5 1215 5 283 9 1212 7 278	1R3R PHI -114 -121 -123 -124 -90 -124 -115 -125 -116 -125 -116	RMS 99 42 85 42 70 45 417 40 61 42 76 42 73	AMP 1228 341 1261 348 1260 342 890 336 1272 335 1251 336 1238	18 1 -91 18 -93 19 -94	MS AMF 21 1139 47 269 97 1144 49 266 87 1139 54 266 555 1156 49 249 78 1109 48 272 88 1119 50 261 90 1131	-87 164 -87 162 -87 163 -91 163 -36 164 -86 163	RMS 86 37 70 40 68 40 92 34 76 32 38 34	AMP 1094 287 1115 285 1117 285 1127 294 1122 291 1102 292 1115	2L3L PHI 53 86 52 85 53 86 53 86 53 86 53 88 53 89 54	PMS 126 43 90 43 86 41 106 38 79 38 91 38	HA 1 - 29 1 - 30 1 - 30 1 - 31 1 - 32 1 - 33 1 - 34 1 - 35 1 - 35 1 - 36 1 - 37 1 - 38
	S/X GAINS	= 111111	/ 111111															
	LST 02 53 26 02 53 56 02 54 26 02 55 56 02 55 56 02 55 56 02 55 57 02 57 27 02 57 27 02 58 27 02 58 27 02 58 27	TP -10580 -11506 -10564 -11708 -10516 -11784 -10520 -11800 -10524 -11800 -10500 -11796	10812 29764 10748 29772 10824 29880 10760 29688 10808 29816 10816	TP -10124 -11724 -10140 -11680 -10076 -11664 -10016 -11660 -11660 -10060 -1016	SYNC 28592 21244 28660 21248 28672 21352 28868 21356 28732 21380 28676 21316	TP -13152 -12752 -13076 -12748 -13088 -12756 -13064 -12820 -13084 -12832 -13064 -12760	SYNC -32632 -32632 -32632 -32632 -32632 -32632 -32632 -32632 -32632 -32632 -32632 -32632 -32632 -32632	T -118 -125 -118 -125 -118 -125 -117 -125 -118 -125 -117 -125 -117	44 3 76 3 08 3 72 3 08 3 64 3 84 3 72 3 04 3 52 3 84 3	SYNC 12764 12764 12764 12764 12764 12764 12764 12764 12764 12764 12764 12764 12764	TP -9884 -10080 -9886 -10072 -9816 -10076 -9816 -10056 -9808 -9812	14028 20916 13952 21004 13880 20852 13828 20848 13948 13978	-10 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	568 720 580 704 716 596 560 720 572 708	SYNC 20844 17644 20860 17700 21048 17700 20976 17768 20848 17716 20772	85-1 0000 0000 0000 0000 0000 0000 0000 0	NELAYS 85-2 0027 0026 0030 0034 0038 0041 0044 0044 0044 0057 0057	65-3 UE 58 OE 5C OE 61 OF 65 OE 69 OE 71 OE 75 OE 76 OE 76 OE 76 OE 76 OE 82 OE 86 OE 84
	*******													*****	******			****
	3C48 RH	IS OBSER	36 10.17 VING WITH	1. 033 01 DS AS OPE	30.55) PATOR	RET	JRN CODE	24482 WAS	87, LS 1, CON	T 02 5	WITCHES	0000 00	56 100 000	00 000	90		C48 CAN 15	954
	BX BY BZ KTERM	-4785. -15086. 6421. 0.	926 -4 534 1 0	4356.828 5260.778 9264.604 0.0	-4533. -14292. 6083. 0.	714 563 0	-13600.1 -42878.1 18250.6	42 89	-794 337 0	85-2/ •230 •215 •974	-75 -238 101	6.691 82.645 3.922 0.0	-55965 58	2.689 5.279 3.800	224; -167	473.23 288.06 895.83 0.0	8 8	
	********								*****	*****	******	*******	*****	*****	******	*****	****	*****
	HDR CLOCK	ERROR (MS	EC) 15 -	40.0 EDITI	NG DONE I	S (PACE	WD22=	00F 2										
	TEMP DEW BARD CABLE LO 750		-8 -8 752 -30131 28959	-12 14752 32 16696	12452 -4 12016 0	-93 75 70	36 -4 24 I	9296 40 7500 2036 4520	70	16 72 30 31 32	-16460 6376 -28096 12023 6	992 10240 7030 30128		44 6136 1567 7 175	8 27	36 604 906 751 384		
(b)	LST 02 53 26 02 53 56 07 54 26 02 55 56 02 55 56 02 56 57 02 56 57 02 57 57 02 58 57 02 58 57 02 58 57 02 58 57	666656 557655 666656 557655 666656 557655 666656 557655 666656	S 866 X 322 S 899 X 338 S 846 X 328 S -1 X 341 S 912 X 333 S 901 X 333	0 127 3 61 0 91 0 55 0 112 0 61 0 -1 1 56 0 107 2 60 0 102 2 56	AMP 912 350 918 349 913 345 -1 344 918 340 917 342	L2L PHI RM: 0 10. 2 4. 0 7. 1 4. 0 10. 2 5. 0 - 0 4. 0 9. 3 4. 0 8.	8 879 8 327 4 899 8 324 8 324 8 324 1 -1 7 320 7 900 7 331 1 898 9 327	1 6 0 4 1 3 0 1 0 2	RMS 100 44 87 47 -1 42 64 78 44 75	AMP 893 338 916 345 915 340 -1 332 923 331 908 332 899	0 1 6 0 5 1 4 0 2 0 2 0	MS AMF 122 925 49 347 99 925 51 333 89 925 55 344 51 32 80 901 50 351 90 90 52 336 92 915	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	RMS 88 40 73 42 71 43 94 37 78 35 90 37 83	343	0 -1 0 -2 0 -1 -3 -1 0 0	RMS 127 45 92 45 90 43 108 40 93 40 93	HA 1.29 1.30 1.30 1.31 1.32 1.33 1.34 1.35 1.36 1.37 1.38
	S/X GAINS		/ 111111															

Fig. III-2. INTLOOK display of all 30 second records for scan 15954 in the (a) raw data stage and (b) in the completely calibrated stage.

no CLOCK or other corrections have been applied; however we see from the corresponding line in Figure III-2b that PHASE, AMPCOR, CLOCK (-40 msec), and BASELINE corrections have been applied because PACB is present. The next series of lines for both Figures III-2a and III-2b give the same contents of the same A/D records: temperature, dew point, barometric pressure, cable pressure, an index of the LO setting (which should be close to 7500000), and other parameters of less interest.

Finally, under the appropriate column labels, the detailed data for each successive 30-second record in each scan are displayed in Figure III-2. The data was taken in dual (D) mode, so the display alternates S and X-band records. The columns showing LST, BAND, AMP (amplitude), PHI (phase), RMS, and HA (hour angle) are self-explanatory. The TPOWER column contains an index roughly describing the total power levels for each of the 6 receivers (1R, 1L, 2R, 2L, 3R, 3L) in a manner we will define in a moment.

The raw data in Figure III-2a appear normal except for unusually high rms' for the pairs involving 85-1 at LST = 02 56 27, and, indeed, something was wrong there because the amplitudes and phases are also anomalous. In the raw data stage the amplitudes are given in arbitrary units of counts. The calibrated data in Figure III-2b show the results of editing (the bad data are missing as shown by the combination of -1's and 0's in the AMP and PHI columns). In addition, the phases are very well centered on zero, as they should be; and the amplitudes tell us 3C48 is 9.0 f.u. at SBAND and 3.3 f.u. at XBAND, as it should be.

The next line in both Figures III-2a and III-2b gives the number of factors of ten (equipment gains) that the amplitudes must be multiplied by for each of the six correlators.

Next, under the appropriate column labels, we have in Figure III-2a the extra diagnostic information requested by the use of

PARM='RCVR, DELAYS' in the EXEC card. For each 30-second record we see the LST, total powers, synchronous detector outputs, and the delay setting between pairs (in hexadecimal form). The diagnostic data of primary interest are the total powers, because sudden changes in these are indicators of bad data. However, because only gross changes tell you very much, the detailed numbers are not essential, and the total power index displayed with the data records is frequently sufficient. The index is calculated in steps whereby: if TP = 10000 to 10999, the index is 5; if TP = 11000 to 11999, the index is 6, etc.

One can obtain a display of LR and RL correlators by specifying PARM = 'XPOL' in the PARM field of INTLOOK. Another option that is frequently used is the display of real and imaginary parts of the visibility function for each correlator, which one can obtain by specifying PARM = 'VISFUN'.

### (2) INTSCRIB

The display program which is most often used is a very flexible program called INTSCRIB. The following program gives the INTSCRIB display shown in Figure III-3a for the same raw data displayed by INTLOOK in Figure III-2a:

//\_EXEC\_INTSCRIB,PARM='LIST',INTAPE=1547,INNAME=RAWDATA
 (results shown in Figure III-3a)

The meaning of each column in the display is obvious from previous discussions, except for the NREC column which gives the number of 30-second records involved (as we shall see, one also uses INTSCRIB and INTLOOK to examine averaged data), and the RMS index. The RMS index is calculated as follows: if RMS = 0 to 99 counts, the index is 0, if RMS = 100 to 199, the index is 1, etc.; until, with RMS of 1000 or greater, an asterisk appears. Note that the equipment gain factors have been multiplied into the amplitudes before display by INTSCRIB.

				DATA FOR CON	FIGURATION 1-18-19		
	SCAN M SOURCE	HA RMS/100 AMP1R2RPH	AMP1L2LPHI	AMP1R3RPHI	AMP1L3LPHI AMP2R3RPHI	AMP2L3LPHI NREC TPOWER	LST
	15954 SD 3C48 15954 XD 3C48	01 17 111101 8660 - 01 17 000000 3225 - 01 18 000000 8991 - 01 18 000000 3380 - 01 19 110000 8460 - 01 19 000000 3280 - 01 20 01 01 01 01 01 01 01 01 01 01 01 01 01	3504 3 19181 -1 3491 2 1 9130 0 3452 2 0 3452 0 2 3440 1 9180 -0 3 3405 3 9171 -1 3 3422 2	8791 1 3272 7 8990 0 3242 5 8583 2 3247 4 0 3201 2 9000 0 3313 3 8980 -0 3273 3 8910 -0	8930 1 9250 -1 3383 7 3470 -1 9160 -0 9260 -1 3454 5 3353 -3 9154 2 9250 0 0 9334 -5 3360 2 3201 -2 9230 0 9010 0 3313 3 3510 0 9080 0 9090 1 3321 2 3360 -1 8990 -1 9190 1	3370 -1 1 666656 ( 9140 -0 1 557655 ( 3362 -2 1 666656 ( 9170 -0 1 557655 ( 3360 -1 1 666656 (	02 53 55 02 54 25 02 54 55 02 55 55 02 55 55 02 56 26 02 57 26 02 57 56 02 58 26 02 58 56
	END						
(a)							
	COTTO ES DESCRIBE				FIGURATION 1-18-19		
	SCAN M SOURCE	HA RMS/100 AMPIR2RPH		AMPIR 3RPHI	AMPIL3LPHI AMP2R3RPHI		LST
	15954 SD 3C48 15954 SD 3C48 15954 SD 3C48 15954 SD 3C48 15954 SD 3C48 15954 SD 3C48 15955 SD 3C48 15955 SD 3C48 15955 SD 3C48 15955 SD 3C48 15954 SD 3C48 15954 SD 3C48 15954 SD 3C48	01 17 10101 13980 -2 01 17 00000 3271 -14 01 18 000000 14510 -2 01 18 000000 3424 -14 01 19 110000 33654 -2 01 19 000000 33356 -14 01 20 444401 11000 - 01 20 000000 3465 -14 01 21 100000 14730 -2 01 21 000000 3381 -14 01 22 100000 3465 -2 01 22 000000 3465 -2 01 22 000000 3466 -2	3045 174 3042 -108 3 3043 173 1 13863 -107 3 3000 173 1 10791 -86 1 3002 172 2 13943 -108 1 2957 174 1 3933 -109 1 2983 173	11887 -115 2786 -121 12157 -116 2759 -123 11609 -114 2765 -124 8440 -90 2724 -126 12156 -116 2830 -126 12123 -117 2786 -126 12021 -117	12285 19 11390 81 3411 -92 2693 16 12611 18 11400 -88 3485 -93 2602 16 12605 20 11394 -81 3428 -94 2692 16 12721 18 11098 -81 3359 -96 2724 16 12510 18 11196 -86 3365 -97 2614 164 12385 17 11317 -86	2875 87 1 666656 6 2887 86 1 1557655 1 1152 53 1 557655 6 2 2887 86 1 666656 6 2 2884 87 1 666656 6 2 2944 87 1 666656 6 2 2911 88 1 666656 6 2 2911 88 1 666656 6 2 2911 88 1 666656 6 2 2920 89 1 666656 6	02 53 25 02 54 25 02 54 55 02 55 25 02 55 55 02 56 56 02 56 56 02 57 26 02 57 26 02 58 26 02 58 26 02 59 26
	END						
(b)	01 17 I 01 18 I 01 18 I 01 18 I 01 19 I 01 20 X 01 20 I 01 21 I 01 22 I 01 22 I 01 22 I	PLOT RANGE+CORR-+-1L2L+- P A P P A P A P A P A P A P A P A P A P	S FOR AMP: 0 ->  A I I A I I A I I A I I A I I A I I A I A	1000 PER SYM -+CORR-+-1I P P P P P P P P P P P P P P P P P P P	A I I I I I I I I I I I I I I I I I I I	+CURR-+-2L3L++  A P I  P A I  A P I  A P I  A P A I  A P A I  A P A I  A P A I  A P A I  A P A I  A P A I  A P A I  A P A I  A P A I  A P A I  A P A I  A P A I	S 02 53 X 02 53 S 02 54 S 02 55 X 02 55 X 02 55 X 02 56 S 02 57 X 02 57 X 02 57 X 02 57 X 02 58 S 02 58 S 02 58
(0)					ONFIGURATION 1-18-19		
	01 17 1 01 17 1 01 18 1 01 18 1 01 19 1 01 19 20 X 01 20 1 01 21 1 01 22 1 01 22 1 01 23 1		A I I I A I I A I I A I I I A I I I A I I I A I I I A I I I A I I I A I I I I A I I I I A I		A I I I I I I I I I I I I I I I I I I I	+CORR-+-2R3R+	S U2 53 X U2 53 X U2 54 X U2 54 S U2 55 X U2 56 S U2 56 S U2 57 X U2 57 X U2 57 S U2 58 S U2 58 S U2 58

Fig. III-3. (a) INTSCRIB display, with PARM='LIST', for scan 15954 in raw data stage; and (b) INTSCRIB display, with PARM='LIST, PLOT', for scan 15954 in calibrated data stage.

There are a large number of PARM options that can be used with INTSCRIB, with the most important being the following:

PARM OPTION	DEFAULT*	USAGE
'LIST'	'LIST'	display of LL and RR data
'XPOL'	'NOXPOL'	display of LR and RL data
'SUM'	'NOSUM'	calculates and displays arith- metically averaged amplitudes and phases for all observations of each source within a particular configuration
'SORT'	'NOSORT'	data for each source displayed to- gether, with sources appearing in order first observed
'PLOT'	'NOPLOT'	amplitudes and phases to be plotted as a function of time
'RANGE='	'RANGE=1000'	range for amplitude plot (RANGE= 2000 useful when CPFU option invoked, RANGE=200 useful for very weak sources)
'NOGRID'	'GRID'	to use or not to use correlator labeling between plots for different sources
'CPFU'	'NOCPFU'	will calculate and display counts per flux unit in place of amplitudes

To illustrate the use of some of the INTSCRIB options, the following program was used to obtain the result shown in Figure III-3b:

//\_EXEC\_INTSCRIB,INTAPE=1548,INNAME=CALDATA,PARM='LIST,PLOT'

(result shown in Figure III-3b)

and to get the result shown in Figure III-4:

//\_EXEC\_INTSCRIB,INTAPE=1548,INNAME=CALDATA,

//\_PARM='CPFU,SUM,PLOT,RANGE=2000'

(result shown in Figure III-4).

<sup>\*</sup> Option invoked when nothing is specified.

Note that in the plots the symbol P ordinarily indicates the phase; however if phase and amplitude need to be plotted at the same point, an X appears. With RANGE = 1000, if AMP < 1000, an A is plotted. If  $1000 \le AMP < 2000$ , a B is plotted, etc.

The use of the CPFU option is of special importance either to obtain or to check on the gain calibration. The INTSCRIB example displayed in Figure III-4 uses a default list of calibrator fluxes which is shown in the Figure. The program then takes the data for any sources included in this list (with the same spelling of name) and displays, not the amplitudes, but the amplitudes divided by the flux densities (CPFU is abbreviation for counts per flux unit). It is usual (but arbitary) to calibrate amplitudes so that point sources have 1000 counts per flux unit. We see that indeed the 3C48 scan being displayed is very well calibrated. Because the SUM option was invoked, we have a display of the averages for all amplitudes and phases; note that the average CPFU is off by only about 2 percent, and the average phase deviation from zero is about a degree. This is somewhat better than usual. The utility of RANGE=2000 for PLOT when using the CPFU option is obvious from Figure III-4, because one can get a quick visual impression of the quality of the calibration.

Use of the CPFU option requires that S and X-band fluxes be supplied. There is a default list stored on disk (use at your own risk); however, in general, the user will want to supply his own. This is accomplished as follows (to obtain the same result as Figure III-4, except only 3C48 would appear on the list):

```
//_EXEC_INTSCRIB,INTAPE=1548,INNAME=CALDATA
//_PARM='CPFU,SUM,PLOT,RANGE=2000'
//FLUXES_DD_*
3C48 9.0 3.3
```

where, after the //FLUXES\_DD\_\* card, one supplies one card per source with: name, an SBAND flux, and an XBAND flux in (A(10), 2F(10,3)) format.

#### PARMS SPECIFIED ARE AS FOLLOWS: CPFU.SUM.PLOT.RANGE=2000

# AMPLITUDES WILL BE IN UNITS OF COUNTS PER FLUX UNIT SOURCES AND THEIR SBAND AND XBAND FLUXES HAVE BEEN SPECIFIED AS FOLLOWS:

9.000	3.300
	1.700
	2.100
	0.850
	1.500
	2.200
	2.000
	2.800
	5.000
	4.800
	2.600
4.800	10.700
	1.000
	1.200
	4.500
4-600	2.200
	5.200
	2.400
5.300	2.500
2-400	2.100
	4.600
	2.200
4-000	3.300
1.700	1.600
	2 - 200 1 - 770 6 - 400 4 - 600 10 - 100 3 - 800 5 - 300 2 - 400 3 - 900 3 - 200 4 - 000

								-		- DATA F	JR CUI	NFIGURAT	ION	1-18-19								
SCAN	М	SOURCE	HA	1	RMS/100	AMP1R2	RPHI	AMPIL2	LPHI	AMP1R3	IHAN	AMP1L3	LPHI	AMP2R3	RPHI	AMP 2L 3	1Hq1	NREC	TPOWER	L	ST	
15954	SD	3C48	01	17	111101	962	-1	1013	-1	976	1	992	1	1027	-1	997	-0	1	557655	02	53	25
15954	XD	3048	01	17	000000	977	3	1062	3	991	7	1025	7	1051	-1	1021	-1	1	666656	02	53	55
15954	SD	3C48	01	18	000000	999	-1	1020	-1	998	0	1017	-0	1028	-1	1015	-0	1	557655	02	54	25
15954	XD	3C48	01	18	000000	1024	0	1058	2	982	5	1046	5	1016	-3	1018	-2	1	666656	02	54	55
15954	SD	3048	01	19	110000	940	1	1014	0	953	2	1017	2	1027	-0	1018	-0	1	557655	02	55	25
15954	XD	3C48	01	19	000000	993	-0	1046	2	984	4	1030	5	1048	-2	1018	-1	1	666656	02	55	55
15954	SD	3C48	01	20	01		0		0		0		0	1037	-5	1027	-4	1	557655	02	56	26
15954	XD	3C48	01	20	000000	1033	2	1042	1	970	2	1006	2	970	-2	1051	-2	1	666656	02	56	56
15954	SD	3C48	01	21	100000	1013	-0	1020	-0	1000	0	1025	0	1001	0	1023	0	1	557655	02	57	26
15954	XD	3C48	01	21	000000	1010	3	1031	3	1004	3	1004	3	1063	0	1036	0	1	666656	02	57	56
15954	SD	3048	01	22	100000	1001	-1	1019	-1	997	-0	1008	0	1010	1	1005	-0	1	557655	02	58	26
15954	XD	3C48	01	22	000000	1025	3	1037	2	992	3	1006	2	1018	-1	1039	1	1	666656	02	58	56
15954	SD	3C48	01	23	100000	953	-1	1013	-1	990	-0	998	-1	1021	1	1017	1	1	557655	02	59	26

# \*\*\*\*\*\*\* AVERAGES FOR CONFIGURATION 1-18-19 \*\*\*\*\*\*\*\*\* QTY-TYPE AVG: AMP, CMS = UNNTO ARITH, PHASE = VECTOR

SOURCE	RIGHT ASC DECLINATION	AMP 1R2R P	н	AMP 1L2L	PHI	AMP 1R3R	PHI	AMP 1L3L	IH9	AMP 2R3R	PHI	AMP 2L3L	. PHI
3C48	01 36 10 +33 01 30	995	1	1032	1	987	2	1015	2	1025	-1	1023	-1
END													

# LHAND AMPLITUDES AND PHASES FOR CONFIGURATION 1-18-19 PLOT RANGES FOR AMP: 0 -> 2000 PER SYMBOL, PHASE: -180 -> +180

SCAN	SOURCE	HA							LST
15954			+	CORR-+-1L2L+-		+CORR-+-1L3L+-	+	+CORR-+-2L 3L+	+ MODE D
13131		17		x	1	X	I	×	15 02 53
		17		PΔ	1	AP	I	×	1x 02 53
		18		¥	Ī	x	1	x	15 02 54
		18		PA	1	×	1	x	IX 02 54
		19		Ç"	î	×	ī	x	15 02 55
		19		PA	î	PA	t	×	1 X 02 55
					v v		ī	x	15 02 56
		20		PA	î	Y	î	PΔ	1x 02 56
		20		, A	;	Ŷ	i	×	15 02 57
		21		ĥ.	;	Ç	i	PΔ	1X 02 57
		21		54	÷	Ç	i	x	15 02 58
		22		Š.		\$	Ť	PA	IX 02 56
		22		PA		\$	î	×	15 02 59
		23		X	1	+CDRR-+-1L3L+-		*COPP-*-31 31*	
SCAN	SOURCE	HA	+	+CORR-+-1L2L+-		+COKK-+-IF3F+-		*Clikk-*-2E3t	

# RHAND AMPLITUDES AND PHASES FOR CONFIGURATION 1-18-19 PLOT RANGES FOR AMP: 0 -> 2000 PER SYMBOL, PHASE: -180 -> +180

SCAN	SOURCE	HA							LST
15954			+	CORR-+-1R2R+		+CORR-+-1R3R+		+CORR-+-2R3R+	MODE D
	01	17	1	AP	I	X	I	PA	15 02 53
	01	17	1	x	1	AP	1	PA	IX 02 53
	01	18	1	x	1	x	1	PA	15 02 54
	01	14	1	x	1	×	ī	×	IX 02 54
	01	19	1	AP	I	AP	1	PA	IS 02 55
	01	19	I	x	1	×	1	PA	1 x 02 55
	01	20	X		X		I	PA	IS 02 56
	01	20	1	PA	1	AP	1	AP	1X 02 56
	01			x	ī	×	I	×	IS 02 57
		21		×	1	×	1	PA	1X 02 57
	01	22	I	x	1	×	I	×	IS 02 58
	01	22	1	x	1	×	1	×	IX 02 58
	01	23	1	AP	I	×	I	x	15 02 59
SCAN	SOURCE	HA	+	CORR-+-1R2R+		+CORR-+-1R3R+	+	+CORR-+-2R3R+	+ LST

Fig. III-4. INTSCRIB display, with PARM='CPFU,SUM,PLOT,RANGE=2000', for calibrated scan 15954.

The reader may have noticed that data input to INTSCRIB is not controlled by INCLUDE/EXCLUDE cards. In fact, unless scan 15954 were the only scan on the tapes used in the examples, one would get a display of all data on the tape. As we shall see, for this reason one usually combines INTSCRIB with the programs INTCOPY or INTAVG that we are about to describe.

### (3) INTINDEX

Some of the information that can be obtained in cumbersome form with INTLOOK, but which is not obtained with INTSCRIB, can be obtained in compact form with a program called INTINDEX. Figure III-5a was obtained with the following program:

//\_EXEC\_INTINDEX,INTAPE=1548,INNAME=CALDATA
//SYSIN\_DD\_\*
INCLUDE\_3C48\_15954
 (results shown in Figure III-5a).

INTINDEX gives, for each scan encountered, the scan number, source name, local sidereal day number, right ascension and declination of reference position at time of observation, RA and DEC of reference position for epoch 1950.0, LST, the hour angle range covered by the

to the data, any combination of PACB indicating which rections have been applied to the data, the interferometer spacings rounded off in hundreds of meters, and the number of 30-second records in the scan. In most cases a combination of INTINDEX and INTSCRIB will provide the user with most of the information he needs about the data.

scan, observer initials, mode, the amount of clock correction applied

### (f) Copying and Averaging Data

# (1) INTCOPY.

There are many obvious reasons why one would want to just copy certain portions of data from one tape to another, or tape to disk, etc.

INTERFEROMETER INDEX

PAGE 1

(a) SCAN SOURCE LSON RA (DATE) DEC (DATE) RA (1950) DEC (1950) LST HA RANGE DBS M CORP PACE SPACINGS RECS

15954 3C48 2448287 01 36 10-170 33 01 30-49 01 34 49-815 32 54 20-41 02 53 07 1-28/ 1-39 RH D -40 PACE 19-18-1 13

----- DATA FOR CONFIGURATION 1-18-19 -----

END

NTCORAV DISPLAY

(C) SCAN SOURCE LST HA UT \$(3.7) RMS \$(11.1) RMS ALPHA PAGE= 1
15954 3C48 2 56 27 1.34 10/11.290/ 657 9.0387 0.0651
15954 3C48 2 56 26 1.34 10/11.290/ 657 3.3648 0.0326 -0.90

	SHAND	SCAN= 1		LLINE 1-			44	SELINE 1-	3			BASELINE	2-3
	LUKK	KEAL	IMAG	AMP	PHASE	REAL	IMAG	AMP	PHASE	REAL	IMAG	AMP	PHASE
	KK	0600.00	-70.00	0000.27	-0.40	8070.00	20.00	00/0-14	C.32	5190.00	-120-00	9190.78	-0.75
	> >	9150.00	-50.00	9150.44	-0.50	9090.00	00.00	9090.20	C.38	9130.00	-60.00	9130.20	-0.38
	KL/LL	-0.77	1.01	1.27	147.00	-0.14	1.00	1.94	112.29	-1.17	-1.74	2.10	-124.00
	LR/LL	-1.32	-1.67	2.13	-120.21	-1.03	-1.09	1.50	-133.33	-0.88	1.52	1.75	120.01
	KL/KK	-0.80	1.05	1.52	141.45	-0.10	1.04	1.99	112.34	-1.15	-1.73	2.08	-123.63
/11	LK/KK	-1.37	-1.74	2.41	-120.02	-1.00	-1.12	1.54	-133.27	-0.88	1.50	1.74	120.38
(d)			PERCEN	T POL=	1.101	AMPLITUDE RMS	- 0.07	y PCS	ITICN ANGLE=	61.908			
Carlo Mar	XBAND		BAS	ELINE 1-	2		DA	SELINE 1-	3			BASELINE	
	LURK	KEAL	IMAG	AMP	PHASE	REAL	IMAG	AMP	PHASE	REAL	IMAG	AMP	PHASE
	KK	30.00	100.00	3331.50	1.12	3250.00	410.00	3250.78	3.70	3390.CO	-70.00	3390.72	-1.18
	LL	3450.00	130.00	3452.45	6.10	3350.00	220.00	3331.22	3.76	3400.00	-50.00	3400.37	-0.64
	KL/LL	-3.72	-3.45	5.00	-157.10		-4.00	4.91	-124.39	-3.C8	5.63	6.42	118.72
	LR/LL	-3.94	3.80	5.48	130.00		1.10	2.44	166.41	-5.53	-3.66	6.67	-152.73
	KL/KK	-3.83	-3.61	5.20	-130.75		-4-10	2.C7	-124.33	-3.13	5.63	6.44	119.06
	LR/KR	-4.12	3.91	5.00			1.14	5.61	168.47	-5.52	-3.10	6.69	-152.39
			PERCEN		5. 405	AMPLITUUE KMS	- 0.14	b PCS	ITICK ANGLE=	-69.817			

Fig. III-5. (a) INTINDEX display for scan 15954; (b) INTSCRIB display of scan 15954 after it has been scan averaged by INTAVG with PARM='ARITH'; (c) INTCORAV display after it has been scan averaged by INTAVG with PARM='ARITH'; (d) INTPOLAV display of scan 15954 after it has been scan averaged by INTAVG.

This is done with a program called INTCOPY which uses INCLUDE/EXCLUDE cards. To illustrate its use, all the contents of Figures III-3b, 4, and 5a could be obtained with the following program:

```
//_EXEC_INTCOPY,INTAPE=1548,INNAME=CALDATA
//SYSIN_DD_*
INCLUDE_3C48_15954
//_EXEC_INTSCRIB,PARM='PLOT'
//_EXEC_INTSCRIB,PARM='CPFU,SUM,PLOT,RANGE=2000'
//_EXEC_INTINDEX
//SYSIN_DD_*
INCLUDE
```

(results shown in Figures III-3b, 4, and 5a).

In the above program we used INTCOPY to select the data we wanted, then its (default) output provided the (default) input to three programs in a row.

### (2) INTAVG

### (i) Program Description

Frequently one wishes to average together a number of 30-second records in order to improve the signal-to-noise (or for some other reason). This is accomplished by INTAVG under control of a number of PARM options and the usual INCLUDE/EXCLUDE cards. The most useful PARM options are:

PARM OPTION	DEFAULT	USAGE
'ARITH'	vector average	amplitudes averaged arith- metically
'LENGTH='	entire scan	specifies time length for average (in minutes)
'NOSCAN'	no more than a single scan aver-aged together	data in adjacent scans with same source name are averaged together

As an example, the following program will average together all the 3C48 data in scan 15954 and the result is then displayed using INTSCRIB:

(results shown in Figure III-5b)

# (ii) Arithmetic vs Vectorial Averaging

The user should understand the ways in which data are averaged. Remember that the data, for each correlator, stored on tape are recorded as the real (R) and imaginary (I) parts of V. If N records are to be averaged together vectorially:

$$\overline{R} = \sum_{i=1}^{N} R_i / N$$

$$\overline{I} = \sum_{i=1}^{N} I_i/N$$

and the displayed "average" amplitude and phase are

$$AMP = (\bar{R}^2 + \bar{I}^2)^{1/2}$$

and

PHI = 
$$tan^{-1} (\overline{1}/\overline{R})$$
.

For arithmetic averaging of amplitudes (PARM = 'ARITH'):

AMP = 
$$\sum_{i=1}^{N} (R_i^2 + I_i^2)^{1/2}/N$$
,

with PHI still being obtained as above.

To illustrate the difference between arithmetic and vectorial averaging of amplitudes, let us consider an example of a point source with flux density S observed at the reference position. Let  $\boldsymbol{\sigma_i}$  be the rms noise for the i-th 30-second record. Under these circumstances

$$R_{i} \stackrel{\sim}{=} S + \sigma_{i}$$

$$I_{i} \stackrel{\sim}{=} \sigma_{i}$$

$$A_{i} \stackrel{\sim}{=} / R_{i}^{2} + I_{i} \stackrel{\sim}{=} S \left[ 1 + \frac{2\sigma_{i}}{S} + \frac{2\sigma_{i}^{2}}{S^{2}} \right]^{1/2}$$

so that: if S >>  $\sigma_i$ , then  $A_i = S + \sigma_i$ ; but if S <<  $\sigma_i$ , then  $A_i = 2^{1/2} \sigma_i$ .

Now with vectorial averaging of N records to obtain an average amplitude,

where

However, with arithmetic averaging,

$$\bar{A}_{arith} = \sum_{i=1}^{N} A_i = S + \bar{\sigma} \text{ if } S >> \bar{\sigma}$$

and

$$\stackrel{\sim}{=} 2^{1/2} \bar{\sigma} \text{ if } S << \bar{\sigma}$$
.

Obviously, in the vectorial average case, averaging N records gives a mean amplitude noise of  $\overline{\sigma}/N^{1/2}$ , whereas for the arithmetic average in most cases the mean amplitude noise is  $\overline{\sigma}$ .

It might seem as if arithmetic averaging should never be used, but this is not true. Whenever the phases (real, not just noise) vary significantly over the range considered for averaging, the above considerations do not apply and arithmetic averaging is preferable since only amplitude noise is introduced and not phase "noise". In practice, one prefers arithmetic averaging when one knows a single strong point source is all that is being observed. Whenever a point source with S of the order of, or less than,  $\bar{\sigma}$  is involved, only vector averaging should be used. It is obvious, but perhaps should be mentioned, that averaged amplitudes will have a very complicated meaning whenever there is more than a single point source in the field.

### (3) INTCORAV

It is obvious that, in addition to the averaging done for each correlator by INTAVG, it would be useful to use the data on all correlators to calculate fluxes whenever point sources (like 3C48) are involved. This is invoked by calling upon INTCORAV after INTAVG has obtained the averages for each correlator, e.g.,

```
//_EXEC_INTAVG,INTAPE=1548,INNAME=CALDATA,PARM='ARITH'
//SYSIN_DD_*
INCLUDE
//_EXEC_INTCORAV
```

(result shown in Figure III-5c).

In addition to calculating the flux densities in flux units, INTCORAV will: (i) calculate the Universal time for the time of observation; (ii) calculate crude rms' based upon the scatter between different correlators; and (iii) calculate the empirical spectral index.

ALPHA = 
$$\log (S_{8085}/S_{2695})/\log (8085/2695)$$
.

Note that the UT is given by MONTH/DAY OF MONTH AND FRACTION OF DAY/ HOURS AND MINUTES OF DAY. We see from Figure III-5c that scan 15954 was taken October 11, at 0657 UT. The philosophy with which one uses INTCORAV is obviously to use the INCLUDE/EXCLUDE card specification of INTAVG to control what point sources are to be used to determine averaged fluxes. INTCORAV will read only temporary disk data sets named '&&OUTNAME', which is the default output name for both INTAVG and INTCOPY.

### (4) INTPOLAV

Once all LL,RR,LR, and RL correlators have been cleaned, corrected and calibrated, one often wishes to examine the average polarization parameters for each scan. This is accomplished using a program called INTPOLAV. INTPOLAV obtains averaged records written on disk by INTAVG and then does the following: First  $V_{LR}/V_{LL}$ ,  $V_{RL}/V_{LL}$ ,  $V_{RL}/V_{LL}$ ,  $V_{RL}/V_{RR}$ , and  $V_{RL}/V_{RR}$  are calculated for each baseline. The resulting twelve values for the percentage of linear polarization (m) and position angle ( $\chi$ ) are then averaged to obtain mean values. In addition, a crude rms estimate is obtained by subtracting the minimum of the 12 calculated percentage polarizations from the maximum, and dividing by 12.

As an example, the following job was used to obtain the INTPOLAV output for scan 15954 of 3C48:

```
//_EXEC_INTAVG,INTAPE=3087,INNAME=CALDATA
//SYSIN_DD_*
INCLUDE_3C48_15954
//_EXEC_INTPOLAV
    (result shown in Figure III-5d).
```

Obviously INTPOLAV is to be used with the same philosophy as INTCORAV--using the INCLUDE/EXCLUDE capabilities of INTAVG to pick out what data is to be averaged. In general, all that is

required for use of either INTCORAV or INTPOLAV is that the data be available on disk with the name &&OUTNAME (see Appendix 4).

### 4. Programs for Cleaning, Correcting and Calibrating Data

### (a) INTEDIT

### (1) Use of INTEDIT.

The all-purpose program for cleaning, correcting, and calibrating data, with the observer deciding upon and controlling the details, is called INTEDIT. In the normal course of events the user will rely upon INTEDIT mainly to solve problems that cannot be handled by the more automatic programs that we will soon discuss. However, in all cases the automatic programs (INTCLEAN, INTCORR, INTCAL) just carry out groups of tasks performed by INTEDIT; therefore we need to discuss its features first.

INTEDIT allows the user to modify, delete, correct, calibrate, etc., data by reading it from tape or disk, performing the desired changes, and writing the resulting data on another tape or disk data set. One decides what to put into INTEDIT by making appropriate use of INTSCRIB (and occasionally INTLOOK), INTAVG, INTBCAL and the diagnostic features of INTCLEAN.

The user instructs INTEDIT concerning what is to be done by means of what are called <a href="edit cards">edit cards</a>. Each edit card is composed of two parts called the <a href="edit cards">verb field</a> and the <a href="edit adverb field">adverb field</a>. The verb field contains specification of a function to be performed (the <a href="edit verb">verb</a>) and the attributes of the data to be processed; the usage of the verb field is very similar to the usage of INCLUDE/EXCLUDE cards. The adverb field gives specific information in terms of numbers, names, etc., that are needed to accomplish the desired editing. Verb and adverb fields are separated by a semicolon. The verb field must precede the adverb field and a verb name must be present. As with the INCLUDE/EXCLUDE cards, it is optional whether the verb field will limit the scope of the data to

be processed. The verb field may specify scan range, LST range, telescopes, correlators, frequencies, telescope pairs, and source names. The symbols for these are the same as for INCLUDE/EXCLUDE cards, except: we can use BL12, BL13, and BL23 to indicate baseline pairs, and LST is indicated by spaced hours, minutes, and seconds enclosed in parentheses, e.g., (10\_24\_57). The verb fields may be in any order, but the beginning scan number or (LST) must precede the terminating scan number (or LST). If no scan range is specified, all scans will be processed. If no LST range is given, all times are processed. If only one scan number or LST is given, this value is used for both beginning and terminating the processing. If no telescope numbers, correlators, frequencies, telescope pairs, or source names are specified, all are assumed.

In both verb and adverb fields any parameter with a format of (hours, minutes, seconds) or (degrees, arcminutes, arcseconds) must be enclosed in parentheses with a blank between each part.\* Any source name with imbedded blanks or which is completely numeric in content must be enclosed in single quotes. Adverb parameters can be separated by blanks or commas.

INTEDIT is used in almost the same way as the other programs we have discussed. For example,

```
//_EXEC_INTEDIT,INTAPE=1601,INNAME=RAWDATA,
//_OUTTAPE=1603,OUTNAME=CALDATA,OUTDISP=NEW
//INTERP.SYSIN_DD_*
  (edit cards)
```

When the program executes it does so in four steps: (i) interpreting, which reads the edit cards and passes one 64 byte record per card to the next step; (ii) sorting, whereby the records to be processed are sorted and arranged by scan number and priority level; (iii) listing, where a list of the sorted records is produced; and (iv) editing, where the actual editing is carried out.

<sup>\*</sup> No extra spaces are allowed within the parentheses.

### (2) Verbs Available in INTEDIT.

Let us now list the names of the verbs and their usage in connection with the verb and adverb fields.

The first two verbs control what data is to be transferred from the INUNIT to the OUTUNIT:

TRANSFER (verb parameters); no adverb required, all data specified are transferred to the OUTUNIT.

e.g., TRANSFER\_1500\_1575; will cause scans 1500 through 1575 to be transferred.

STOP (final scan number); no adverb required, editing terminates after the specified scan or before processing scans with numbers greater than the specified scan. Editing will resume anew only if further edit cards follow.

e.g., STOP\_1575; will stop the processing when scans greater than 1575 are encountered.

Next are the series of verbs whereby data can be flagged\* as bad (or unflagged);

DELETE (verb parameter); no adverb required, used to specify which data records are to be flagged.

e.g., DELETE\_(12\_17\_13)(12\_55\_43)\_17890\_SBAND; will cause all SBAND data in scan 17890 to be flagged if the LST is between  $12^h17^m13^s$  and  $12^h55^m43^s$ .

Flagging is performed if data in a specified word number or bit number do not satisfy a specified test (<,>, or =) (see "Users Guide" for information about record types and word or bit numbers).

ERASE (verb parameters); TYPERECORD. The specified record type is not transferred to the OUTUNIT. If the adverb is omitted, the entire

<sup>\*</sup> A data record is flagged by changing its weight from 1 to -1; whenever programs encounter flagged records they bypass and ignore them.

scan is erased. This is much more drastic than flagging because one cannot easily restore the data if desired later on.

RESTORE (verb parameters); no adverb required, the data records which have been flagged are unflagged or restored to original condition.

e.g., RESTORE 1789 SBAND;

Next are four verbs that are used for automatic corrections which must be applied only once to the data.

PHASE (verb parameters); no adverb required, both phases (mainly) and amplitudes (very slightly) are adjusted for effects discussed earlier, using parameters from A/D records and headers.

e.g., PHASE;

all data is processed by this once.

AMPCOR (verb parameter);  $k_s - k_x$ . The correction to outside the atmosphere is applied (affecting only amplitudes). Default values of  $k_s$  and  $k_x$  are 0.07 for SBAND and 0.19 for XBAND.

e.g., AMPCOR;

usually the default values are satisfactory.

CLOCK (verb parameters); (error) . The clock error, in seconds of time, is removed from the phase data, where F indicates it is fast (positive clock error), S that it is slow (negative clock error).

e.g., CLOCK\_1795\_1870; 0.015S.

BASELINE (verb parameters);  $(B_x)_{-}(B_y)_{-}(B_z)_{-}(k)$ . Phases are modified based upon difference between old and new baselines.

e.g., BASELINE 1798 1900 SBAND BL12; -6812.271 -21440.015 9115.563 0.0.

Note that the BAND must always be specified, and the pair involved (BL12, BL13, or BL23).

Finally there is the set of verbs used to make various changes in the data.

REPLACE (verb parameters); TYPERECORD\_WORDNUMBERORBITNUMBER\_
REPLACEMENT VALUE. The correct contents of a particular bit number or
word are replaced by a replacement value. The replacement value may
be preceded by 0 (octal), H (hexadecimal), or enclosed in single quotes.

e.g., replace 1570; 2\_16\_0.

POSITION (verb parameters); (RA)\_(DEC). Phases are adjusted such that an old reference position is replaced by a new reference position.

e.g., POSITION\_SCOX-1; (16\_18\_23.249)(-15\_34\_37.84).

HEADCORR (scan number for previous good scan); RA=(H\_M\_S)

+ DEC=(D M\_S)\_LST=(H\_M\_S)\_SCAN=...\_MODE=...\_SOURCE=...

Used to correct information in headers. The first header following the scan specified in the verb field is updated by the adverb parameters. The other header information is copied from the specified scan. Continuation cards, for this verb only, must contain a + in column 1.

e.g., HEADCORR\_670; MODE=D\_SOURCE=SCOX-1\_LST=(14\_13\_45) means that scan 671 will have its header information changed as specified by the adverbs, with the other information being copied from scan 670.

MULTIPLY (verb parameters); (number or set of six numbers). The visibility functions are multiplied by the given number, or, if all six correlators (1R2R, 1L2L, 1R3R, 1L3L, 2R3R, 2L3L) are to be multiplied by numbers, all six can be specified. Used for manual gain calibration, where the numbers are the  $\mathbf{g}_{\mathbf{g}}$  discussed earlier.

e.g., MULTIPLY\_1000\_1070\_SBAND\_1R2R; 1.35 or MULTIPLY \_1000\_1070\_SBAND: 1.35\_1.23\_0.91\_1.1\_0.98\_1.7.

PHICENT (verb parameters); (number or set of six numbers).

The phases are decreased by the specified amount, usually to accomplish phase centering.

e.g., PHICENT\_1000\_1070\_SBAND\_1R2R;-107 PHICENT\_1000\_1070\_SBAND:-107\_17\_98\_-37\_75\_-100

### (3) Tape Manipulation.

or

In all of the data processing one soon adopts the habit of thinking of the data processing in terms of trying to create certain data tapes. Each of these data tapes correspond to one of the stages defined earlier in this chapter while discussing the theory of data processing. It is very difficult to process interferometric data without using at least three tapes, and frequently even more are used. For the rest of this chapter we will discuss straightforward methods of processing involving three magnetic tapes. As an example, we will illustrate the steps in the processing with a segment of about eleven hours of data taken on September 30, 1972.

We assume that the data exists in raw form (V"=A" exp  $i\phi$ ") on a tape that we will call RAWTAPE and that good amplitude and phase calibrator observations are interspersed throughout the data. We can use either INTEDIT or a combination of INTCLEAN and INTCORR to perform the cleaning and correcting needed to produce data (V'=A' exp  $i\phi$ ') on a tape we will call CORRTAPE. Finally, complex system gain calibration with either INTEDIT, or INTCAL, for LL and RR correlators, and programs called INTPCAL and INTPCOR for LR and RL correlators, are used to produce data (V=A exp  $i\phi$ ) on what we will call a CALTAPE. This sequence of happenings has been schematically represented in Figure III-1.

### (4) Cleaning Data with INTEDIT.

The cleaning process, which we have not defined clearly as yet, involves deletion of all bad data and, wherever possible, replacement of bad data with good data. By deletions we usually mean flagging of data records or entire scans; by replacement of bad data with good we mean the rectification of mistakes made when headers or A/D records were written. Unfortunately, bad data records cannot be replaced.

The first step in cleaning data is to examine both the data itself and the data diagnostics generated by the DDP116 during the process of recording the data. The usual method of examining the data is to obtain INTINDEX output for each of the scans and an INTSCRIB display of all the 30-second data records. The data diagnostics are obtained from use of INTCLEAN.

We will illustrate the methods of data processing by giving the programs and resultant output used in processing a set of data consisting

primarily of point sources. The scan range involved is 14969 to 15028. To obtain the INTINDEX (see Figure III-6), INTSCRIB (see Figure III-7, with parts a through n referring to successive pages of computer output) and INTCLEAN (see Figures III-8 and 9) displays for this scan range, one can use the following programs:

```
//_EXEC_INTCOPY,INTAPE=3085,INNAME=RAWTAPE
//SYSIN_DD_*
INCLUDE_14969_15028
//_EXEC_INTINDEX
//SYSIN_DD_*
INCLUDE
//_EXEC_INTSCRIB
//_EXEC_INTCLEAN
    (results shown in Figures III-6, 7, 8, and 9)
```

Examination of the INTINDEX display (Figure III-6) informs us concerning what data on what sources are contained in the scan range of interest. First signs of bad header information can also appear in terms of nonsensical results for certain scans, particularly nonsensical baseline information.

Next one examines the INTSCRIB display of the 30-second data records (Figure III-7), with the INTCLEAN display of data diagnostics (Figures III-8 and 9) on one hand and the observing logs on the other. Problems noticed by the operators during the observing will be noted in the logs and the appropriate data records can be submitted to close scrutiny. Most of the time the data diagnostics generated by INTCLEAN are of greatest use in detecting bad data. For the moment we will concentrate on only the diagnostic display provided by INTCLEAN, ignoring the messages concerning deletions performed by INTCLEAN; these deletions are part of the "automatic" processing to be discussed later.

The diagnostic summary shown in Figure III-9 gives a listing of the various errors, with a severity proportional to the indicated number of asterisks. We will not discuss each type of message in detail because the user will find that only experience, guided by what the user hopes to achieve, allow proper interpretation of these messages.

			INTERF	EROMETER INDE	x				PAGE	1
SCAN SUURCE L	SDN RA (DATE)	DEC (DATE)	RA (1950)	DEC (1950)	LST	HA RANGE	DBS M	CLOCK COPR PACE		DATA
15002 P0607-15 2448 15003 P0056-17 2448 15004 3C454-3 2448 15006 3C119 2448 15006 3C119 2448 15006 3C119 2448 15007 P01064-01 2448 15008 P0438-43 2448 15007 P0614-34 2448 15010 3C138 2448	1275 02 26 37.777 1275 02 03 23.638 1275 04 30 44.731 1275 02 03 1.718 1275 01 50 31.718 1275 15 03 1.718 1275 17 02 03 1.718 1275 17 02 03 1.718 1275 17 03 1.718 1275 18 19 18 4.7539 1275 18 19 18 4.7539 1275 18 19 18 18 18 18 18 18 18 18 18 18 18 18 18	33 01 28.48 67 13 48.75 15 06 35.77 41 35 04.41 -28 36 07.90 -28 36 07.90 08 03 14.03 42 09 01.59 16 00 24.38 -21 00 25.77 -17 09 11.16 33 01 28.48 -28 36 07.90 40 52 08.98 -21 00 25.77 -33 01 28.48 -28 36 07.90 40 52 08.98 -21 00 25.77 -33 01 28.48 -28 36 07.90 40 52 08.98 -21 00 25.77 -33 01 28.48 -21 00 25.77 -33 01 28.48 -21 00 25.77 -35 01 28.94 -49 50 18.94 -49 50 18.94 -41 35 04.41 -16 22 49.38 -17 03 43.58 -17 04 40.75 -18 00 24.38 -17 05 18 04.13 -05 05 09.78 -16 00 24.38 -17 05 18 04.13 -05 05 09.78 -16 00 24.38 -17 09 11.16 -16 00 24.38 -17 09 11.16 -16 00 24.38 -17 09 11.16 -16 00 24.38 -17 09 11.16 -16 00 24.38 -17 09 11.16 -18 02 24.38 -17 09 11.16 -18 02 24.38 -17 09 11.16 -18 02 24.38 -17 09 11.16 -18 02 24.38 -17 09 11.16 -18 02 24.38 -17 09 11.16 -18 02 24.38 -17 09 11.16 -18 05 04.41 -18 15 06 35.77 -18 10 07 -18 10	21 49 10.582 20 30 37.627 01 14 25.924 01 34 49.812 02 24 41.126 05 38 43.491 05 38 43.491 04 29 07.884 03 16 09.127	32 54 20.65 67 07 40.10 14 59 50.61 44 59 50.61 44 132 08.67 -28 42 36.69 -28 42 36.69 -28 42 36.93 42 02 08.83 15 52 53.82 -21 07 53.54 -17 16 48.32 32 54 20.65 -28 42 36.61 40 47 12.38 -21 07 53.48 32 54 20.40 67 07 39.75 49 49 42.76 41 32 08.53 16 17 40.17 -21 07 53.48 15 52 53.66 17 40.91 19 00.98 32 08 36.70 11 49 09.51 01 19 00.98 32 08 36.70 17 49 09.51 01 19 00.98 32 08 36.70 17 49 09.51 05 14 59.19 -05 12 17.30 15 52 53.66 32 54 20.40 32 54 20.40 32 54 20.40 32 54 20.40 32 54 20.40 32 54 20.40 32 54 20.40 32 54 20.40 32 55 253.66 32 57 20.40 32 58 20.40 32 58 20.40 32 58 20.40 32 58 20.40 32 58 20.40 32 59 20.40 32 59 20.40 32 59 20.40 32 59 20.40 32 59 20.40 32 59 20.40 32 59 20.40 32 57 20.40 32 57 20.40 32 58 20.40 32 58 20.40 32 59 20.40 32 57 20.40 32 58 20.40 32 59 20.40 32 50 20.40 32 50 20.40 32 50 20.40 32 50 20.40 32 50 20.40 32 50 20.40 32 50 20.40 32 50 20.40 32 50 20.40 32 50 20.40 32 50 20.40 32 50 20.40 32 50 20.40 32 50 20.40 32 50 20.40 32 50 20.40 32 50 20.40 3	22 12 57 22 23 17 22 33 05 22 42 19 22 55 37 23 02 25 5 37 23 12 09 23 12 17 23 32 17 24 13 20 25 27 27 27 27 27 27 27 27 27 27 27 27 27 27 2	-1.54/-1.42 -5.39/-5.28 -2.15/-2.04 4.18/ 4.26 3.82/ 3.94 1.28/ 1.28	EFF 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0		19-18-1 19-18-1	1444508544512350276544611114 11154044463355435764
			INTERF	EROMETER INDE	x	на		CLOCK	PAGE	2 DATA
SCAN SOURCE L	SDN RA (DATE)	DEC (DATE)	RA (1950)	DEC (1950)	LST		08S M	CORR PACE		
15023 1216+48 2448	3276 11 17 31.738 3276 05 19 36.798 3276 05 40 31.165 3276 12 17 45.541 3276 12 43 30.839 3276 12 45 52.330 3276 13 16 20.627 3276 13 18 37.494	10 15 19.82 12 43 40.19 16 36 56.18 49 50 19.02 48 39 01.12 40 57 08.77 49 09 15.05 34 34 27.15 51 56 49.91 30 38 58.49	07 42 48.445 11 16 20.730 05 18 16.507 05 38 43.548 12 16 38.905 12 42 26.403 12 44 50.102 13 15 17.997 13 17 41.495 13 28 49.664	10 18 33.01 12 51 06.82 16 35 27.29 49 49 42.84 48 46 37.68 41 04 36.72 49 16 42.69 34 41 36.71 52 03 58.67 30 45 58.01	06 33 02 06 44 47 07 49 06 08 27 33 08 37 00 08 45 01 08 53 08 09 03 27	-1.35/-1.24 -4.74/-4.63 1.42/ 1.50 2.14/ 2.68 -3.84/-3.70 -4.11/-3.99 -4.01/-3.90 -4.39/-4.25 -4.25/-4.15 -4.31/-4.17	EF D EF D EF M EF M EF M EF M	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	19-18- 1 19-18- 1 19-18- 1 19-18- 1 19-18- 1 19-18- 1 19-18- 1 19-13- 1 19-13- 1	14 13 10 64 17 14 14 17 13

Fig. III-6. INTINDEX display for raw data form of scans 14969 through scans 15028.

					DATA FOR COM		1-18-19			
	SCAN M SOURCE 14969 SD P0056-17	HA RMS/100 -02 55 000000	973 -9	992 -99	934 -96	1030 30	AMP2R3RPHI 915 -96	AMP2L3LPHI NRE	1 665665	LST 22 02 37
	14969 XD P0056-17 14969 XD P0056-17 14969 XD P0056-17	-02 54 000000 -02 54 000000 -02 53 000000	101 -79 896 7 60 -9	152 -113 1004 -85 155 -105	90 6 806 -79 41 -76	900 49 60 9	152 169 941 -94 148 160	126 72 856 47 165 65	1 666666 1 666666	22 03 07 22 03 37 22 04 07
	14969 SD P0056-17 14969 XD P0056-17 14969 SD P0056-17	-02 53 000000 -02 52 000000 -02 52 000000	886 16 31 72 816 7	1006 -77 67 -27 1030 -72	820 -81 89 -63 858 -75	920 53 80 83 974 54	960 -91 143 168 751 -94	942 53 70 82 938 51	1 665665 1 666666 1 665665	22 04 37 22 05 07 22 05 37
	14969 XD P0056-17 14969 SD P0056-17 14969 XD P0056-17	-02 51 000000 -02 51 000000 -02 50 000000	111 -63 807 -8 110 -95	72 -106 1010 -89 114 -128	130 -58 862 -95 111 -63	53 22 932 35 111 -27	145 164 954 -95 164 166	107 68 955 48 161 68	1 666666 1 665665 1 666666	22 06 07 22 06 37 22 07 07
	14969 SD P0056-17 14969 XD P0056-17 14969 SD P0056-17	-02 50 000000 -02 49 000000 -02 49 000000	899 -8 161 -68 910 -2	1022 -99 123 -76 989 -82	825 -101 20 -90 850 -88	965 28 160 -4 838 51	1093 -95 114 142 1000 -92	905 46 92 41 870 47	1 665665 1 666666 1 665665	22 07 37 22 08 07 22 08 37
	14969 XD P0056-17 14969 SD P0056-17 14970 SD 3C48		113 45 871 48 13010 -18	80 -90 997 -46 13194 -107	31 72 868 -57 11176 -114	40 180 871 87 12636 18	176 137 901 -93 11289 -84	104 73 892 49 10902 56	1 666666 1 665665 1 655665	22 09 07 22 09 37 22 13 15
	14970 XO 3C48 14970 XD 3C48 14970 XD 3C48	-03 21 000000	2696 -159 14137 -21 2952 -159	2548 150 13586 -109 2688 152	2422 -142 11636 -117 2660 -142	3143 -114 12901 15 3202 -117	2549 166 11295 -85 2525 165	2661 85 11182 55 2593 87	1 666666 1 655665 1 666666	22 13 45 22 14 15 22 14 45
	14970 SD 3C48 14970 XD 3C48 14970 SD 3C48	-03 20 000000 -03 19 000000	13401 -21 2839 -170 13887 -27	13585 -109 2606 138 13640 -115	11444 -115 2410 -153 11612 -121	12951 17 3234 -126 12826 11	11258 -85 2520 166 11393 -85	11166 54 2725 86 11357 55	1 655665 1 666666 1 655665	22 15 15 22 15 45 22 16 15
	14970 XD 3C48 14970 XD 3C48 14970 XD 3C48	-03 18 000000	2942 177 13064 -26 2875 -160	2661 129 13632 -113 2655 150	2583 -170 12278 -120 2530 -144	3261 -141 13129 12 3117 -116	2686 168 11312 -84 2589 164	2710 91 11056 55 2808 86	1 666666 1 655665 1 666666	22 16 45 22 17 15 22 17 45
, .	14970 SD 3C48 14970 XD 3C48 14970 SD 3C48 14970 XD 3C48	-03 17 000000 -03 16 100000	12709 -26 2745 -170 13069 -22	13535 -114 2694 141 13607 -109	11748 -122 2594 -155 12186 -117	12871 12 3234 -127 12977 16	10914 -85 2653 166 10705 -84	11109 54 2660 88 10987 54	1 655665 1 666666 1 655665	22 18 15 22 18 45 22 19 15
(a)	14970 XD 3C48 14971 SD DD224+67 14971 SD DD224+67 14971 XD DD224+67	-03 16 000000 -04 04 0000 -04 03 000000 -04 03 000000	2729 -169 1511 -26 1494 -16 1566 -142	2747 142 1691 -109 1793 -109 1582 168	2589 -153 1452 -121 1483 -120 1452 -142	3173 -124 1455 8 1462 14 1793 -112	2597 166 0 1523 -82 1370 178	2675 86 0 1396 58 1486 95	1 655665 1 655665 1 655665	22 19 45 22 22 30 22 23 00 22 23 30
	14971 SD D0224+67 14971 SD D0224+67 14971 XD D0224+67	-04 02 0000 -04 02 000000 -04 01 000000	1596 -10 1531 -12 1668 -135	1604 -94 1747 -100 1530 180	1494 -104 1422 -112 1400 -136	1475 27 1465 21 1732 -105	1493 -82 1447 174	0 1398 58 1494 98	1 555665 1 555665 1 666666	22 24 00 22 24 30 22 25 00
	14971 SD D0224+67 14971 SD D0224+67 14971 XD D0224+67	-04 01 0000 -04 00 000000 -04 00 000000	1671 -13 1388 -18 1585 -159	1681 -99 1736 -103 1607 151	1513 -111 1548 -114 1286 -158	1509 21 1549 17 1797 -129	1520 -83 1365 175	0 1493 59 1363 98	1 555665 1 555665 1 666666	22 25 30 22 26 00 22 26 30
	14971 SD D0224+67 14971 SD D0224+67 14971 XD D0224+67	-03 59 0000 -03 59 000000 -03 58 000000	1584 -25 1496 -13 1548 -127	1680 -113 1651 -101 1622 -177	1486 -125 1401 -114 1369 -119	1613 7 1603 17 1700 -90	1492 -83 1336 171	1324 59 1368 96	1 555665 1 555665 1 666666	22 27 00 22 27 30 22 28 00
	14971 SD D0224+67 14971 XD D0224+67 14972 SD NRAD91	-03 58 0000 -03 57 000000 -03 29 000000	1544 -14 1709 -140 5313 -12	1736 -103 1656 175 5713 -99	1408 -110 1399 -129 5239 -105	1416 18 1790 -101 5475 28	1393 176 4722 -86	1502 93 4564 52	1 555665 1 666666 1 655665	22 28 30 22 29 30 22 33 23
	14972 XD NRAO91 14972 SD NRAO91 14972 XD NRAO91	-03 29 000000 -03 28 000000 -03 28 000000	2360 -120 5183 -10 2167 -121	2284 -169 5795 -98 2310 -169	2139 -101 5065 -103 2130 -100	2697 -71 5578 29 2588 -75	2204 161 4686 -87 2151 160	2142 84 4694 51 2155 83	1 666666 1 655665 1 666666	22 33 53 22 34 23 22 34 53
	14972 SD NRAO91 14972 XD NRAO91 14972 SD NRAO91 14972 XD NRAO91	-03 27 000000 -03 27 000000 -03 26 000000 -03 26 000000	5202 -14 2155 -141 5154 -14 2115 -153	5860 -102 2241 169 5884 -102 2210 155	5214 -106 2097 -122 5189 -109 2060 -129	5643 27 2496 -94 5620 24 2504 -101	4540 -89 2185 158 4647 -87 2183 155	4714 52 2183 82 4668 52 2214 75	1 655665 1 666666 1 655665 1 666666	22 35 23 22 35 53 22 36 23 22 36 53
	14972 SD NRAD91 14972 XD NRAD91 14972 SD NRAD91	-03 25 000000 -03 25 000000 -03 24 000000	5645 -22 2239 -165 5547 -28	5915 -110 2139 145 5914 -115	4946 -116 2027 -141 5095 -118	5369 16 2507 -113 5339 13	4884 -87 2052 154 4841 -88	4668 52 2236 76 4691 52	1 655665 1 666666 1 655665	22 36 53 22 37 23 22 37 53 22 38 23
	14972 XD NRAO91 14972 SD NRAO91 14972 XD NRAO91	-03 24 000000 -03 23 000000 -03 23 000000	2143 177 5393 -26 2120 180	2096 132 5824 -114 2000 131	2036 -160 5022 -117 1939 -157	2454 -133 5236 15 2383 -129	1953 159 4783 -88 1950 157	2138 81 4687 50 2089 78	1 666676 1 655665 1 666676	22 38 53 22 39 23 22 39 53
	14973 SD 3C119	-05 48 0000	7357 -10	7582 -97	6322 -106	7003 26	0	0	1 666656	22 42 37
	SCAN M SOURCE	HA RMS/100	AMP1R2RPH1 7920 -6	AMP1L2LPHI 7861 -93	AMP1R3RPHI 6799 -101	AMP1L3LPH1 7382 32	AMPZR3RPHI O	AMPZL3LPHI NR	1 666666	LST 22 43 07
	14973 SD 3C119 14973 XD 3C119 14973 SD 3C119	-05 47 000000 -05 46 000000 -05 46 0000	7660 0 2013 -77 7734 6	7712 -87 1836 -127 7747 -82	6773 -97 1536 -67 6940 -91	7379 36 1812 -37 7498 42	6127 -85 1553 168	6241 55 1510 91	1 666666 1 666666 1 656666	22 43 37 22 44 07 22 44 37
	14973 SD 3C119 14973 SD 3C119 14973 XD 3C119	-05 45 0000 -05 45 000000 -05 44 000000	7795 -2 7773 -3 1936 -106	7820 -90 7724 -92 1842 -152	7082 -98 6947 -101 1740 -90	7593 34 7426 32 2070 -65	6386 -85 1680 169	6318 55 1810 91	1 656665 1 655665 1 666666	22 45 07 22 45 37 22 46 07
	14973 SD 3C119 14973 SD 3C119 14973 SD 3C119 14973 XD 3C119	-05 44 0000 -05 43 0000 -05 43 000000 -05 42 000000	8077 -15 8161 -20 8634 -19	7916 -102 7958 -107 7967 -107 1889 156	6934 -109 6821 -115 7219 -115 1735 -141	7456 24 7423 17 7567 18	0 0 6226 -86	0 0 6532 54	1 656665 1 655665 1 655665	22 46 37 22 47 07 22 47 37
	14973 XD 3C119 14973 SD 3C119 14973 SD 3C119 14973 XD 3C119	-05 42 000000 -05 42 0000 -05 41 000000 -05 41 000000	2118 -156 8717 -26 8723 -24 2178 -150	1889 156 8028 -113 8109 -112 1827 161	7433 -122 7491 -121 1880 -135	2150 -112 7685 11 7661 12 2071 -107	1656 165 0 6349 -84 1718 160	1787 82 0 6432 56 1909 84	1 655665 1 656665 1 656665	22 48 07 22 48 37 22 49 07 22 49 37
	14974 SD P2149-28 14974 XD P2149-28 14974 SD P2149-28	01 05 000000 01 05 000000 01 06 000000	2564 4 723 -131 2611 -5	2640 -81 563 -174 2641 -92	2337 -81 555 -104 2429 -95	2456 53 762 -73 2417 39	2160 -96 684 151 2140 -91	2142 46 673 72 2234 50	1 665665 1 665665	22 55 55 22 56 25 22 56 55
	14974 XD P2149-28 14974 SD P2149-28 14974 XD P2149-28	01 06 000000 01 07 000000 01 07 000000	669 -76 2641 13 575 -73	550 -127 2714 -76 552 -125	532 -40 2394 -79 528 -37	645 -16 2466 55 641 -4	644 156 2231 -92 590 152	635 71 2117 48 658 73	1 666666 1 666666	22 57 25 22 57 55 22 58 25
	14974 SD P2149-28 14974 XD P2149-28 14975 SD DV080	01 08 000000 01 08 000000 03 13 0000	2615 18 626 -25 1959 -23	2669 -73 579 -75 1974 -107	2311 -77 628 14 1665 -111	2488 58 648 34 1760 21	2140 -89 675 155 0	2134 49 690 80 0	1 665665 1 666666 1 655665	22 58 55 22 59 25 23 02 40
	14975 SD 0V080 14975 XD 0V080 14975 SD 0V080	03 14 000000 03 14 000000 03 15 0000	2116 -20 883 -158 1963 -23	2001 -109 818 155 1939 -110 1959 -115	1736 -107 742 -133 1727 -110	1840 23 839 -112 1809 23	1580 -92 804 159 0	1457 47 740 91 0	1 655665 1 665666 1 655665	23 03 10 23 03 40 23 04 10
(b)	14975 SD 0V080 14975 XD 0V080 14975 SD 0V080 14975 SD 0V080	03 15 000000 03 16 000000 03 16 0000 03 17 000000	1985 -27 876 169 1806 -32 1908 -35	819 120 1917 -120 1926 -122	1836 -113 729 -171 1847 -125 1696 -121	1859 18 892 -143 1762 9 1802 11	1575 -95 686 161 0 1600 -92	1444 48 743 85 0 1479 47	1 665666 1 655665 1 655665	23 04 40 23 05 10 23 05 40 23 06 10
	14975 XD 0V080 14975 XD 0V080 14975 XD 0V080	03 17 000000 03 18 0000 03 18 000000	933 170 1963 -34 1927 -33	792 115 1844 -123 1912 -122	760 -178 1811 -125 1689 -123	1008 -150 1833 11 1835 4	742 166 0 1641 -92	741 86 0 1437 48	1 655665 1 655665 1 655665	23 06 40 23 07 10 23 07 40
	14975 XD 0V080 14975 SD 0V080 14975 SD 0V080	03 19 000000 03 19 0000 03 20 000000	973 158 1970 -37 1930 -37	824 113 1839 -125 1915 -121	682 -175 1704 -128 1766 -128	846 -145 1704 4 1840 6	639 160 0 1660 -90	751 76 0 1536 48	1 665666 1 655665 1 655665	23 08 10 23 08 40 23 09 10
	14975 XD DV080 14976 SD BLLAC 14976 XD BLLAC	03 20 000000 01 10 000000 01 11 000000	920 -171 9918 -21 6928 -153	829 139 8955 -109 6112 157	769 -155 7795 -116 5742 -143	1043 -122 8333 17 6754 -114	733 163 7394 -86 5163 168	680 93 7219 55 5891 89	1 665666 1 666665 1 665666	23 09 40 23 12 27 23 12 57
	14976 SD BLLAC 14976 XD BLLAC 14976 SD BLLAC	01 12 000000	10019 -19 6755 -165 9576 -28	9178 -107 5892 145 8880 -114	7862 -116 5688 -151 7793 -123	8327 17 6760 -122 8310 11	7337 -86 5182 164 7478 -86	7137 54 5859 87 7187 54	1 666665 1 665666 1 666666	23 13 27 23 13 57 23 14 27
	14976 XD BLLAC 14976 SD BLLAC 14976 SD BLLAC 14976 XD BLLAC	01 13 000000 01 13 000000 01 14 000000 01 15 000000	6573 -178 9561 -42 9617 -43 6590 148	5780 133 9006 -129 8965 -130 5814 99	5544 -166 7828 -136 7639 -137 5582 163	6594 -137 8414 -3 8298 -4 6613 -169	5217 165 7541 -87 7404 -86 5158 166	5704 88 7261 52 7086 53 5706 87	1 666666 1 665665 1 666665	23 14 57 23 15 27 23 16 27
	14976 XD BLLAC 14976 SD BLLAC 14976 XD BLLAC 14976 SD BLLAC	01 15 000000 01 15 000000 01 16 000000 01 16 000000	9935 -46 6596 159 9504 -37	9075 -133 5694 111 8986 -124	7897 -141 5297 171 7979 -131	8376 -8 6514 -161 8347 2	5158 166 7384 -86 5224 167 7572 -87	7220 53 5860 90 7242 53	1 666665 1 665666 1 665666	23 16 57 23 17 27 23 17 57 23 18 27
	14976 XD BLLAC 14976 XD BLLAC 14976 SD BLLAC 14977 SD 3C454.3	01 17 000000	6477 156 9994 -33 14272 -48	5705 108 9038 -120 15100 -136	5323 170 8008 -128 12598 -142	6542 -161 8552 6 14082 -10	4989 165 7503 -87 12584 -88	5809 87 7164 53 12467 51	1 665666 1 665665 1 665665	23 18 27 23 18 57 23 19 27 23 22 05
	14977 XD 3C454.3 14977 SD 3C454.3 14977 SD 3C454.3	00 29 111100 00 30 100100 00 31 110100	10559 168 14852 -46 14664 -37	9810 119 15626 -133 15448 -125	8303 -171 13455 -140 13573 -130	10796 -143 14590 -8 14597 3	9216 158 13230 -87 12990 -88	10143 79 12722 53 12668 51	1 665666 1 665665 1 655665	23 22 35 23 23 05 23 24 05
	14977 XD 3C454.3 14977 XD 3C454.3 14977 XD 3C454.3	00 31 110100 00 32 111100 00 32 000000	10429 -165 15010 -33 10334 -164	9889 145 15317 -120 9893 148	6837 -151 13275 -126 9205 -145	10883 -122 14213 7 11037 -117	9799 164 12941 -88 9668 162	10184 87 12381 52 10032 83	1 665666 1 655665 1 666666	23 24 35 23 25 05 23 25 35
	14977 SD 3C454.3 14977 XD 3C454.3		14303 -30 10470 -165	15394 -117 9863 145	13654 -123 8569 -145	14722 9 10940 -117	13115 -87 9258 159	12615 52 10000 81	1 655665 1 666666	23 26 05 23 26 35

Figs. III-7a-n. INTSCRIB display of 30 second raw data records for scans 14969 through 15028.

	SCAN H SOURCE	HA RMS/100	AMP1R2RPHI	AMPILZLPHI	AMP1R3RPHI	AMP 1L3LPHI	AMP2R3RPHI	AMP2L3LPHI N	REC TPOWER	LST
(c)	14977 SO 3C654.3 14977 SO 3C654.3 14977 SO 3C655.3 14978 SO POIL4-21 14979 SO POIS6-17 14979	00 34 110100 00 35 100100 00 35 100100 00 35 100100 00 36 100100 00 36 111100 -01 42 000000 -01 41 000000 -01 41 000000 -01 39 000000 -01 39 000000 -01 37 000000 -01 36 000000 -01 37 000000 -01 38 000000 -01 38 000000 -01 39 000000 -01 30 000000 -01 31 000000000000000000000000000000000	15225 -32 10578 -172 15908 -33 10519 -168 15453 -30 9654 176 33165 17 3365 16 5503 -115 3004 11 407 -79 2878 20 461 -95 20 2878 20 461 -95 20 2878 20 461 -95 20 2878 20 461 -95 20 2878 20 2878 20 461 -95 20 2878 20 2878 20 2879 11 2879 -18 1001 -3 1330 -12 1000 -8 1022 -4 72 -106 9377 -11 134 -48 1022 -4 72 -106 9377 -17 135 -12 107 -10 117 -8 171 -8	19317 -120 9573 139 15322 -120 9389 142 15290 -117 3103 -70 3103 -70 3103 -70 3103 -70 3104 -77 3104 -77 3105 -70 3107 -77 320 -17 320	12902 -125 12902 -125 13127 -126 1327 -126 1327 -126 1327 -126 1327 -126 1327 -126 1327 -126 1327 -126 1327 -126 1327 -126 1327 -126 1327 -126 1327 -126 1327 -126 1327 -126 1327 -127 127 127 127 127 127 127 127 127 127	14344 7 10848 -123 14430 6 10255 -123 14419 10 10046 -139 2888 58 2898 57 2998 7-3 2998 7-3 2894 64 2897 65 2894 61 2817 56 458 -70 2884 31 796 39 125 -29 99 44 160 0 905 45 86 -54 785 31 133 -81 98 41 183 -81 98 17 122 277 1234 27 127 127 127 127 127 127 127 127 127 1	12862 - 87 9110 158 12940 - 87 8291 162 12949 - 87 8293 161 2893 161 2893 161 2893 161 2893 161 2893 161 2893 161 2893 161 2893 161 2893 161 2893 161 2893 161 2893 161 2893 161 2893 161 2893 161 2893 161 2893 161 2893 161 2893 169 2893 1	12492 52 9675 79 12494 53 9043 83 12554 53 386 73 2570 50 2545 51 386 73 2554 47 490 73 2554 47 490 73 2553 46 2538 45 2672 490 49 2014 82 200 64 2518 45 210 94 210 48 21	1 655665 1 666666 1 656665 1 676666 1 675667 1 676676 1 677677 1 655665 1 776777 1 665665 1 776777 1 655665 1 7766666 1 666666 1 776676 1 666666 1 776676 1 666666 1 776676 1 666666	23 27 05 23 27 35 23 28 35 23 29 35 23 29 35 23 29 35 23 29 35 23 32 35 23 32 35 23 34 35 23 34 35 23 35 55 23 34 35 23 35 55 23 34 35 23 35 35 23 37 35 23 37 35 23 38 35 23 37 35 23 37 35 23 38 35 23 37 37 38 38 38 38 38 38 38 38 38 38 38 38 38
	SCAN M SOURCE	HA RMS/100	AMP1R2RPHI	AMP1L2LPHI	AMP1R3RPHI	AMP1L3LPH1	AMPZR3RPHI	AMPZL3LPHI N		LST
(d)	14981 SO P2149-28 14982 SO CYGX-3 14983 SO P0114-21 14983 SO D0224+67 14985	22 16 000000 22 17 000000 22 17 000000 22 18 000000 22 18 000000 22 18 000000 23 18 000000 24 18 000000 25 18 000000 26 18 000000 27 18 000000 28 40 000000 28 40 000000 28 40 000000 28 40 000000 28 40 000000 28 40 000000 29 40 1111 29 45 000000	2255 - 29 660 178 2232 - 16 2230 - 10 671 - 94 671 - 94 671 - 94 671 - 94 671 - 94 671 - 94 671 - 94 671 - 94 671 - 94 672 - 12 5828 - 18 5972 - 12 5828 - 18 5972 - 12 5828 - 18 5972 - 12 5828 - 18 5973 - 29 5974 - 12 5974 - 13 5974 - 12 5974 - 13 5974 - 1	2514 -113 523 135 2403 -102 2510 -89 5140 -109 5150 -109 5150 -109 5150 -109 5170 -109	2173 -116 502 -145 2207 -108 2207 -108 2207 -108 500 -00 500 -00 500 -00 500 -00 500 -00 500 -00 500 -00 500 -00 500 -00 500 -12 4920 -119 5109 -110	2335 15 2352 14 6306 -44 6308 -44 6308 -44 6308 -44 6308 -44 6308 -44 6308 -44 6308 -44 6308 -44 6308 -44 6308 -44 6308 -44 6308 -44 6308 -44 6308 -44 6308 -44 6308 -44 6308 -44 6308 -44 6308 -45 6309 -45 6309 -45 6309 -45 6309 -15 6309 -15 6309 -15 6301 -14 6309 -15 6309 -15 6301 -14 6309 -15 6301 -14 6309 -15 6301 -14 6309 -15 6309	2100 -90 538 158 0 2090 -89 518 155 0 0 4667 -85 1665 175 0 4773 -84 1618 174 1618 174 1618 174 2621 -92 513 147 2745 -96 5509 135 2725 -94 511 149 2727 -99 604 146 2680 -91 2727 -99 1091 1692 169 1091 -85 2502 164 10806 -85 2471 165 10806 -85 2471 165 10806 -85 2471 165 10806 -86 2471 165 10806 -86 2471 165 10806 -86 2471 165 10806 -86 2471 165 10806 -86 2471 165 10806 -86 2471 165 10806 -86 2471 165 10806 -86 2471 165 10806 -87 2492 167 10806 -88 2471 165 10806 -	2004 48 608 81 0 1970 49 541 74 0 0 4516 54 1736 98 0 4494 54 1749 96 62 61 2515 49 662 61 2515 49 662 61 2515 49 662 61 2701 46 2515 49 262 68 65 2600 41 2701 46 2811 88 10014 57 10012 80 10014 57 10492 56 2811 88 10414 57 10414	1 066666 1 6776666 1 606666 1 6076676 1 5076676 1 5076676 1 5076676	00 07 20 00 07 20 00 07 20 00 07 20 00 07 20 00 00 20 00 20 00 00 20 00 00 00 00

	SCAN M SOURCE	HA RMS/100	AMPIR2RPHI	AMP1L2LPHI	AMP1R3RPHI	AMP1L3LPHI	AMP2R3RPHI	AMP2L3LPHI NE	EC TPOWER	LST
(e)	14986 SD 3C147 14987 SD 3C119 14988 SD 3C119 14988 SD CTA21 14988	-04 45 1001 -04 45 1001 -04 43 1111 -04 43 11011 -04 43 11011 -04 43 11011 -04 44 100101 -05 44 1101 -07 44 1101 -08 41 1010 -08 42 1111 -09 44 1101 -09 45 100000 -09 27 000000 -09 27 000000 -09 28 000000 -09 29 000000 -09 29 000000 -09 29 000000 -09 29 000000 -09 29 000000 -09 29 000000 -09 29 000000 -09 29 000000 -09 000000 -09 000000 -09 000000 -09 000000 -09 000000 -09 000000 -09 000000 -09 000000 -09 000000 -09 000000 -09 000000 -09 0000000 -09 000000 -09 00000000 -09 0000000000	20077 -8 4922 -132 20283 -20 20244 -21 20405 -27 4931 -147 20405 -22 20407 -27 20407 -27 20407 -27 20407 -27 20407 -27 20407 -31 2014 -19 2174 -129 2175 -42 2199 150 7977 -35 2164 155 6241 -45 2163 150 621 -42 2250 144 8408 -44 2250 144 8408 -44 2250 144 8408 -44 2250 144 8408 -44 2250 144 8408 -44 2250 144 8408 -44 2250 144 8408 -44 2250 144 8408 -45 2164 161 851 138 1866 2 -47 186 161 187 188 189 187 189	18917 - 96 4310 - 179 18828 - 108 18725 - 110 4174 - 165 18997 - 108 18980 - 112 18997 - 108 18980 - 112 18991 - 108 18912 - 129 2000 - 102 18122 - 129 2000 - 102 18122 - 129 2000 - 102 18122 - 129 2000 - 102 1825 - 120 1899 - 188 2644 - 127 1899 - 188 2644 - 130 2003 - 93 2654 - 124 1996 - 104 2625 - 120 1826 - 127 1889 - 128 1894 - 128 1895 - 128 1897 - 128 1898 - 129 1	1758 + 106 4346 -123 17675 -118 18148 -121 4398 -138 18387 -117 17568 -123 40191 -127 40	18770 27 5222 -94 18913 15 18966 12 18966 15 18968 15 18933 15 18548 15 18933 15 18548 16 1933 15 18548 16 1933 15 18548 16 1933 15 18548 16 1933 15 18548 16 1933 16 17691 -5 2463 -16 17691 -1 2598 -169 1776 -2 2435 -16 1776 -2 2440 -175 176 -2 2440 -175 176 -2 245 -16 173 1-6 176 10 173 1-6 176 10 179 1-3 1663 -169 179 1-3 170 1-6 1711 1-7 17116 -4 1802 173 1705 -12 1711 1-7 17116 -4 1802 173 1705 -12 1707 170 170 170 170 170 170 170 170 170	3889 172 15633 -83 4039 173 15596 -84 1894 169 6611 -84 1940 167 6767 -85 1911 165 6785 -86 1911 165 6785 -86 1961 179 6845 -86 1961 179 6858 -86 1891 167 6675 -86 1891 167 6675 -86 1891 167 6675 -86 1891 167 6675 -86 1891 167 6658 -86 1891 167 6658 -86 1891 167 6658 -86 1891 167 6658 -86 1891 167 6658 -86 1891 167 6658 -86 1891 167 6658 -86 1891 167 6658 -86 1891 167 1995 168 1	4393 94 15428 57 4205 95 15319 56 15319 57 15419	1 65566 1 655666 1 555665 1 665666 1 655665 1 665666 1 655665 1 665666 1 655665 1 655665 1 655665 1 655666 1 555665 1 655666 1 555665 1 655666 1 555665 1 655666 1 555665 1 655666 1 655666	00 55 01 00 05 01 00
(f)	SCAN M SOURCE  14990 SD 3C454-3  14990 SD 3C458-3  14990 SD 3C458-3  14990 SD 3C458-3  14991 SD 3C418	HA RHS/100  22 41 1001  22 42 000001  22 43 1000  22 43 1000  22 43 1000  22 44 000000  22 45 000001  22 45 000001  22 45 00000  22 46 0000  22 47 000100  25 05 0000  25 05 0000  25 05 0000  25 07 0000  25 08 0000  25 08 0000  25 08 0000  25 10 0000  25 10 0000  25 10 0000  25 10 0000  25 10 0000  25 10 0000  25 10 0000  25 10 0000  25 10 0000  25 10 0000  25 10 0000  25 10 0000  25 10 0000	AMPIR ZRPHI 14727 -34 14844 -41 14844 -41 14984 -40 11995 152 12798 -40 11095 152 13767 -32 13015 -22 13015 -22 13015 -21 13122 -15 13767 -32 13016 -17 10719 -135 6070 -14 5591 -22 6013 -33 5765 -28 5765 -28 5765 -28 5765 -28 5765 -28 5765 -28 5765 -28 5765 -28 5765 -28 5765 -18 5776 -18 57	AMP IL 2L PHI  10179 -122 10219 -128 10219 -128 11433 -128 11433 -128 11433 -128 11434 -110 116057 -102 11314 -176 6020 -100 5995 -108 6020 -100 5995 -108 6020 -100 5995 -108 6020 -100 5995 -108 6020 -100 5995 -108 6020 -100 5995 -118 6021 -120 5995 -118 6021 -120 5995 -118 6021 -120 5995 -118 6021 -120 5995 -118 6050 -106 6060 -106 6060 -105	AMPIRSRPHI  13384 - 130 13783 - 136 13783 - 136 13783 - 136 13783 - 138 14262 - 138 10662 - 138 10662 - 138 10662 - 138 10692 - 113 1069 - 116 10386 - 131 5592 - 113 5609 - 118 5792 - 128 5792 - 129	AHP IL 3L PHI 15179 2 15253 -3 15023 -7 15023 -7 15027 -169 15139 4 15111 12 15139 4 15111 12 15349 17 13229 -103 5897 22 5748 14 5858 7 5858 7 5858 6 5878 16 5700 17 3140 -134 3130 -126	AMPZR3RPHI  12687 -85 12635 -84 10350 168 012542 -83 10406 173 12488 -02 10384 174 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	AMP2L3LPHI NR 12793 55 12765 55 10840 90 12836 56 11038 93 12814 57 10983 96	1 655665 1 655665	LST  01 34 08 01 34 36 01 35 38 01 36 08 01 36 08 01 37 38 01 37 38 01 38 06 01 38 06 01 39 06 01 39 38 01 39 38 01 43 33 01 44 03 01 45 03 01 46 33 01 48 03 01 48 03
	14991 XD 3C418 14992 XD 9C106+01 14992 XD P0106+01 14993 XD NRA0140 14994 XD NRA0140 14994 XD NRA0140 14995 XD NRA0140 14994 XD NRA0140	05 11 000000 05 11 00000 06 47 000000 06 47 000000 07 000000 00 48 000000 00 49 000000 00 50 000000 00 51 000000 00 51 000000 00 51 000000 00 51 000000 00 51 000000 00 51 000000 00 51 000000 00 51 000000 00 51 000000 00 51 000000 00 51 000000 00 52 000000 00 52 000000 01 29 000000 01 29 000000 01 29 000000 01 25 000000 01 25 000000 01 25 000000 01 25 000000 01 25 000000 01 25 000000 01 25 000000 01 25 000000 01 25 000000 01 25 000000 01 25 000000 01 25 000000 01 25 000000 01 25 000000 01 25 000000 01 25 000000	2934 -177 6010 -35 3017 -203 3017 -203 3017 -203 3012 -177 4092 -26 3579 -166 4127 -27 3818 -144 4053 -22 3137 -167 3185 -132 3185 -132 3185 -132 3185 -132 3185 -132 3185 -144 1805 -144 1905 -145 1816 -146 1816 -146 1817 -147 1817 -147 1818 -144 1818	2708 135 6090 -123 3755 -105 3288 14-156 3414 -156 3905 -111 3274 144 3901 -113 3477 169 3260 145 3956 -109 3260 145 3966 -116 3476 -116 3477 169 3260 145 3767 -116 3767 -116 3	2634 -170 5479 -132 3352 -114 3186 -121 3350 -133 3511 -120 3057 -149 3057 -149 3057 -149 3068 -123 3078 -153 3078 -153	3009 -140 5603 2 3405 18 3902 -95 3803 -13 3910 -121 3885 -101 3885 -101 3885 -101 3885 -101 3885 -101 3887 -12 3981 -1 3981	2651 175 3395 -87 3003 164 3227 -68 3227 -68 3229 -68 3068 164 3252 -88 3268 -88 2892 164 3366 -88 2892 164 3262 -88 3464 162 3262 -88 3464 162 3262 -88 3464 162 3262 -88 3466 169 3411 -88 1603 169 3417 -86 1571 167 3511 -65 3604 -69 3612 -69 3704 -69 3704 -88	2681 97 3120 54 3372 85 3372 85 3372 85 3372 85 3372 85 3372 87 33128 52 3392 85 33487 84 3525 87 3128 52 3392 85 3270 753 3887 84 3402 87 3385 55 1700 91 3286 56 1980 55 1730 89 2082 87 2082 87 2082 87 2082 87 2082 87 2083 88	1 065666 1 055665 1 055665	01 49 03 01 149 03 01 149 03 01 149 03 01 149 03 01 149 05 01 159 05 05 05 05 05 05 05 05 05 05 05 05 05

	SCAN M SOURCE	HA RMS/100	AMPIR2RPHI	AMPILZLPHI	AMP1R3RPHI	AMP1L3LPHI	AMP2R3RPHI	AMP2L3LPHI	NREC TPOWER	LST
(g)	14994 SD PO735+17 14994 SD PO735+17 14994 XD PO735+17 14995 XD PO735+17 14995 SD SC120 14995 SD SC120 14995 XD SC446 14996 XD SC454-3 14997 XD SC455-3 14997 XD SC456-3 14999 XD SC48 14998 XD SC48 14999 XD OC224+67 14999 XD DO224+67 14999 XD DO224+67 14999 XD DO224+67 14999 XD DO224+67	-05 18 0000 -05 18 0000 -05 17 000000 -05 17 000000 -05 16 0000 -02 08 00000 -02 08 00000 -02 07 111100 -02 06 00000 -02 05 000000 -02 05 111100 -02 06 111100 -03 07 111100 -04 12 00000 -04 12 00000 -04 12 00000 -04 13 00000 -05 14 00000 -06 15 00000 -07 07 11100 -08 07 11100 -09 07 07 07 07 07 07 07 07 07 07 07 07 07	2701 2 2807 -4 1514 -55 2773 19 8139 -27 10226 19 10226 19 10227 1	2630 -85 2640 -90 1241 -105 2622 -69 9773 -116 10711 -12 10721 -12 10731 -12 10731 -13 10740 -13	2180 -91 2390 -95 1243 -39 2534 -76 8802 -115 9616 -166 8768 -122 9877 -157 8573 -119 9571 -163 8300 -125 9716 -156 9636 -166 6768 -122 9877 -157 6486 -122 9877 -157 6486 -122 9877 -157 6486 -122 9871 -158 9716 -159 9716 -159 9716 -159 9716 -159 9716 -159 9716 -159 9716 -159 9716 -159 9716 -159 9716 -159 9716 -159 9716 -159 13768 -108 13915 -110 13939 -161 13939 -161 13939 -161 13939 -161 13939 -161 13939 -161 13737 -125 13766 -120 1475 -116 1475 -116 1475 -117 1475 -115 1476 -115	2295 41 2460 38 1384 -8 2384 54 9267 147 12062 -127 9087 14 12025 -139 9148 10 12143 -129 9087 14 12225 -139 9148 10 12143 -129 6868 59 6865 31 3246 -75 3233 -75 6772 42 6868 59 6865 31 3246 -75 3233 -75 6772 42 6877 42 687 43 687 4	2063 - 87 1135 162 7 997 - 86 10988 153 10998 153 10999 156 8684 - 88 10692 159 8690 - 87 10778 157 10852 158 10862 158 10862 159 10862 158 10862 158 10862 158 10862 158 10862 168 10862 173 10862	2080 50 1254 85 0 849 571 181528 81 18158 751 181528 81 18164 78 8383 81 1864 78 83247 51 11570 78 81247 95 1041 92 1041 92 1051 93 10778 93 10779 95 10779	1 666665 1 655665	02 18 15 02 19 15 02 18 16 02 19 15 02 19 45 02 29 45 02 29 45 02 22 28 88 02 29 22 28 88 02 29 29 88 02 29 29 88 02 29 29 88 02 29 29 88 02 29 29 88 02 29 29 88 02 29 29 88 02 29 29 29 88 02 29 29 29 88 02 29 29 29 29 29 29 29 29 29 29 29 29 29
	SCAN M SOURCE	HA RMS/100	AMP1R2RPHI	AMPILZLPHI	AMP1R3RPHI	AMP1L3LPHI	AMPZR3RPHI	AMP2L3LPHI	NREC TPOWER	LST
(h)	1499 XD 00224+67 14999 XD 00224+67 15000 XD 3C147 15000 XD 07742+10 15001 XD 07742+1	00 38 000000 00 38 000000 00 39 000000 00 39 000000 00 39 000000 00 39 000000 00 40 00000 00 40 00000 00 41 000000 00 42 000000 00 42 000000 00 42 000000 00 42 000000 00 42 000000 00 42 000000 00 42 000000 00 42 000000 00 42 000000 00 42 000000 00 42 000000 00 40 000000 00 40 000000 00 40 000000 00 40 000000 00 40 000000 00 40 000000 00 40 000000 00 40 000000 00 40 000000 00 40 0000000 00 40 0000000 00 40 0000000 00 40 0000000 00 40 0000000 00 40 00000000	1863 -169 1869 -27 1869 -27 1870 -23 1895 -167	1714 147 1774 -114 1774 -114 1774 -114 1774 -114 1774 -114 1774 -114 1703 -109 1642 -119 1703 -116 1703 -116 1703 -116 1703 -116 1703 -117 17168 -132 1719 -109 1719 -117 1719 -171 1719 -	1548 -158 1421 -128 1421 -128 1349 -162 1549 -139 1449 -158 1411 -120 1500 -168 1411 -120 1500 -168 1411 -120 1500 -168 1411 -120 1500 -168 1411 -120 16568 -129 1686 -137 16988 -128 16568 -129 16568 -129 16568 -129 16568 -129 16568 -129 1760 -161	1939 -129 1578 -129 1578 -129 1578 -131 1572 -131 1572 -131 1572 -131 1572 -13 1486 -12 1578 -17 17547 -8 18157 -14 18157 -14 18157 -14 18157 -15 17961 -14 18157 -15 18151 -15 17961 -14 17829 -6 1518 -15 17961 -15 18193 -15 18	1318 173 1446 -94 1254 171 165 -94 1252 176 0 1316 174 15511 -93 13871 171 15571 -93 13705 171 15571 -93 13705 171 15571 -93 13705 171 15571 -93 13705 171 15571 -93 13705 171 15571 -93 14052 173 15699 -85 1370 -91 15922 -137 15928 -167 15928 -167 15928 -167 15928 -167 15928 165 15921 -158 1692 -159 1693	1495 95 1322 03 1415 95 1416 95 1320 16 1466 95 1512 93 15122 97 14286 93 17254 36 14384 97 15060 56 14560 56 14560 76 1457 79 15277 55 14287 97 15277 55 15418 59 15418 59 15418 59 15418 59 15418 79 15	1 665666 1 655665 1 655666 1 655665 1 665666 1 655665 1 655665 1 655665 1 655665 1 655665	03 04 55 03 05 55 03 05 55 03 06 55 03 07 55 03 07 55 03 07 25 03 08 25 03 07 13 03 13 03 13 03 13 03 14 03 03 14 03 03 15 03 03 17 03 03 16 03 03 17 03 03 16 03 03 17 03 03 16 03 03 17 03 03 16 03 03 17 03 03 18 03 03 17 03 03 24 42 03 25 12 03 26 12 03 26 12 03 27 12 03 28 12 03 29 12 03 29 12 03 29 12 03 29 13 03 13 03 03 14 03 03

	SCAN M SOURCE	HA RMS/100	AMP1R2RPHI	AMPILZLPHI	AMP1R3RPHI	AMP1L3LPHI	AMP2R3RPHI	AMPZL3LPHI N	REC TPOWER L	.sT
(i)	15003 SD P0056-17 15003 SD P0056-17 15003 SD P0056-17 15003 SD P0056-17 15004 SD 3C454-3 15005 SD NRA091 15006 SD 3C119 15007 SD P0106+01	22 50 000000 02 51 000000 02 51 000000 02 51 000000 04 59 100000 04 59 10000 05 01 00000 05 01 1000 05 01 1111 05 02 1100 05 03 100000 05 03 100000 05 03 100000 05 03 100000 06 05 05 1001 07 07 07 07 07 07 07 07 07 07 07 07 07 0	942 4 82 - 104 911 3 910 - 1 14840 - 10 15732 - 10 15732 - 10 15732 - 10 15732 - 10 15632 - 1 15632 - 1 15634 - 2 15657 4 14944 - 1 10913 - 114 9932 - 11 15452 - 6 5800 - 40 2522 148 5763 - 45 2553 164 2553 164 2553 164 2554 17 2564 7 - 2 2574 177 5587 - 2 2648 17 2774 177 2887 - 2 2886 - 3 2013 177 2081 156 2082 177 2081 157 2081 157 2081 177 2081 177 208	1051 - 87 134 - 117 984 - 77 980 - 88 15038 - 98 15180 - 94 15180	870 -93 106 -49 930 -91 13761 -1108 13249 -108 13249 -108 13277 -110 13293 -122 13425 -108 13819 -96 13757 -110 13293 -122 13425 -108 13526 -99 9488 -110 13527 -105 13526 -99 13550 -120 13527 -105 1	950 41 191 -47 877 42 890 38 14328 25 14048 25 14048 25 14059 24 14156 12 14190 26 14346 38 16181 34 10829 -8 13781 29 13781 29 13781 29 13781 29 13781 29 13781 29 13781 29 13781 29 13781 29 13781 29 13781 29 13781 29 13781 29 13781 29 13781 29 13781 29 1388 -170 219 -16 2582 -143 5470 -1 2085 -158 2743 -147 5400 6 2743 -147 5400 6 2743 -147 5400 6 2743 -147 5400 6 2743 -147 5401 6 2743 -147 5401 6 2743 -158 2719 -138 2719	950 - 900 160 176 970 - 90 970	890 52 104 73 104 173 104 105 105 105 105 105 105 105 105 105 105	1 666666 03 1 656656 03 1 656656 03 1 656656 03 1 666666 03 1 666666 03 1 666666 03 1 666666 03 1 666666 03 1 666666 03 1 666666 03 1 666666 03 1 666666 03 1 666666 03 1 666666 03 1 655665 04 1 655665 04 1 656666 04	02 57 03 27 03 57 04 27 04 57 05 27 05 57 06 27 06 57 07 27
	SCAN M SOURCE	HA RMS/100	AMP1R2RPHI	AMP1L2LPHI	AMP1R3RPHI	AMP1L3LPHI	AMPZR3RPHI	AMP2L3LPHI )	IREC TPOWER L	.st
(j)	15007 SD P010+01 15008 XD P0438-43 15009 XD P0438-43 15009 XD P0438-43 15009 XD P0438-43 15009 XD P0614-34 15009 XD R0614-34 15009 XD R061	03 22 000000 -00 05 100000 -00 05 100000 -00 05 100000 -00 05 100000 -00 07 000000 -00 07 000000 -00 07 000000 -00 07 000000 -00 07 000000 -00 07 000000 -00 07 000000 -00 07 000000 -01 33 000000 -01 33 000000 -01 32 0000000 -01 32 0000000 -01 32 0000000 -01 32 0000000 -01 32 00000000 -01 32 0000000000000000000000000000000000	3864 -30 5783 32 716 54 7357 95 1624 160 7357 95 1624 160 1626 -26 6882 110 1796 -16 1796 -16 1796 -16 1796 -16 1796 -16 1796 -16 1796 -16 1796 -16 1796 -16 1796 -16 1796 -16 1796 -16 1796 -16 1796 -16 1796 -16 1796 -16 1797 -1797 12 1798 37 1774 -25 490 12 1759 10 1778 37 1774 -15 1788 37 1788 37 1788 37 1799 11 1798 37 1799 11 179	3837 -117 -56 -700 0 6750 8 1 6460 -3 3 1 6545 102 6640 12 1592 1592 1592 1592 1592 1592 1592 1	3380 -127 6054 -57 858 75 6324 2 1330 -304 6013 10 6013 17 601	3521 6 6296 76 1057 103 6577 136 165	3149 - 86 5855 - 94 1692 169 5921 - 89 1676 162 5921 - 89 1216 5921 - 89 1328 162 5740 - 90 1392 168 5692 - 92 1512 160 5740 - 90 1392 145 2118 - 83 218 - 8	3096 54 5587 46 1671 87 5256 15 1551 69 1395 81 1393 87 1484 78 1472 496 1488 66 1570 89 1484 96 1488 66 1570 89 1484 17 1488 66 1570 89 158 17 12011 43 158 71 2011 43 158 71 2011 43 158 71 2011 43 158 71 2011 43 158 71 2011 43 158 71 2011 43 158 71 2010 87 2023 43 481 69 2101 43 258 87 269 87 269 87 269 87 269 87 27 2023 43 481 69 2101 43 210 87 210	1 666776 04 1 666776 04 1 777777 04 1 666776 04 1 787787 04 1 787787 04 1 787787 04 1 787787 04 1 787787 04 1 787787 04 1 787787 04 1 787787 04 1 787787 04 1 787787 04 1 787787 04 1 666666 04 1 776777 04 1 666666 04 1 776777 04 1 666666 04 1 776777 04 1 666666 04 1 776777 04 1 666666 04 1 776777 04 1 666666 04 1 776777 04 1 666666 04 1 776777 04 1 666666 04 1 776777 04 1 666666 04 1 776776 04 1 666666 04 1 776777 04 1 666666 04 1 776777 04 1 666666 04 1 776776 04 1 666666 04 1 776777 04 1 666666 04 1 776777 04 1 666666 04 1 776776 04 1 666666 04 1 776776 04 1 666666 04 1 776776 04 1 666665 04 1 776776 04 1 666665 04 1 666665 04 1 7766776 04 1 666665 04 1 666665 04 1 7766776 04 1 666666 05 1 676666 05 1 676666 05 1 675665 05 1 675665 05 1 675665 05 1 675665 05 1 675665 05 1 675665 05 1 675665 05 1 675665 05 1 675665 05 1 675665 05 1 655665 05 1 655665 05 1 555665 05 1 555665 05 1 555665 05 1 555665 05	47 25 47 55 48 25 49 25 53 56 54 26 55 56 55 56 56 56 57 26

	SCAN M SOURCE	HA RMS/100	AMP1R2RPHI	AMP1L2LPHI	AMP1R3RPHI	AMP1L3LPHI	AMP2R3RPHI	AMP2L3LPHI NREC TPOWER LST	
(k)	15012 SD 00224+67 15013 SD 30244-67 15013 SD 30244-7 15013 SD 30244-7 15013 SD 30244-7 15013 SD 30244-7 15013 SD 3024-7 15014 SD 3024-7 15015 SD P1116+12	02 47 000000 02 47 000000 02 48 0000 02 48 0000 02 49 00000 02 49 00000 02 50 000000 02 50 000000 02 51 00000 02 52 000000 02 52 000000 02 52 000000 03 52 000000 00 15 111010 00 16 000000 00 17 11111 00 16 000000 00 17 11100 00 16 11110 00 17 000000 00 17 11100 00 18 000000 00 19 1000000 00 19 1000000 00 19 1000000 00 19 1000000 00 19 1000000 00 19 1000000 00 19 1000000 00 19 10000000 00 19 10000000 00 19 10000000 00 19 10000000 00 19 10000000000	1499 -17 1499 -17 1498 -14 1498 -14 1498 -16 1498 -25 1736 -16 1498 -25 1736 -16 1556 -28 1668 -25 1736 -16 18407 -21 4501 17 19381 -24 4679 -17 48590 -37 46597 16 18590 -37 46597 16 18590 -37 46597 17 19187 -20 18590 -37 4659 16 18590 -37 4659 1	1695 -107 1436-164 1436-165 1634 -105 1571 -109 1674 -114 1577 141 1593 -112 11593 -122 11593 -122	1462 -116 1400 -1416 1401 -1416 1378 -114 1474 -121 1536 -120 1539 -161 1486 -125 1444 -121 1466 -133 1466 -123 1466 -123 1373 -165 16412 -134 15360 -123 1373 -165 16412 -134 1570 -123 16412 -134 173 -161 16718 -134 173 -161 16718 -134 173 -161 16718 -134 173 -161 16718 -134 173 -161 16718 -134 16718	1550 16 1871 -114 1871 -114 1871 -114 1508 19 1602 12 1524 10 1937 -134 1510 10 1504 12 1591 15 11844 -12 17301 13 17499 -13 17498 -2 4524 -199 4549 -137 17405 16 1600 4 4247 177 17094 -15 4373 -16 6671 110 -143 16671 11198 -153 6674 11 11198 -153 6674 11 11198 -153 6674 11 11295 -123 6671 11 11295 -123 6671 12 11315 -13 11315 -13 113	1486 -85 1336 174 0 0 1497 -84 1395 175 0 0 1515 -85 1343 176 15190 -84 3659 173 15029 -83 3571 172 15183 175 15184 -84 1395 171 14712 -85 3264 173 15028 -85 3264 173 15028 -85 3264 173 15028 -85 3264 173 15028 -85 3264 173 15028 -85 3264 173 15028 -85 3427 176 5695 -86 8573 171 6712 -85 5994 -86 8573 171 6059 -87 9264 170 9265 165 5994 -86 825 165 5994 -86 838 172 0 1991 -86 838 172 0 1991 -88 831 175 0 1991 -88 833 175 0 1991 -88 833 175 0 1991 -88 833 175 0 1991 -88 833 175 0 1991 -88	1450 55 1 655665 05 13 38 8 1358 96 1 666660 05 14 28 0 1 655665 05 14 28 0 1 655665 05 15 28 0 1 655665 05 15 28 0 1 655665 05 16 28 0 1 655665 05 16 28 0 1 655665 05 16 28 0 1 655665 05 16 28 0 1 655665 05 16 28 0 1 655665 05 16 28 0 1 655665 05 16 28 0 1 655665 05 16 28 0 1 655665 05 16 28 0 1 655665 05 16 28 0 1 655665 05 16 28 0 1 655665 05 16 28 0 1 655665 05 12 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	
	SCAN M SOURCE	HA RHS/100	AMP1R2RPHI	AMP1L2LPHI	AMP1R3RPHI	AMP 1L 3L PHI	AMPZR3RPHI	AMP2L3LPHI NREC TPCWER LST	
(L)	15016 SD P1055+01 15017 SD P0059-14 15018 SD P00614-34	-05 02 0000 -05 02 00000 -05 02 000000 -05 00 000000 -05 00 000000 -04 59 0000 -05 00 000000 -05 00 000000 -05 00 000000 -06 57 000000 -07 57 000000 -07 57 000000 -07 58 0000000 -07 58 0000000 -07 58 0000000000000000000000000000000000	4285 57 43712 29 4603 24 4603 24 4708 39 4400 39 4400 53 4395 55 4405 59 2472 98 4400 63 31615 -3 1368 11 3484 13 3484 13 3598 -11 1380 -8 1303 -113 3598 -11 1417 -131 3590 11 1380 -8 33595 -12 1380 -10 1224 -95 2713 17 635 -83 635 -83 647 -99 2844 10 667 -99 2846 10 2846 6 799 -99 2847 10 687 -99 2848 10 687 -99 2849 10 687 -99 2849 10 687 -99 289 10 687 -99 289 10 687 -99 289 10 687 -99 289 10 687 -99 289 10 687 -99 289 10 687 -99 289 10 687 -99 289 10 687 -99 289 10 89 10	3898 -30 3917 -34 1403 -33 3919 -63 3919 -65 39711 -34 3887 -28 20095 -48 3910 -24 3910 -24 3910 -19 11007 -102 1389 -103 1399	3618 -37 3736 -39 1229 173 3739 -69 1933 78 3788 -39 3822 -34 2113 119 3762 -33 3764 -30 3764 -30 3764 -30 3764 -30 3764 -30 3764 -30 3764 -30 3764 -30 3764 -30 3764 -30 3764 -30 3776 -60 3776	3824 95 3846 132 1399 153 390 94 3999 100 2374 146 3861 102 3866 103 3863 94 11953 -41 11953 -41 11953 -41 11953 -41 11953 -40 2374 -455 2374 -146 2376 -174 2455 400	3355 -87 2012 153 3371 -88 2044 155 147 2131 -93 601 159 159 160 159 159 159 159 159 159 159 159 159 159	0   666666   05   54   33   3294   54   1   666666   05   50   33   393   51   1   666666   05   50   33   393   51   1   666666   05   50   33   393   51   1   666666   05   50   33   2026   52   1   666666   05   50   33   2026   52   1   666666   05   50   33   2026   52   1   666666   05   50   33   2026   52   1   666666   05   50   33   2026   53   1   666666   05   50   33   2026   53   1   666666   05   50   33   2026   53   1   666666   05   50   33   2026   53   1   666666   05   50   203   2026	

	SCAN M SOURCE	HA RMS/100	AMP1R2RPHI	AMPIL2LPHI	AMPIRSRPHI	AMP IL3LPHI	AMP2R3RPHI	AMP2L3LPHI N	REC TPOWER	LST
(m)	15020 XD P1114-12 15020 XD P1146-12 15020 XD P1146-12 15020 XD P1146-12 15021 XD 3C138 15022 XD 3C147	-04 41 000000 -04 41 000000 -04 41 000000 -04 41 000000 -04 41 0000000 -04 41 0000000 -04 47 0000000 -04 39 000000 -04 38 000000 -01 25 1000000 -01 25 0000000 -01 26 000000 -01 27 000000 -01 27 000000 -01 28 000000 -01 28 000000 -01 29 000000 -01 29 000000 -01 29 000000 -01 29 000000 -01 29 000000 -01 20 000000 -02 10 1000000 -02 11 110 -02 10 000000 -02 11 110 -02 12 000000 -02 11 110 -02 12 000000 -02 11 110 -02 12 000000 -02 11 110 -02 12 000000 -02 11 110 -02 12 1111 -02 14 1111 -02 15 000000 -02 17 1111 -02 16 11111 -02 17 000000 -02 17 1111 -02 18 11111 -02 18 000000 -02 17 1111 -02 18 11111 -02 19 000000 -02 10 1111 -02 12 1111 -02 12 100000 -02 12 1111 -02 12 1111 -02 12 100000 -02 12 1111 -02 12 100000 -02 12 1111 -02 12 100000 -02 12 1111 -02 12 1111 -02 12 100000 -02 12 11111 -02 12 100000 -02 12 11111 -02 12 1111 -02 12 1111 -02 12 1111 -02 12 11101 -02 12 1111 -02 12 1	1270 -80 2618 -80 2618 -90 2618 -91 2728 -93 2801 10 2813 -9 2801 10 2813 -91 186 -11 18593 -41 2422 122 8923 -92 8923 -92 2409 146 9058 -37 2271 157 8923 -45 2407 140 19130 -35 20075 -28 19130 -35 20075 -28 19144 -38 4507 154 1948 -36 19499 -34 1948 -36 19499 -34 1948 -36 19499 -34 1948 -36 19499 -31 18625 -36 19491 -38 18728 -47 18825 -36 19491 -38 18728 -47 19886 -17 19897 -28	1034 -128 2493 -811 1002 -152 1002 -152 2555 -82 1002 -152 2553 -178 2454 -96 1020 -152 2564 -128 211 73 2211 73 2212 73 2182 -132 2182 -132 218374 -122 18374 -122 18374 -123 1849 -123 1849 -123 18601 -125 4218 105 18621 -123 18621 -123 18631 -118 18632 -124 18621 -123 18621 -132 18621 -132 1874 -115 18652 -144 1874 -115 18674 -116 18674 -116 18674 -116 1874 -117 1874 -117	1142 -60 2380 -89 2380 -89 329 329 329 329 329 329 329 329 329 32	1207 -26 2504 24 244 244 2647 -47 1209 -19 2477 48 2371 34 1305 -63 7541 -1 2514 168 7930 -13 2779 170 27797 170 27797 170 27385 -163 27383 -5 2483 -172 17352 1 17409 0 4796 -17 17250 0 4796 -17 17250 1 17752 1 17761 5 1761 5 1761 5 1761 5 1761 5 1761 6	950 158 2129 -65 1023 158 21012 -61 1023 158 21012 -61 2071 -88 2190 -90 92e 162 6793 -83 2011 164 6793 -83 2011 164 6793 -83 2011 164 6793 -83 2041 165 6879 -85 2044 167 15126 -87 3507 169 15240 -83 3507 169 15240 -83 3507 169 15240 -83 3507 169 15240 -83 3507 169 15186 -84 3681 173 0 15186 -84 3681 173 0 15186 -83 3681 173 0 15186 -84 3691 171 15731 -84 3691 171 15731 -84 3691 173 15783 -84 3691 171 15783 -84 3691 171 15783 -84 3691 171	1006 84 2033 55 1014 80 2104 81 2104 82 2104 83 2103 51 1031 87 6249 54 2211 88 6471 55 2310 89 6421 55 221 84 6593 54 2211 86 6683 55 2261 84 2211 86 6683 67 14974 55 3664 87 15144 55 3684 87 14974 55 3684 87 14974 55 3687 80 15142 55 3688 87 14974 55 3689 96 3911 90 15087 55 4082 88 0 15087 55 4082 88 0 15087 55 4084 87 15144 55 33849 96 3911 90 15087 55 4082 88 0 15087 55 4082 88 0 14991 56 3911 90 15087 55 4084 87 15146 55 3991 96 151558 56 3911 90 151558 56 3911 90 151558 56 3911 90 151558 56 3911 90 151558 56 3911 90 151558 56 3911 90 151558 56 3911 90 151558 56 3911 90 151558 56 3911 90 151558 56 3911 90 151558 56 3911 90 151558 56 3911 90 151558 56 3911 90 151558 56 3911 90 151558 56 3911 90 151558 56 3911 90 151558 56	1 665666 1 655665 1 655665 1 655665 1 655665 1 655665 1 666666 1 665665 1 666666 1 665665 1 776666 1 665665 1 776666 1 655665 1 776666 1 555665 1 55665 1 55665	06 35 50 06 36 50 06 36 50 06 37 50 06 37 50 06 38 50 06 39 50 06 49 36 06 40 36 06 40 36 06 40 36 06 41 36 06 41 36 06 41 36 07 49 25 07 49 25 07 49 25 07 50 55 07 50 55 08 00
(n)	SCAN M SOURCE  15022 SD 3C147 15022 XD 3C147 15022 XD 3C147 15022 SD 3C147 15022 XD 3C147 15022 SD 3C147 15022 XD 3C147 15022	MA RMS/100 02 30 100100 02 30 000000 02 31 1011 02 32 000000 02 32 1111 02 33 01110 02 32 000000 02 32 1111 02 33 01110 02 33 01110 02 34 1111 02 35 11110 02 36 11111 02 36 11111 02 36 11111 02 36 11111 02 37 1111 02 38 101100 02 38 1111 02 39 22110 02 38 101100 04 10 10100 04 10 10100 04 10 10100 04 10 10100 04 10 100000 04 10 000000 04 11 000000 04 14 000100 04 15 000000 04 16 000000 04 16 000000 04 17 000000 04 18 000000 04 19 000000 04 10 000000 04 10 000000 04 10 000000 04 11 000000 04 12 000000 04 14 000000 04 14 000000 04 15 000000 04 14 000000 04 14 000000 04 14 000000 04 15 000000 04 16 000000 04 17 000000 06 18 000000 06 19 000000 06 10 000000 07 10 000000 08 10 000000 09 10 000000 09 10 000000 09 10 0000000 09 10 0000000000	AMPIR ZRPHI  19354 -30 4999 177 19734 -31 18726 -20 4924 -101 19316 -23 19622 -28 4682 -178 19622 -28 4682 -178 20454 -37 5066 -161 20046 -20 20512 -37 5066 -164 20046 -20 20514 -37 5066 -164 20047 -20 20514 -37 5066 -164 20047 -20 20514 -37 5066 -161 20047 -20 20514 -37 5066 -161 20047 -20 20514 -37 5066 -161 20047 -17 5066 -161 20046 -200 20047 -17 5066 -161 20046 -200 20047 -17 5066 -161 20046 -200 20046 -	AMPILZLPHI  18833 -117  4525 129  18978 -18  18637 -108  18637 -108  186465 152  18818 -110  18925 -115  4224 133  18955 -117  18955 -117  18955 -117  18956 -118  18957 -109  18968 -107  18983 -125  4004 142  18992 -135  4004 142  18992 -135  4004 142  18992 -135  4004 142  18992 -135  4004 142  14906 -101  14808 -101  14808 -101  14808 -118  14544 -118  14584 -118  14594 -118	AMP1R3RPHI  17162 -126 4007 -170 16964 -127 16667 -117 1623 -155 16270 -120 17014 -125 4742 -168 16520 -130 16520 -130 16520 -130 16520 -130 16520 -130 16520 -130 16520 -130 16520 -130 16520 -130 16520 -130 16520 -130 16520 -130 16520 -130 16520 -130 16520 -130 16520 -130 16520 -130 16752 -130 16	AMP IL 3L PHI  18016 7 5033 -141 17994 6 17636 16 5178 -127 17636 13 17877 8 5030 -141 17877 8 17864 -17 17865 -17 17865 -17 17865 -17 17865 -17 17866 -12 4736 -12 17866 -12 4736 -12 17866 -12 4736 -12 17622 17 17727 -2 4556 -116 17703 4 18047 8 14048 -12 14564 -13 14564 -13	AMPZERRPHI  15690 -85 3769 165 3769 165 0  15786 -84 3803 170  15486 -84 3803 170  15618 -84 3804 170  15506 -85 3488 174 1593 -85 3488 174 15741 -83 3804 157 4097 151 4011 151	AMP2L3LPHI N  14869 54 4053 67 14979 50 14979 56 3971 92 14990 56 3971 92 14900 55 4012 97 15147 55 3967 93 01 15072 94 4034 98 15932 56 11997 59 11994 51 11944 51 11944 51 11944 51 11944 51 11945 51 11947 50 11948 51 11947 50 11948 51 11949 51 11949 51 11228 99 12287 99 12173 52 12287 99 12173 52 11986 51 11867 50 111975 50 111975 50 111775 50 111775 50 111775 50 111775 50 111778 51 112378 53 112246 52 12250 52	REC TPOMER  1 556665 1 556665 1 556666 1 556665 1 556665 1 556665 1 556666 1 556666 1 556666 1 556666 1 556666 1 556666 1 556666 1 556666 1 556665	LST  C8 10 55  O8 11 25  O8 11 25  O8 12 55  O8 12 55  O8 12 55  O8 13 55  O8 13 55  O8 14 25  O8 13 55  O8 14 25  O8 15 55  O8 16 55  O8 17 25  O8 16 55  O8 17 25  O9 11 48  O9 15 48  O9 15 48  O9 17 48  O9 16 48  O9 17 48  O9 17 48  O9 18 48  O9 17 48  O9 18 48  O9 19 48

END

INTCLEAN
MESSAGES WITH SEVERITY OF 3 OR MORE WILL CAUSE DELETION OF AFFECTED CORRELATORS
CORRELATOR RMS'S IN EXCESS OF 1000 FOR HIGH GAIN AND 200 FOR MEDIUM OR LOW GAIN WILL BE FLAGGED
SEVERITY 5 PROBLEMS MAY CAUSE OTHER CHECKS TO BE SUPPRESSED
X1 => HEADER BAD: X2, X3 => DATA, A/D RECORD ERASED

SCAN	T IME	SEVERITY		CORR	MESSAGE	** PROGRA	M PROCES	SSED 04/04/197	3 **	MSG STATUS	SOURCE RECORD/WORD	RA DEC MD WORD CONTENTS
14969 14970	22 02 18 22 12 57										P0056-17	
14971	22 22 11										3C48 D0224+67	013610+330128 D 022637+671348 D
14972	22 33 04 22 42 18										NR AD 91 3C119	020323+150635 D 043044+413504 D
14974	22 55 19 22 55 36										P2149-28	215031-283607 D
14974	22 55 36				ABNORMAL	RETURN TO N	EW SCAN				P2149-28 HDR 19	215031-283607 D
14975	23 02 20 23 12 08										OVO80 BLLAC	194847+080314 D 220137+420901 D
14977 14978	23 21 46 23 32 16										3C454.3	225238+160024 D
14979	23 41 00										P0114-21 P0056-17	011534-210025 D 005747-170911 D
14980 14981	23 52 59 00 02 30										3C48 P2149-28	013610+330128 D 215031-283607 D
14982 14983	00 13 54 00 23 50										CYGX-3	203128+405208 D
14984	00 33 10										P0114-21 3C48	011534-210025 D 013610+330128 D
14985 14986	00 42 07										D0224+67 3C147	022637+671348 D 054031+495018 D
14986	00 53 12				ABNORMAL	RETURN TO N	IEW SCAN				3C147 HDR 19	054031+495018 D
14987	01 01 32				HOHOMMAE		ER SOAN				3C119	043044+413504 D
14988 14989	01 11 40 01 22 16										CTA21 PO114-21	031727+162249 D 011534-210025 D
14990	01 32 20										3C454.3 3C418	225238+160024 0 203749+511343 D
14992	01 53 36										P0106+01	010716+012632 D
14992	01 54 00	*			ABNORMAL	RETURN TO N	EW SCAN				P0106+01 HDR 19	010716+012632 D 10
14993 14994	02 02 11 02 13 25										NRA0140 P0735+17	033449+321314 U 073633+174607 D
14995 14996	02 22 39										3C120	043145+051804 D
14997	02 41 36										3C446 3C454.3	222424-050509 D 225238+160024 D
14998	02 52 42 02 53 02										3C48 3C48	013610+330128 D 013610+330128 D
14999	02 53 02 03 02 06				ABNORMAL	RETURN TO N	EW SCAN				HDR 19 D0224+67	20 022637+671348 N
15000	03 12 44										3C147	054031+495018 D
15001	03 22 23 03 29 43	****		1R2R	RMS EXCE	EDS LIMITS					DTA 48	074403+101519 D 206
15002 15003	03 31 41 03 44 18										P0607-15 P0056-17	060828-154203 D 005747-170911 D
15004	03 52 09 03 57 28	****		1R2R	DMC EVE	EDS LIMITS					3C454.3	225238+160024 D
	03 57 28	****		1L2L	RMS EXCE	EDS LIMITS					DTA 48 DTA 52	283 248
	03 57 28 03 57 58	****		1L3L 1R2R		EDS LIMITS EDS LIMITS					DTA 60 DTA 48	232 327
	03 57 58 03 57 58	****		1L2L 1R3R	RMS EXCE	EDS LIMITS					DTA 52 DTA 56	294 259
15005	03 57 58	****		1L3L		EDS LIMITS					DTA 60	285
15005	04 02 38 04 03 27			85-3	XL RECEI	VER FAULT IN	DICATION	4			NRAO91 DTA 15	020323+150635 D 00000000000000001
15006	04 12 11 04 12 37										3C119 3C119	043044+4135C4 D 043044+413504 D
1997(191)	04 12 37 04 13 26	:		85-3		RETURN TO N		N *NGW INACTIVE	-		HDR 19	10
15007	04 23 00	-		03-3	AL RECEI	VER PAOLI IN	DICATIO	THOM INACTIVE	-			010716+012632 D
15008	04 32 55 04 35 45	***		85-1	XL TOTAL	POWER OUT O	F RANGE				P0438-43 DTA 37	043927-433555 D -15196
	04 35 45 04 36 45	***		85-3 85-3		POWER OUT O		N.			DTA 40 DTA 15	-15064 00000000000000000000000000000000000
	04 36 45	***		85-2	XL TOTAL	POWER OUT O	F RANGE				DTA 39	-15176
	04 37 45 04 37 45	***		85-3 85-2	XL TOTAL	POWER OUT O	F RANGE	*NOW INACTIVE			DTA 15 DTA 39	000000000000000000000000000000000000000
	04 39 45 04 39 45	***		85-1 85-2		POWER OUT O					DTA 36 DTA 39	-15200 -15068
15009	04 41 36 04 42 25	***		85-1				*NOW INACTIVE			P0614-34	061538-345518 P
	04 42 25	***		85-1	XL TOTAL	POWER OUT O	F RANGE	*NOW INACTIVE	*		DTA 36 DTA 37	-14408 -14680
	04 42 25 04 42 25	***		85-2 85-3				*NOW INACTIVES			DTA 39 DTA 40	-13852 -13964
15010	04 53 07 05 03 13										3C138 3C48	051936+163656 D 013610+330128 D
15012	05 12 09										D0224+67	022637+671348 D
15013 15014	05 22 43 05 33 10										3C147 DA267	054031+495018 D 092520+390924 D
15015	05 41 50 05 51 14										P1116+12 P1055+01	111731+124340 D 105705+014249 D
15017 15018	06 01 54										P0859-14	090059-140851 D
15019	06 12 24 06 22 46										P0614-34 D0742+10	061538-345518 D 074403+101519 D
15020	06 33 02 06 44 47										P1116+12 3C138	111731+124340 D 051936+163656 D
15022	07 49 05 07 49 05				ARNOPHAL	RETURN TO N	IEU SCAN				3C147 HDR 19	054031+495018 D
	08 19 55	****		1R2R	RMS EXCE	EDS LIMITS	LE JUNG				DTA 48	222
15023	08 19 55 08 27 32	****		1L 2L		EDS LIMITS					DTA 52 1216+48	205 121745+483901 M
15024	08 27 32 08 37 00				ABNORMAL	RETURN TO N	IEW SCAN				HDR 19 1242+41	2 124330+405708 M
15025 15026	08 45 00 08 53 08										1244+49	124552+490914 M 131620+343427 M
15027	09 03 27										1317+52	131837+515649 M
15028	09 11 29	NORMAL	END								3C 286	132952+303858 M

Fig. III-8. First part of INTCLEAN display for processing of scans 14969 through 15028 from the RAWTAPE.

DIAGNOSTIC SUMMARY 04/04/1973	DIAGNOSTIC SUMMARY	04/04/1973	DIAGNOSTIC SUMMARY 04/04/1973
NUMBER OF OCCURENCES		DIAGN	OSTICS
TESTS ON FIRST 6 WORDS		NO ER	RORS = 0
	***** **** **** ** **	NEGAT WORD DATE TIME	AL DATA TYPE IVE SCAN NO 3 ¬= 0 ILLEGAL NEGATIVE ILLEGAL
TESTS ON HEADER RECORDS		NO HE	ADERS FLAGGED = 0 OUT OF 65
	** ***** ***** 7  * *****	BLANK RIGHT 2ND P ILLEG ABNOR	CAN NO. OUT OF SEQUENCE REMOVED IN SOURCENAME " ASC. < O. HDR BAD. OSN WORD < O. HDR BAD. AL MODE. HDR BAD. MAL RETURN TO NEW SCAN INE CHANGE. HDR BAD
TESTS ON DATA RECORDS			
AFFECTED CHANNELS 85-1 85-2 85-3 NO TEL R L R L R		85- RECEI 85- IF SE 85- TELES BL GAINS FOCUS	TA RECORDS DELETED = 0 OUT OF 892  DATA MODE, POLN SELN DISAGREE VER SYSTEM IN MANUAL CONTROL LECTION DOES NOT MATCH MODE COPE OR DELAY TRACKING DISABLED IN MANUAL CTRL, SETTINGS CHANGED AND POLN MOTORS IN MANUAL CONTROL R LD SYSTEM LOCK OR LEVEL PROBLEMS
1 5 2 5	****  *  1	RCVR 85- BOX T 85- RE 85- TO RMS E SCAN	STEM LOCK PROBLEMS  IF LEVEL OUT OF RANGE  EMP OUT OF RANGE  CEIVER FAULT INDICATION  TAL POWER OUT OF RANGE  XCEEDS LIMITS  NUMBER ERROR. RECORD DELETED.  TUDE JUMP OVER 300
TESTS ON A/D RECORDS		NO A/	D RECS DELETED = 0 OUT OF 61
	*****	ro co	PRESSURE EXCEEDS LIMITS UNTER OUT BY >1 KHZ, DELAY CENTER CHANGE
TOTAL OF 1018 RECORDS PROCESS	ED		

NO OPERATOR MESSAGES FOUND

Fig. III-9. Second part of INTCLEAN display, the diagnostic summary, for processing of scans 14969 through 15028 from the RAWTAPE.

In Figure III-8 data diagnostics for each scan are listed. For each scan the display always gives: scan number, LST at the time header is written, source name, right ascension and declination of reference position precessed to date of observation, and the mode. Whenever faults are detected by system monitors or the DDP116, details concerning the fault are recorded on tape and appear in the INTCLEAN display. For each fault encountered, the following are printed out (see Figure III-8): LST for the header/or A/D record/or data record involved; the severity code of the fault, ranging from a single asterisk for a minor complaint to five asterisks for a major disaster; description of the fault encountered; the type of information (HDR, A/D, or DTA) and word (in terms of tape format) involved in the fault; and the contents of the word associated with the faulty data. A summary of the possible faults that can be detected, together with a summary of those actually deleted, is given by INTCLEAN as shown in Figure III-9.

Going through the data diagnostics in Figure III-8, we can begin discussing what needs to be done to clean scans 14969 through 15028 using INTEDIT. The first series of complaints concern "abnormal return to new scan". This is of no concern to the observer, but simply means that during execution of an observing scan some sort of computer interrupt caused an extra header to be written on tape before the observing was continued. However, with scan 15001 there is a complaint of "rms exceeds limits" for certain correlators. This is frequently an indicator of bad data because it means the fringe-fitting algorithm encountered difficulty in coming up with a solution consistent with expectations. Guided by the LST time for the complaint we examine the data record at 03<sup>h</sup>29<sup>m</sup>43<sup>s</sup> in scan 15001 (Figure III-7h) and see that there are unusual rms indices for this record for all SBAND correlators involving 85-1. Furthermore, some of the amplitudes are also anomalous. Therefore, we clearly must delete the bad data, so we prepare the following DELETE card:

and we can then pass on to a number of complaints about scan 15004. Noting excessive rms' in Figure III-7i for XBAND data involving 85-1, together with anomalous amplitudes, we prepare:

DELETE 15004 XBAND (03 57 28) (03 57 58) 85-1;

Going on, we note in Figure III-8 complaints of "XL receiver fault" for 85-3. In this case examination of the appropriate data records in Figure III-7 reveal nothing anomalous, so we conclude that the problem did not affect the data seriously, therefore we do nothing (a conservative observer might delete the offending data as a matter of principle).

In scan 15008 we see complaints of another serious fault (three or more asterisks usually means faults serious enough to require deletions): "total power out of range" for a number of XBAND receivers. Indeed, from Figure III-7j, the total power indices show many anomalies. Further, many of the XBAND amplitudes and phases appear anomalous. Several records involving 85-1 require deletions:

DELETE\_15008\_XBAND\_(04\_33\_45) (04\_34\_45) 85-1;

and we will also erase all XBAND data occurring for this scan after  $04^{\rm h}35^{\rm m}45^{\rm s}$  (we will ERASE rather than DELETE only to give some variety in the example; ordinarily only DELETE would be used):

ERASE\_15008\_XBAND\_(04\_35\_45)\_(04\_39\_45);

Continuing on with Figure III-8, we see more complaints of excessive rms in scan 15022; but the amplitudes and phases are consistent with all the other data so we do nothing. Without good reason to believe the amplitudes and phases are acceptable, we would automatically delete these data records also. Coming to the end of Figure III-8 we have finished examining the data diagnostics recorded on tape. As the reader might suspect, the example just discussed contains fewer than average complaints.

Unfortunately the data diagnostics do not detect many serious faults. For this reason the user must spend a considerable amount of

time examining the raw data records while searching for anomalies. In cases where dual-mode data predominates the observer may prefer to examine an INTSCRIB display where first one frequency then another is shown; this could be accomplished by using the following program:

```
//_EXEC_INTCOPY, INTAPE=3085, INNAME=RAWTAPE
//SYSIN_DD_*
INCLUDE_SBAND
END_REWIND
INCLUDE_XBAND
// EXEC_INTSCRIB
```

What anomalies can be detected just by examining an INTSCRIB of the data records? Only experience will help the user very much, but one always does at least the following: (i) scan the RMS indices looking for sudden changes; (ii) scan the TPOWER indices looking for anomalous changes; (iii) look at the calibrator amplitudes and phases to verify that one is getting roughly constant large amplitudes, and phases roughly constant over short periods; and (iv) if you know what to expect, look for anomalous behavior in all other sources. If the delays malfunction, all amplitudes involving a particular telescope will appear noise-like; remember that noise amplitudes of about 70 counts are the most probable, with a possible range from a few counts to somewhat over a hundred. Interference or other anomalies can show up in unusual amplitudes in random records.

The user will quickly become familiar with the odd behavior of data when the fringe period exceeds 30 seconds. The fringe fitting algorithm will not give a solution for amplitude and phase unless a considerable fraction of a fringe period is included. Hence, as we see in Figure III-7 starting at  $22^{\rm h}22^{\rm m}30^{\rm s}$  LST, zeroes are recorded until enough samples of a fringe period are collected to make a solution meaningful. This problem is most serious when the spacing is short (like 100 m); but always occurs near hour angles of  $+4^{\rm h}40^{\rm m}$  (west) when

so-called <u>cross-over</u> occurs. At cross-over the fringe period temporarily becomes "infinite" and, depending upon the spacing, many minutes may pass before enough data are collected to fit a fringe.

Part of the cleaning process involves replacement of bad data in A/D records or headers. In practice one assumes that these are correct until something tells us otherwise, since such problems are usually rare or have negligible effect on the data. The most frequent problem occurs when a bit is "dropped" by the DDP116 when a header is written, so the information written may be garbage. Because of their placement in the header, bad baselines appear most often, but mode, LST, source name, and even scan number may occasionally be messed up. These problems are solved by use of HEADCORR or REPLACE features of INTEDIT; they are never solvable just by using the automatic programs soon to be discussed.

Once all DELETE, ERASE, HEADCORR, and REPLACE edit cards have been prepared they could be run with INTEDIT to clean the data tape. In most cases, however, one cleans the data in the same pass of INTEDIT in which one applies the automatic corrections we will now discuss.

### (5) Correcting Data with INTEDIT.

Without further delay we can prepare the cards to accomplish the PHASE, AMPCOR, and CLOCK corrections. The data needed for the latter are obtainable either from observing logs or from tables kept at the interferometer control building. For the data we are processing in our example, we prepare:

PHASE\_14969\_15028; AMPCOR\_14969\_15028; CLOCK\_14969\_14996;0.005S CLOCK\_14997\_15028;0.006S

Ordinarily one need not have the CLOCK correction accurate to more than a few milli-seconds; however, we have divided it in two for this case to illustrate how a number of data segments may require different CLOCK corrections.

Finally, we borrow a set of accurate baseline constants, usually already determined by NRAO staff, to apply baseline corrections. In case they are not available, we will shortly discuss the program INTBCAL whereby the user may determine his own. The BASELINE cards are of the form:

BASELINE\_14969\_15028\_SBAND\_BL12;-4785.5938\_-15089.9192\_6421.5360\_0.0 but we will not list all of them since the user can examine them shortly in one of the figures.

All of the edit cards used to accomplish cleaning and correcting, when applied to data on RAWTAPE, produce a CORRTAPE where the visibility functions are in the V'=A' exp  $i\phi$ ' stage. The following program accomplishes this:

```
//_EXEC_INTEDIT,INTAPE=3085,INNAME=RAWTAPE
//_OUTTAPE=3086,OUTNAME=CORRTAPE,OUTDISP=NEW
//INTERP.SYSIN_DD_*

TRANSFER_14969_15028;

DELETE_15001_SBAND_(03_29_43)_85-1;

DELETE_15004_XBAND_(03_57_28)_(03_57_58)_85-1;

DELETE_15008_XBAND_(04_33_45)_(04_34_45)_85-1;

ERASE_15008_XBAND_(04_35_45)_(04_39_45);

PHASE_14969_15028;

AMPCOR_14969_15028;

CLOCK_14969_14996;0.005S

CLOCK_14997_15028;0.006S

BASELINE_14969_15028_SBAND_BL12; etc.

(results shown in Figures III-10-12)
```

Note that we have added a TRANSFER card. In this case it is redundant, because all data called for particular processing is automatically transferred to the OUTUNIT; however, it is helpful to habitually include a TRANSFER card, because frequently one edits only part of the data that one wishes to remain together on tape,

The output from the above pass with INTEDIT is shown in Figures III-10-12. In Figure III-10 we see the reproduction of each card together with an interpretation, in hexadecimal form, of the instructions on each card. Format and other errors on the edit cards are found by examination of this output. Figure III-11 shows the result after sorting according to priority of each verb. Finally, Figure III-12 shows the output produced as each edit card processes the data, so that one can confirm that everything has been accomplished. At the end a summary of all processing is given.

Of course, the wise user will want to see the data itself to see if it looks correct. In particular, one can use the following program to check on whether deletions and erasures were accomplished correctly:

```
//_EXEC_INTCOPY,INTAPE=3086,INNAME=CORRTAPE
//SYSIN_DD_*
INCLUDE_15001
INCLUDE_15004
INCLUDE_15008
//_EXEC_INTSCRIB
    (results shown in Figure III-13)
```

Comparing the results of Figure III-13 with the raw data in Figure III-7 proves that what was intended has been accomplished.

One could obtain an INTSCRIB display of all the data on CORRTAPE, but that would only be to confirm that the calibrators lack only gain calibration and phase centering. Since our next task is to take care of this unfinished business, and doing this forces us to examine the amplitudes and phases of the calibrators, one usually combines examination of the CORRTAPE with determination of  $g_{\rm S}$  and  $\phi_{\rm S}$  for each correlator.

Before proceeding, let us diagrammatically summarize what is generally done in cleaning and correcting with INTEDIT.

```
VERB PRI SOURCE SCANI SCANZ LSTI LSTZ SMASK XMASK
14969 15028 00 00 00 23 59 59 FFFF FFFF
DELETE 15001 SBAND (03 29 43) 85-1;
DELETE 7 15001 15001 03 29 40 03 29 50 F3CC 0000
DELETE 15004 XBAND (03 57 28) (03 57 58) 85-1;
DELETE 7 15004 15004 03 57 20 03 58 00 0000 F3CC
...........
DELETE 15008 XBAND (04 33 45) (04 34 45) 85-1;
DELETE 7 15008 15008 04 33 40 04 34 50 0000 F3CC
ERASE 15008 XBAND (04 35 45) (04 39 45);
ERASE 5 15008 15008 04 35 40 04 39 50 0000 FFFF
PHASE 14969 15028;
PHASE 19
         14969 15028 00 00 00 23 59 59 FFFF FFFF
CLOCK 14969 14996; 0.0055
CLOCK 12 14969 14996 00 00 00 23 59 59 FFFF FFFF
CLOCK CORRECTION IS 00 00 00.00500 SECONDS
CLOCK 14997 15028: 0.0065
CLOCK 12 14997 15028 00 00 00 23 59 59 FFFF FFFF
CLOCK CORRECTION IS 00 00 00.00600 SECUNDS
BASELINE 14969 15028 SBAND BLI2:-4765-5938 -15086-9192 6421-5360 0-0
BASELINE 11 14969 15028 00 00 00 23 59 59 C300 0000
BX= -4785-593800 BY= -15086-919200 BZ= 6421-536000 BK=
BASELINE 14969 15028 SBAND BL13:-4533.3667 -14292.7077 6083.5536 0.0
BASELINE 11 14969 15028 00 00 00 23 59 59 30C0 0000
BX= -4533.366700 BY= -14292.707700 BZ= 6083.553600 BK=
BASELINE 14969 15028 5BAND BL23:-252.2271 -794.2115 337.9823 0.0
DASELINE 11 14969 15028 00 00 00 23 59 59 0030 0000
Bx= -252.227100 BY= -794.211500 BZ= 337.982300 BK=
## RASELINE 14969 15028 XBAND BL12:-14356.7814 -45260.7576 19264.6080 0.0

## BASELINE 11 14969 15028 00 00 00 23 59 59 0000 C300

## BX= -14356.781400 BY= -45260.757600 BZ= 19264.608000 BK=
BASELINF 14969 15028 XBAND BL13:-13600.1001 -42878.1231 18250.6608 0.0

8ASELINE 11 14969 15028 00 00 02 35 95 90 0000 3000

8x= -13500.100100 8Y= -42878.123100 8Z= 18250.660800 8K=
BASELINE 14969 15028 XBAND BL23:-756.6813 -2382.6345 1013.9469 0.0
BASELINE 11 14969 15028 00 00 00 23 59 59 0000 0C30
BX= -756.681500 6Y= -2382.634500 8Z= 1013.946900 BK=
END OF EDIT CARDS
```

Fig. III-10. First part of INTEDIT output display showing the edit cards that have been supplied and their interpretation.

EDIT CARD ORDER FOLLOWING SORT/MERGE STEP (CARDS ARE RE-SORTED INTERNALLY, IN ORDER OF PRIORITY, AS NEEDED)

Fig. III-11. Second part of INTEDIT output where the translated edit cards are sorted and listed.

INTERFEROMETER EDITING PROGRAM - NRAD DUAL FREQUENCY INTERFEROMETER (S AND X BANDS) EDITING BEGINS AT 19 36 30 ON 04/04/73

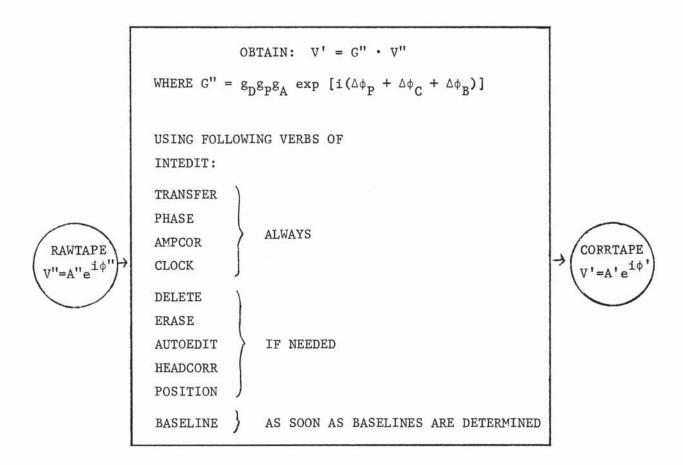
```
INPUT FILE BEGINS AT HEADER 14969 LST 22 02 19 SIDEREAL DAY NO. 2448275
   THE DDNAME IS FT10F001
THE DSNAME IS HJELLMNG.RAH
THE UNIT NUMBER IS 134
THE VOLUMN SERIAL NUMBER IS 666666
     THE DISPOSITION IS OLD
                             RECFM IS VB (VB=>VSB)
LRECL IS 204
BLKSIZE IS 2248
EDIT CARD BASELINE 14969 15028 NOW ACTIVE AT SCAN 14969 N=
EDIT CARD BASELINE 14969 15028 NOW ACTIVE AT SCAN 14969 N=
EDIT CARD BASELINE 14969 15028 NOW ACTIVE AT SCAN 14969 N=
EDIT CARD BASELINE 14969 15028 NOW ACTIVE AT SCAN 14969 N=
EDIT CARD BASELINE 14969 15028 NOW ACTIVE AT SCAN 14969 N=
EDIT CARD BASELINE 14969 15028 NOW ACTIVE AT SCAN 14969 N=
EDIT CARD BASELINE 14969 15028 NOW ACTIVE AT SCAN 14969 N=
EDIT CARD AMPGOR 14969 NOW ACTIVE AT SCAN 14969 N=
EDIT CARD AMPGOR 14969 15028 NOW ACTIVE AT SCAN 14969 N=
EDIT CARD AMPGOR 14969 NOW ACTIVE AT SCAN 14969 N=
EDIT CARD PHASE 14969 15028 NOW ACTIVE AT SCAN 14969 N=
EDIT CARD PHASE 14969 15028 NOW ACTIVE AT SCAN 14969 N=
EDIT CARD PHASE 14969 15028 NOW ACTIVE AT SCAN 14969 N=
EDIT CARD PHASE 14969 15028 NOW ACTIVE AT SCAN 14969 N=
EDIT CARD PHASE 14969 15028 NOW ACTIVE AT SCAN 14969 N=
EDIT CARD PHASE 14969 15028 NOW ACTIVE AT SCAN 14969 N=
EDIT CARD PHASE 14969 15028 NOW ACTIVE AT SCAN 14969 N=
EDIT CARD PHASE 14969 15028 NOW ACTIVE AT SCAN 14969 N=
EDIT CARD PHASE 14969 15028 NOW ACTIVE AT SCAN 14969 N=
EDIT CARD PHASE 14969 15028 NOW ACTIVE AT SCAN 14969 N=
EDIT CARD AMPGOR 14969 N=
EDIT CARD AMPGOR 14969 N=
EDIT CARD BASELINE 14969 15028 NOW ACTIVE AT SCAN 14969 N=
EDIT CARD AMPGOR 14969 N=
EDIT CARD CAND AMPGOR 14969 N=
EDIT CARD BASELINE 14969 15028 NOW ACTIVE AT SCAN 14969 N=
EDIT CARD AMPGOR 14969 N=
EDIT CARD BASELINE 14969 N=
EDIT CARD BASELIN
   THE OUTPUT FILE:
   THE DDNAME IS FT08F001
THE DSNAME IS SYS73093.T195908.RF000.FIG10#12.CORR
THE UNIT NUMBER IS 136
THE VOLUMN SERIAL NUMBER IS 777777
THE DOLUMN SERIAL NUMBER IS 777777
THE DISPOSITION IS NEW
   DCB PARAMETERS:
                             RECFM IS VB (VB=>VSB)
LRECL IS 204
BLKSIZE IS 2248
   CLOCK CORRECTION HAS CHANGED FROM 00 00 00.0000 TO 00 00.0050 AT SCAN 14969 LST 22 02 19
   EDIT CARD CLOCK 14997 15028 NOW ACTIVE AT SCAN 14997 N= 11
EDIT CARD CLOCK 14969 14996 00 00 00 23 59 50 IS RETIRING AT SCAN 14997
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      J= 8 N+1= 11
  CLOCK CORRECTION HAS CHANGED FROM 00 00 00.0050 TO 00 00.0060 AT SCAN 14997 LST 22 02 19
 EDIT CARD DELETE 15001 15001 NOW ACTIVE AT SCAN 15001 N= 11
EDIT CARD DELETE 15001 15001 03 24 40 03 24 50 IS RETIRING AT SCAN 15002
EDIT CARD DELETE 15004 15004 NOW ACTIVE AT SCAN 15004 N= 11
EDIT CARD CARD ERASE 15008 NOW ACTIVE AT SCAN 15008 N= 11
EDIT CARD DELETE 15008 15008 NOW ACTIVE AT SCAN 15008 N= 12
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      J= 2 N+1= 11
   ALL EDIT CARDS READ AT SCAN 15008
N+1=
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        N+1=
   EDITING TERMINATED BY END OF INPUT FILE
  EDIT SYNOPSIS:
                                                                                                                                         949 RECORDS
6 RECORDS
9 RECORDS
883 RECORDS
883 RECORDS
    TRANSFER PERFORMED ON
  DELETE PERFORMED ON DELETE PERFORMED ON CLOCK PERFORMED ON AMPCOR PERFORMED ON PHASE PERFORMED ON PERFORMED ON DERFORMED ON DEFENSION DERFORMED ON DEFENSION DEFEN
                                                                                                                                              883 RECORDS
  GETHOR WAS CALLED 67 TIMES
GETBL WAS CALLED 65 TIMES
GETBL WAS CALLED 65 TIMES
                       61 A-D RECORDS WERE PROCESSED
                 1033 RECORDS READ FROM INPUT FILE
1009 RECORDS WRITTEN ON OUTPUT FILE
```

Fig. III-12. The third and last part of the INTEDIT display in which the properties of the input data set and output data set are described and a description of what processing INTEDIT has accomplished is given.

				- DATA FOR CO	NF I GUPA TI O	N 1-18-19					
SCAN M SOURCE	HA RMS/100	AMP1R2RPH1	AMP1L2LPHI	AMP1R3RPHI	AMP1L3LP	HI AMP2R	3RPHI	AMP 2L 3L	PHI NR	C TPOWER	LST
15001 SD D0742+10	-04 21 000000	6520 -66	6087 -154	5415 -156	5630 -	23 4900	-90	4978	49	1 655665	03 22 42
15001 XD D0742+10	-04 20 000000	3245 55	2811 7	2741 88	3114 1	19 2638	143	3058	68	1 665666	03 23 12
15001 SD D0742+10	-04 20 000000	6480 -71	6111 -159	5740 -159	5903 -	27 4942	-92	4988	47	1 655665	03 23 42
15001 XD D0742+10	-04 19 000000	3422 45	2779 -5	2663 82	3283 1	10 2601	147	2945	67	1 665666	03 24 12
15001 SD D0742+10	-04 19 300000	6199 -76	5942 -165	5558 -166	5763 -	34 5062	-92	4867	49	1 655665	03 24 42
15001 XD D0742+10	-04 18 000000	3481 57	2816 10	3025 87	3476 1	15 2679	155	2791	75	1 665666	03 25 12
15 301 XD D 0742+10	-04 17 000000	3403 87	2934 39	2915 117	3345 1	47 2522	152	2840	73	1 665666	03 26 12
15001 SD D0742+10	-04 17 000000		6109 -153	5974 -153	6039 -	20 5078	-93	4944	47	1 655665	03 26 42
15001 XD D0742+10	-04 16 000000	3247 64	2695 17	2946 99	3210 1	28 2655	145	2866	67	1 665666	03 27 12
15001 SD D0742+10	-04 16 000000	6782 -67	6025 -155	5784 -158	5828 -	24 5000	-91	4995	49	1 655665	03 27 42
15001 XD D0742+10	-04 15 000000	3283 76	2880 30	2930 111	3281 1	36 2688	148	2799	70	1 665666	03 28 12
15001 SD D 0742+10	-04 15 000000	6807 -62	6119 -149	5866 -150	5841 -	18 5004	-93	5003	47	1 655665	03 28 42
15001 XD D0742+10	-04 14 100000	3280 67	2833 19	2962 103	3258 1	32 2546	147	2851	69	1 665666	03 29 12
15001 SD D0742+10	-04 14 00	0	0	0		0 5043	-100	5168	42	1 655665	03 29 43
15004 SD 3C454.3	04 59 1000	16497 -65	16727 -153	15296 -162	15922 -	27	0		0	1 666666	03 52 28
15004 SD 3C454.3	05 00 1000	17500 -66	16507 -153	14738 -161	15623 -	28	0		0	1 666666	03 52 58
15004 SD 3C454.3	05 30 0000	16503 -66	16497 -154	15201 -162	15926 -	29	0		0	1 666666	03 53 28
15004 SD 3C454.3	US 01 0000	17389 -63	16911 -150	15230 -158	15877 -	26	0		0	1 666666	03 53 58
15004 SD 3C454.3	05 01 1111	17195 -70	16569 -156	15325 -163	15785 -	29	0		0	1 666666	03 54 28
15004 SD 3C454.3	05 02 1100	16839 -79	16463 -166	14840 -175	15795 -	41	0		0	1 666666	03 54 58
15004 SD 3C454.3	05 02 0001	17653 -61	16536 -149	14983 -161	15836 -	27	0		0	1 666666	03 55 28
15004 SD 3C454.3	05 03 0000	17502 -53	16798 -140	15444 -150	16022 -	15	0		0	1 666666	03 55 58
15004 SD 3C454.3	05 03 100000	16711 -58	16658 -146	15118 -152	15860 -	20 14390	-86	13168	55	1 666666	03 56 28
15004 XD 3C454.3	05 04 1000	14100 74	12646 25	12257 88	13984 1	17	0		0	1 666666	03 56 58
15304 XD 3C454.3	J5 04	0	0	0		0	0		0	1 666666	03 57 28
15004 XD 3C454.3	05 05 00	0	0	0		0 11888	158	12670	90	1 666666	03 57 58
15304 SD 3C454.3	05 05 1101	17534 -77	16477 -165	15204 -174	15638 -	41	0		0	1 666666	03 58 28
15004 SD 3C454.3	05 06 1011	17401 -69	16546 -157	15100 -164	15461 -	32	0		0	1 666666	03 58 58
15004 SD 3C454.3	05 06 1000	17360 -63	16700 -151	15012 -160	15451 -	26	0		0	1 666666	03 59 28
15008 SD P0438-43	-00 06 000000	9581 -119	9494 153	8541 160	8898 -	67 8223	-102	7836	38	1 666776	04 33 15
15008 XD P0438-43	-00 05 00	0	0	0		0 3353	146	3314	64	1 776777	04 33 45
15008 SD P0438-43	-00 05 000000	10398 -56	9548 -143	8927 -141	9315	-7 8313	-96	7351	43	1 666776	04 34 15
15008 XD P0438-43	-00 04 00	0	0	0		0 2928	119	3026	37	1 777777	04 34 45
15308 SD P0438-43	-00 04 000000	10274 -95	9672 177	8884 -178	8980 -	45 8082	-98	7582	41	1 666776	04 35 15

Fig. III-13. An INTSCRIB display of the 30 second records for scans 15001, 15004, and 15008, after they have been selected from the CORRTAPE by INTCOPY, to allow examination of the scans where deletions or erasures should have been performed, so that it can be confirmed that the desired results were obtained.

END



## (6) Calibrating LL and RR Data With INTEDIT

The last stage in the data processing for LL and RR correlators is the determination of  $G'=g_S^{}\exp(-i\phi_S^{}),$  i.e., determinations of the gain factor  $(g_S^{})$  needed to put all amplitudes in units of 1000 counts per flux unit, and determination of the phase center  $(\phi_S^{}).$  We will now describe a simple way of accomplishing this.

We make use of INTSCRIB with the CPFU and SUM options. For the sample data that we are using to illustrate the data reduction procedure, the following program will allow us to determine the CPFU and mean phase for each calibrator in the default list (see Figure III-4):

```
//_EXEC_INTCOPY,INTAPE=3086,INNAME=CORRTAPE,
// OUTUNIT=DISK,OUTNAME='&&DATA'
//SYSIN DD *
INCLUDE 14969 15028
// EXEC INTAVG, PARM='ARITH', INUNIT=DISK, INNAME='&&DATA',
//_OUTUNIT=DISK,OUTNAME='&&SBAND'
//SYSIN DD *
INCLUDE SBAND
//_EXEC_INTSCRIB, PARM='CPFU, SUM, SORT, NOGRID, RANGE=2000',
//_INUNIT=DISK,INNAME='&&SBAND'
 //_EXEC_INTAVG, PARM='ARITH', INUNIT=DISK, INNAME='&&DATA',
 //_OUTUNIT=DISK,OUTNAME='&&XBAND'
//SYSIN_DD_*
 INCLUDE_XBAND
 //_EXEC_INTSCRIB, PARM='CPFU, SUM, SORT, NOGRID, RANGE=2000,
 //_INUNIT=DISK,INNAME='&&XBAND'
     (results shown in Figure III-14 (SBAND) and III-15 (XBAND)
```

Let us first discuss the determination of the phase center  $(\phi_S)$  from the results of Figure III-14 and Figure III-15. All the calibrators shown are good phase calibrators and the average phase  $(\phi^*)$  for each source for each correlator is obtained because of the SUM option. As discussed earlier, we determine  $\phi_S$  from data on  $\phi^*$  by a fit to the data according to the formula

$$\phi_S = \overline{\phi^{\dagger}}$$
.

We see no significant phase drifts in the data for each scan, so we obtain  $\varphi_S$  from averaging together the  $\varphi^1$  for each source:

# PHASE CENTER $(\phi_S)$

CORRELATOR	1R2R	1L2L	1R3R	1L3L	2R3R	2L3L
SBAND	-76	-164	-166	-33	-91	49
XBAND	38	-9	68	97	153	74

									- DATA	OR CO	FIGUEAT	ION	1-18-19								
SCAN	M SOURCE	на	R	MS/100	AMPIR2	RPHI	AMP11.	2LPHI	AMPIR	RPHI	AMP 1L3	SLPHI	AMP ZP 3	RPHI	AMP2L3	LPHI	NREC	TPOWER		LST	
14970 S	3048	-03	19	000000	1518	-67	1542	-155	1335	-159	1468	-27	1263	- 87	1256	53	7	655665	22	16	15
14980 S				000000	1397			-157	1267		1394			-86	1193	53		666666		55	
14984 SI				000000	1467	-69		-157	1210		1308		1193	-87	1143	52		656665		36	
14998 S				000000	1398	-80		-167	1263		1399		1220	-86	1188	53		655665		56	
15011 S				000000		-70		-157	1361		1428		1232	-84	1185	55		655665		36	
14973 S				000000	1606	-81		-168	1391		1489		1250	-89	1269	51		650665		45	
14987 S				000000	1561	-84		-171	1326		1464		1264	-87	1241	52		555665		05	
15006 S	30119	-00	14	000000	1487	-71	1452	-158	1216	-165	1365	-33	1151	-86	1137	54	7	666665	34	15	56
14986 Si	30147	-04	43	200000	1675	-72	1544	-159	1475	-166	1544	-33	1279	-86	1249	54	o	655665	20	56	21
15000 S				000000	1617			-160	1349		1428			-86	1208	54		656665		16	
15013 S				000000	1499			-150		-158	1357		1185	-86	1145	54		506665		26	
15022 SI				000000	1557			-149	1325		1405		1224	-86	1193	54		555665		05	
ISULE S	, ,,,,,,	02		00000	.,,,	- OL	1471		1323		1403		1624	- 00	1173	34		333603	0.0	0.5	23
14986 S	CTA21	-02	01	000000	1427	-85	1551	-173	1338	-176	1456	-43	1244	-90	1238	50	8	655665	01	15	30
14991 S	3C418	05	07	0000	1519	-67	1585	-154	1419	-163	1507	-29		0		o	10	655665	01	45	03
14993 S	NRA0140	-01	28	000000	1457	-80	1571	-167	1346	-173	1442	-41	1271	-87	1225	53	8	656665	02	06	00
15010 S	30134		23	000000	1515	-77	1502	-164	1283	-168	1376	-34	1211	-07	1180	54	,	666665	04	56	24
15021 5				200000	1611			-168	1318		1411		1236		1167	53		665665		47	
17021 3	, 50150	01		700000	1011	-00	1,70,	- 100	1310		1411	- 3.7	1230	-00	1101	,,	,	06 300 3	56	• • •	00
15014 S	DA267	-03	48	000000	1543	-77	1513	-164	1398	-170	1467	-37	1259	-88	1240	53	7	555665	05	36	30
15015 SI	P1116+12	-05	31	000000	1725	-66	1679	-155	1468	-157	1623	-22	1431	-93	1407	48	10	566666	05	45	52
15020 S	P1116+12	-04	41	000000	1784			-164	1533		1563		1341		1303	47		655665		36	
15028	1 30266	-04	14	000		0	1509	-168		0	1496	-37		0	1238	48	17	550665	99	15	48
													ON 1-18			*					
SOURCE	RIGHT	ASC DE	CL I	NATION	A'4P	1828	PHI	AMP 11	LZL PHI	AME	1 R3R P	114	AMP 1L3	L PHI	дмр	2R3P	PH1	АМР	21.31	РНІ	Ĺ
3048	01 36	10 +	33	01 28	14	69	-71	1509	-158	1.7	88 -1	65	1400	-32	122	3	-46	112		53	4
30119		44 +			15		-79	1525	-166			72	1439	-39	122		- 47	121		52	
30147		31 +			15		-67	1516	-155			62	1434	-30	123		-86	119		54	
CT421	03 17			22 49	14.		-85	1552	-173			76	1456	-43	124		-90	123		50	
3C418	20 37			13 43	15		-67	1586	-154			63	1508	-29			0			(	
NRAU140	03 34			13 14	14		-80	1572	-167			73	1442	-41	127		-47	122		53	
30138	05 19			36 56	15		-78	1543	-166			70	1394	-37	122		-36	117		53	
DA267	39 25			09 24	15		-77	1514	-164			70	1468	-37	125		-88	124		53	
P1116+1		31 +			17		-71	1648	-159			61	1593	-27	138		-92	135		48	
3C286		52 +				0	0	1509	-168		0	0	1497	-37		o	0	123		48	
END																					

Fig. III-14. An INTSCRIB display, with PARM='CPFU,SUM,SORT', of the calibrators on the CORRTAPE, so SBAND gains and phase centers can be determined.

										- DATA	FOR CONF	IGURA	TION	1-18-19								
SCAN M	SOURCE	h	Δ	45/	100	AMP1R2	RPHI	AMPIL	2LPH1	AMP I P	3RPHI	AMP1L	3L PHI	AMP2R3	IHAR	AMP2L3	IL PHI	NRFC	TPOWER		LST	
14970 XD	10.44	-44	19	0000	000	947	63	886	13	845	85	1064	113	818	159	847	81	7	666656	22	16	45
14280 XD				0000		859	61	820	12	777	82	965		747		178	33		666666		56	
14934 XD				000		1010	63	920	14	773	84	980		743	160	825	81		665666		36	
14998 XD				000		926	43	873	-7	804	58	1013		804	165	852	67		665666		56	
15011 (0				000		961	72	351	23	809	81	953			170	830	91		676666		06	
14973 XD	3C119	-05	43	000	000	1117	29	999	-17	931	54	1091	82	886	155	940	76	4	666666	22	47	00
14707 40	3C119	-03	24	0000	000	1068	18	937	-30	945	38	1216	65	904	162	962	82	8	665056	01	05	51
15 10 6 XD	3C11+	-00	14	0000	000	997	57	384	7	793	72	1005	100	665	168	759	88	7	666656	04	16	26
14936 XU	30147	-04	43	0000	000	1080	66	931	13	947	81	1124	110	853	166	942	88	4	665666	00	56	46
15000 XD	3C147	-02	23	000	000	1026	56	919	7	894	72	1094	99	785	165	883	87	7	665666	03	16	33
15013 XD	3C147	-00	13	0000	000	940	65	871	16	761	76	934	105	691	168	752	90	7	666666	05	26	32
15022 XD	3C147	Úc	25	0000	000	996	34	890	35	829	98	997	126	731	166	800	87	20	566666	08	05	57
14988 XD	CTAZI	-02	01	0000	000	1002	10	997	-40	897	40	1134	68	876	152	919	12	8	665666	01	16	00
14991 XD	3C 418	Op	10	000	000	953	65	894	17	841	79	1026	108	887	168	896	90	4	665666	01	48	18
14993 XD	NRA0140	-01	28	000	coc	952	31	929	-19	773	50	997	78	783	163	827	84	7	665666	02	36	00
15010 XD	20124	-00	22	3000	200	842	36	752	-12	709	59	859	86	442	110	711	0.1	- 5	77/77/			
15021 XD				0000		920	29		-20	777	54	940		737	160	711 807	81		776776		56	
		125					2,	010	-20	,,,	24	740		131	100	807	91	,	000000	56	*'	30
15014 XD	DA 261	-03	48	000	000	1065	40	969	-9	972	59	1164	87	877	164	948	86	6	655666	05	36	30
15015 XU	P1110+1c	-05	31	0000	000	1291	61	1167	10	1030	96	1216	126	1100	148	1117	70	5	674676	35	46	10
15020 XD	P1110+12	-04	41	0000	000	1307	40	1117	-7	1132	75	1286	102	986	150	1030	73	6	665666	06	36	30
15028 M	3C 2 86	-04	14	0 0	0	1075	19		0	959	52		0	850	149		0	17	556665	09	15	48
														ON 1-18-								
SOURCE	RIGHT	ASC D	ECLI	MAT	ON	AMP	1R2R	PHI	AMP 11	.2L PHI	AMP	1 R3R	PHI	AMP 1L3	L PHI	AMP	2R3R	PHI	AMP	2L 3L	PH	1
3C 4 d		10				9		61	871	11	80		78	996	106			163	82		8	
30119		) 44				10		34	957	-14	89		54	1104	81			161	68		8.	
30147	05 40			50 1		10		68	903	19	85		82	1038	110			166	84		8	
CTA21	03 1			22 4		10		10	998	-40	89		40	1135	68			152	91		7	
30418	20 3			13 4			53	65	895	17	84		79	1026	108			168	89		9	
NPA0140	4د 03			13 1			52	31	929	-19	77		50	997	78			163	82		8	
30138	05 19			36 5			82	32	786	-16	74		56	900	84	70		160	75		8	
DA267	09 25			09 2		10		40	970	-9	97		59	1164	87			164	94		8	
P1116+12	11 17			43 4		12		50	1142	1	108		85	1252	114			149	107		7	
30236	13 29	52	+ 30	38 5	8	10	15	19	0	0	96	0	52	0	0	85	0	149		0		0
ENO																						

Fig. III-15. An INTSCRIB display, with PARM='CPFU, SUM, SORT', of the calibrators on the CORRTAPE, so XBAND gains and phase centers can be determined.

Determination of  $g_S$  is somewhat similar. Because of our having used the CPFU option to get the results shown in Figures III-14 and 15, the average CPFU for each source is obtained. Now, however, we must face the problem that very few sources are good gain calibrators. This is partly because flux densities for many sources are poorly known and partly because many, if not most, of the sources vary with time. As can be seen from Figures III-14 and 15, the CPFU vary considerably. The user must make his amplitude calibration on the basis of what he thinks is best. One could average all CPFU, counting on the errors for poorly known sources being random and canceling; or else one can select a few sources believed to be steady, well measured objects. For this example, we will do the latter, using the data for 3C48, 3C119, 3C147, 3C418, NRAO140, 3C138, and 3C286 to obtain  $g_S = 1000/\text{CPFU}$  as follows:

SYSTEM GAIN FACTORS (	g <sub>c</sub> )
-----------------------	------------------

CORRELATOR	1R2R	1L2L	1R3R	1L3L	2R3R	2C36
SBAND	0.644	0.647	0.754	0.686	0.817	0.830
XBAND	1.102	1.133	1.176	0.987	1.247	1.183

Now we use INTEDIT to effectively multiply

$$V = G' V' = g_S A' \exp [i(\phi' - \phi_S)]$$

so the CORRTAPE can be transformed into the CALTAPE for all LL and RR correlators. The following program will accomplish this, with additional forms of data display so we can evaluate how good the results are:

```
//_EXEC_INTEDIT,INTAPE=3086,INNAME=CORRTAPE,
//_OUTTAPE=3087,OUTNAME=CALTAPE
//INTERP.SYSIN_DD_*
TRANSFER_14969_15028
PHICENT_14969_15028_SBAND:-76_-164_-166_-33_-91_49
PHICENT_14969_15028_XBAND;38_-9_68_97_153_74
MULTIPLY_14969_15028_SBAND;0.644_0.647_0.754_0.686_0.817_0.830
MULTIPLY_14969_15028_XBAND;1.102_1.133_1.176_0.987_1.247_1.183
```

Note that PHICENT uses the determined values of  $\phi_S$  as input, then effectively multiplies each V' by exp (-i $\phi_S$ ) just as MULTIPLY multiplies V' by  $g_S$ .

Examining the INTSCRIB display of the results where the CPFU option was used, we see from Figure III-17 that the important amplitude calibrators are near 1000 CPFU and the phases are all close to zero. Finally, a simple INTSCRIB display of all the data, using the SORT option, allows us to examine the final amplitudes (A) and phases  $(\Phi)$  for each scan for all sources. Since everything appears normal, we can declare that all LL and RR correlators have been transformed to the state V = A exp  $(i\Phi)$  and one could begin doing science with the data.

The user may find it convenient to use one of the features of the program INTBCAL, which we will discuss in the next section, to determine the phase centers. We will discuss this as one of the uses of INTBCAL.

As before we can schematically represent the CORRTAPE to CALTAPE transformation as follows:

```
VERB PPI SUUPCE
                SCAN1 SCAN2 LST1
                                   LST2 SMASK XMASK
14969 15028 00 00 00 23 59 59 FFFF FFFF
PHICENT 14969 15028 SBAN01-76 -164 -166 -33 -91 49
PHICENT 13 14969 15028 00 00 00 23 59 59 FFFF 0000
PHICENT FACTUR(S) -0.21111 -0.45556 -0.46111 -0.09167 -0.25278 0.13611
PHICENT 16969 15028 XBAND138 -9 68 97 153 74
PHICENT 13 14069 15028 00 00 00 23 59 59 0000 FFFF
PHICENT FACTOR(S) 0,10550 -0,02550 0,18889 0,26964 0,42500 0,20556
MULTIPLY 14964 15U28 SHANDI 0.644 0.647 0.754 0.686 0.817 0.830 MULTIPLY 14 14969 15028 00 30 00 23 59 59 FFFF 0000 MULTIPLY FACTOR(S) 0.64000 0.4700 0.75600 3.68600 0.61700 0.83000
MULTIPLY 14969 15028 XBAND11.102 1.133 1.176 0.987 1.247 1.183 MULTIPLY 14 14969 15028 00 00 00 23 59 59 0000 FFFF MULTIPLY FACTOR(S) 1.10200 1.13300 1.17600 0.98700 1.24700 1.18300
EDIT CARD ORDER FOLLOWING SORT/MERGE STEP
(CARDS ARE RE-SORTED INTERNALLY, IN ORDER OF PRIORITY, AS NEEDED)
INTERFEROMETER EDITING PROGRAM - NRAD DUAL FREQUENCY INTERFEROMETER IS AND X BANDS) EDITING BEGINS AT 18 00 59 DN 04/05/73
INPUT FILE BEGINS AT HEADER 14969 LST 22 02 19 SIDEREAL DAY NO. 2448275
THE DONAME IS FT10F001
THE DSNAME IS HJELLMNG.CORR
THE UNIT MUMBER IS 133
THE VOLUMN SERIAL NUMBER IS 555555
THE DISPOSITION IS GLD
DCB PARAMETERS:
RECFM IS VB (VB=>VSB)
LRECL IS 204
BLKSIZE IS 2248
EDIT CARD TRANSFER
EDIT CARD PHICENT
EDIT CARD PHICENT
EDIT CARD MULTIPLY
EDIT CARD MULTIPLY
                      14969 15028 NDW ACTIVE AT SCAN 14969 N= 1
14969 15028 NDW ACTIVE AT SCAN 14969 N= 2
14969 15028 NDW ACTIVE AT SCAN 14969 N= 3
14969 15028 NDW ACTIVE AT SCAN 14969 N= 4
14969 15028 NDW ACTIVE AT SCAN 14969 N= 5
ALL EDIT CARDS READ AT SCAN 14969
THE DDNAME IS FT08F001
THE DSNAME IS SV573095.T173013.PF000.FIG16#18.CAL
THE UNIT NUMBER IS 136
THE VOLUMN SERIAL NUMBER IS 777777
THE DISPOSITION IS NEW
EDITING TERMINATED BY END OF INPUT FILE
EDIT SYNOPSIS:
TRANSFER PERFORMED ON 948 RECORDS
MULTIPLY PERFORMED ON 1766 RECORDS
PHICENT PERFORMED ON 1766 RECORDS
GETHOR WAS CALLED 66 TIMES
GETBL WAS CALLED 883 TIMES
GETBL WAS CALLED 1 TIMES
   O A-D RECORDS WERE PROCESSED
  1309 RECORDS READ FROM INPUT FILE
1009 RECORDS WRITTEN ON OUTPUT FILE
```

Fig. III-16. INTEDIT output describing the processing by which data are calibrated, to obtain the CALTAPE from the CORRTAPE.

										DATA F	UR CO	NFIGURAT	100	1-18-19								
SCAN	м	SJURCE	НА		PMS/100	AMP1K?	RPHI	AMP1L2	LPHI	AMP1F3	PPHI	AMP1L.	IH9,	AMP2R3	1H99	AMP 2L 3	LPHI	MREC	TPOWER	ι	ST	
14970	SO	3C46	-33	19	000000	975	9	996	9	1005	7	1005	6	1031	4	1041	3	7	655665	22	16	15
14973					000000	1032	-5	1011	-4	1047	-7	1018	-7	1019	2	1052	2		656665		45	
14980					000000	898	3	964	7	955	3	955	3	983	5	988	4		666666		55	
1+184					990000	943	6	962	7	911	5	896	4	974	4	943	3		656665		36	
14986					000000	1077	4	993	5	1111	-0	1058	-0	1044	5	1036	5		655665		56	
14967					000000	1003	-3	1003	- 7	997	-11	1000	-11	1029	3	1028	3		555665		05	
14988					000000	915	- 9	1001	-9	1007	-9	994	-10	1014	1	1026	o		655665		15	
14991					0202	976	9	1921	10	1066	3	1032	4		ō	1010	õ		655665		45	
		NRAU14U			000000	935	-4	1012	-3	1011	-7	985	-7	1031	3	1013	4		656665		06	
14998					000000	898	-4	261	-3	951	-8	958	-8	995	5	986	4		656665		56	
15300			-04			1040	4	986	4	1015	-1	978	-1	1015	5	1002	5		655665		16	
15 30 6					000000	955	5	436	6	916	î	933	o	939	5	942	5		666665		15	
15010			-00			975	-1	969	ő	965	-2	942	-3	988	4	976	5		666665		56	
15 )11					000000	1003	6	987	7	1024	-1	978	-1	1005	6	962	6		655665		06	
15013			-00			965	13	270	14	968	7	429	7	966	5	949	5		566665		26	
15014					000000	991	-1	977	-0	1051	-4	1004	-4	1026	3	1026	3		555665		36	
		P1116+12			200000	1102	9	1077	9	1101	9	1102	11	1165	-2	1164	-1		666666		45	
		P1110+12			000000	1141	0	1041	0	1147	1	1064	0	1088	-1	1076	-2		655655		36	
15021					303003	1036	-4	1021	-4	992	-6	965	-6	1308	5	966	4		665665		47	
15022					300000	1001	14	963	15	997	9	963	9	999	5	990	5		555665		05	
15328			-04				o.	975	-4		ú	1026	-4		ó	1027	-1		550665		15	
14970					000000	1040	25	1005	22	992	17	1045	16	1018	6	1003	i		660666		16	
14973					000000	1225	- B	1129	- 8	1090	-14	1072	-15	1100	2	1110	2		566666		47	
14980					000000	943	23	927	21	912	13	950	11	931	9	918	9		666666		56	
14984		JC48			000000	1107	25	1038	23	907	16	964	14	923	6	970	7		665656		36	
14906					000000	1188	23	1053	27	1110	13	1107	13	1061	13	1112	14		665666		56	
14937					000000	1170	-20	1113	-21	1105	-30	1193	-31	1126	9	1134	8		665656		05	
14980					000000	1102	-28	1123	-31	1049	-28	1113	-29	1088	-1	1032	-2		605666		16	
14991					000000	1046	27	1011	26	985	11	1002	11	1103	15	1057	16		665666		48	
		NRAU14J	-01			1045	-7	1046	-9	905	-18	980	-19	974	9	972	10		665656		30	
14998					000000	1018	5	938	2	942	-9	995	-11	998	12	1006	13		665666		56	
15 100			-02			1127	18	1039	16	1050	4	1078	2	978	12	1043	13		665666		16	
15006					000000	1092	19	997	16	928	3	987	2	826	15	895	14		666665		16	
15010					000000	925	-2	847	-3	828	-9	844	-11	623	7	838	7		776776		56	
15011					000000	1053	34	962	32	946	13	935	13	956	18	981	17		676656		06	
15013					000000	1034	27	935	25	892	8	920	9	860	15	887	15		666666		26	
15014					000000	1173	2	1098	0	1142	-9	1147	-10	1092	11	1120	12		665666		34	
		P1110+12			000000	1412	22	1312	19	1200	28	1185	29	1362	-5	1311	-4		676676		46	
		P1110+12			000000	1425	2	1250	2	1323	6	1263	5	1218	-3	1208	-1		665666		36	
15021					000100	1011	-9	922	-10	911	-14	925	-14	913	7	952	6		664666		47	
15022					000000	1094	46	1035	44	971	30	982	28	909	12	953	13		566666		05	
15028					0 0 0	1181	-19	-000	0	1127	-16	,,,,	0	1058	-4		. 0		556665		15	
.,,,,,		2000											~					•	2,0003	.,	1	70

Fig. III-17a. First part of INTSCRIB display, with PARM='CPFU, PLOT, NOGRID, RANGE=2000', of the scan average of calibrators on the CALTAPE.

END

	RHAND AMPLIT PLOT RANGES FOR A	UDES AND PHASES FOR CONFIGURATION 1-1 MP: 0 -> 2000 PER SYMBOL, PHASE: -18	8-19	
14970 3C48 1 14973 3C119 1 14980 3C48 1 14984 3C40 1	PA A P	+	PA X X X X	IS 22 16 IS 22 45 IS 23 55 IS 00 36
14936 3C147   1 14937 3C119   1 14933 CTA21   1 14941 3C413   1 14993 NRA0140   1	PA PA AP AP	I P A I I P A I I P A I I P A I I P A X I P A X	X PA X	IS 00 56 IS 01 05 IS 01 15 IS 01 45 IS 02 06
14998 3C48 1 15000 3C147 1 15-06 3C119 1 15010 3C138 1	A P PA A P X	1	X AP AP X	IS 02 56 IS 03 16 IS 34 15 IS 64 56
15011 3C48   1 15013 3C147   1 15014 0A257   1 15015 P1116+12   1 15020 P1116+12   1	AP A D X PA P A	I X I I A P I I P A I I P A I I P A I I P A I I	AP X P A P A	15 05 06 15 05 26 15 05 36 15 05 45 15 06 36
15021 3C138 I 15022 3C147 I 15028 3C286 X 14970 3C48 I 14973 3C119 I	PA AP AP	I PA I I X X X X I A P I I P A I I	AP PPA	15 06 47 15 03 05 1 39 15 1x 22 16 1x 22 47
14980 3C43 I 14784 3C43 I 14986 3C147 I 14987 3C119 I 14988 CTA21 I	A P AP X P A	I A P I I I P A I I P A I I P A I I	Δ P A P X PA P A	1x 23 56 1x 00 36 1x 00 56 1x 01 05
14591 3C418 I 14993 NRA0140 I 14998 3C48 I 15300 3C147 I	A P P A X X	I AP I I X I I X I I X I I X I I X I I X I I X I I X I I X I I X I I X I I X X I I X	AP AP AP	1x 31 16 1x 31 46 1x 32 06 1x 32 56 1x 33 16
15006 3C119	AP AP AP PA	I AP I I A P I I A P I I A P I I A P I I I A P I I I A P I I I P A I I I I	A P A P A P P P A	1x 04 16 1x 04 56 1x J5 06 1x 05 26 1x 05 36
15015 P1116+12 I 15020 P1116+12 I 15021 3C138 I 15022 3C147 I 15028 3C246 I SCAN SUURCE HA +	P A P A PA A P PA PA A P PA	I PA I I P A I I AP I I A P I I P A I	P A P A P P A P P A P P A P P A P P A P P A P P A P P A P P A P P A P A P P A	1x 05 46 1x 06 36 1x 06 47 1x 08 05 1 09 15
14970 3C48 I 14973 3C119 I	PLOT RANGES FOR A+CORR-+-1L2L+AP X	UDES AND PHASES FOR CONFIGURATION 1-1 MP: 0 -> 2000 PER SYMBOL, PHASE: -18 +	0 -> +180 	IS 22 10 IS 22 4
14980 3C48 I 14984 3C48 I 14984 3C48 I 14986 3C147 I 14987 3C119 I 14988 CTA21 I	А Р А Р X РА РА	I AP I I AP I I PA I I PA I I PA I I	AP X PA X	15 22 45 15 23 55 15 00 36 15 00 56 15 01 05 15 01 15
14991 3C418 I 14993 NRAD140 I 14996 3C48 I 15000 3C147 I 15006 3C119 I	AP X AP X	I PA X I PA I I X I I AP I	X X X AP	IS 01 45 IS 02 06 IS 02 56 IS 03 16 IS 04 15
15010 3C138 I 15011 3C48 I 15013 3C147 I 15014 0A267 I 15015 P1116+12 I	AP A P X X	I AP I I X I I A P I I X I I X I I X I I X I I X I I X I I X I I X I I X I I X I X I I X X I X I X I X X I X I X X I X I X X I X I X X I X X I X X I X	Х АР АР РА Р А	15 04 56 15 05 06 15 05 26 15 05 36 15 05 45
15020 P1116+12 I 15021 3C138 I 15022 3C147 I 15023 3C286 I 14970 3C48 I	PA X A P X A P	I PA I I X I I X I I X I I X I I X I I X I I X I I X I I X I I X I I X I I X I I X I X I X I X X I I X	PA AP X PA AP	IS 06 36 IS 06 47 IS 08 05 I 09 15 IX 22 16
14973 3C119 I 14980 3C48 I 14984 3C48 I 14986 3C147 I 14987 3C119 I	P A A P A P A P	I P A I I A P I I I A P I I I P A I I P A I	P A A P A P P A P A P P A P A P A P A P	1X 22 47 1X 23 56 1X 00 36 1X 00 56 1X 01 05
14988 CTA21 I 14991 3C418 I 14993 NRAU140 I 14998 3C48 I 15000 3C147 I	P A P A A A A A A A A A A A A A A A A A	I P Λ I I AP I I I P A I I P A I I P A I I I P A I I I P A I I P	PA AP AP AP X	IX 01 16 IX 01 48 IX 02 06 IX 02 56 IX 03 16
15006 3C119 I 15010 3C138 I	A P	I X I I I I I I I I I I I I I I I I I I	A P A P	1X 04 16 1X 04 50
15011 3C48 I 15013 3C147 I 15014 DA267 I 15015 P1116+12 I	A P A P P A	I AP I I AP I I I AP I I I I I I I I I I	A P A P PA	1x 05 06 1x 05 26 1x 05 36 1x 05 46

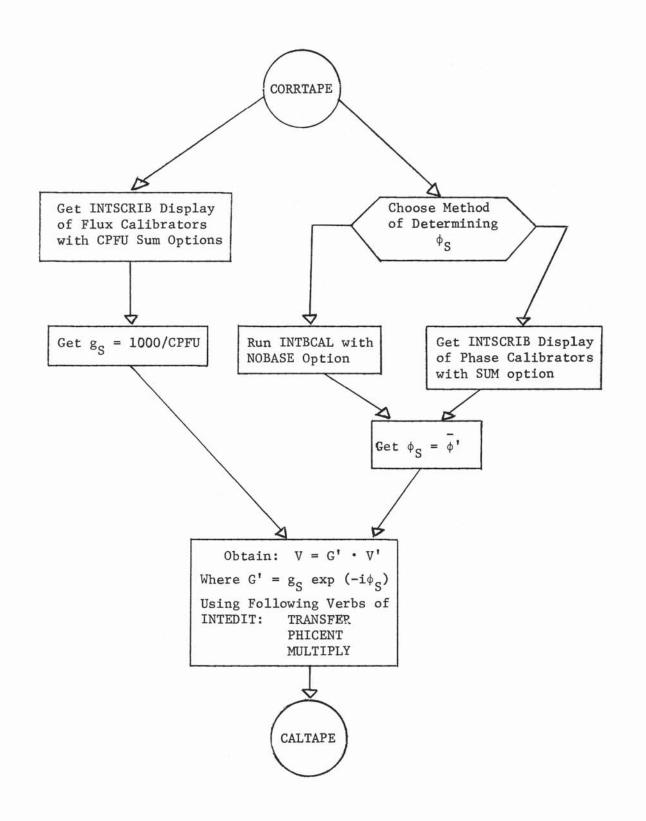
Fig. III-17b. Second part of the INTSCRIB display, with PARM='CPFU,PLOT,NOGRID, RANGE=2000', of the scan averages of calibrators on the CALTAPE.

				D	ATA FO	R CON	FIGURAT	ION	1-18-19					
SCAN M SOURCE 14969 SD P0056-17	HA RMS/100	AMPIRZRPHI 643 -6	714	PHI A	MP1R3R	-3	711	LPHI	AMP2R3 823	RPHI	812	LPHI	NREC TPOWER 8 665665	LST 22 06 07
14979 SD P0056-17 15003 SD P0056-17 14969 XD P0056-17 14979 XD P0056-17 15003 XD P0056-17	-01 12 000000 02 49 000000 -02 51 000000 -01 11 000000 02 49 000000	700 2 628 9 110 0 128 39 155 15	660 666 140 144 202	1 8 0 34 33	705	5 7 -13 39 24	632 618 100 113 161	5 9 0 45 30	847 832 200 131 245	-7 -4 -3 -9 12	785 772 136 116 177	-7 -4 -17 -31 -16	9 655665 8 655665 7 666666 9 776777 3 666666	23 45 18 03 47 08 22 06 07 23 45 48 03 47 08
14970 SO 3C48 14980 SO 3C48 14984 SD 3C48 14998 SO 3C48 15011 SO 3C48 14970 XD 3C48 14980 XD 3C48 14984 XD 3C48 14988 XD 3C48 15011 XD 3C48	-03 19 000000 -01 40 000000 -00 59 000000 01 20 000000 -03 19 000000 -01 39 000000 -00 59 000000 01 20 000000 03 30 000000	9137 10 8410 8 8826 8 8292 -9 9101 -3 3175 20 2877 18 3411 21 3064 -21 3144 3	9060 8787 8771 8751 8969 3203 2957 3355 3147 3069	7 7 -10 -3 18 17 20 -22	9076 8640 8273 8537 9114 3294 3041 3046 3123 3115	6 -11 -7 11 11 14 -25 -7	9216 8768 8250 8799 8938 3326 3031 3102 3185 3029	6 -11 -8 11 9 14 -25 -6	9182 8797 8721 8876 8908 3319 3066 3076 3306 3169	5 4 3 2 4 10 9 6 3 10	9299 8870 8529 8863 8795 3232 2977 3179 3256 3184	5 4 3 2 3 9 6 4 10	7 655665 6 666666 7 656665 7 656665 7 656665 7 666666 6 666666 6 665666 7 665666 4 676666	22 16 15 23 55 48 00 36 30 02 56 21 05 06 22 22 16 45 23 56 18 00 36 30 02 56 51 05 06 55
14971 SD D0224+67 14985 SD D0224+67 14999 SD D0224+67 15012 SD D0224+67 14971 KD D0224+67 14985 KD D0224+67 14999 KD D0224+67 15012 KD D0224+67	-04 01 000000 -01 40 000000 00 38 000000 02 49 000000 -01 40 000000 00 39 000000 02 50 000000	1030 18 1222 13 1081 9 1016 10 1732 50 1945 32 1831 23 1700 29	1125 1154 1114 1063 1850 1869 1825 1716	14 9 9 52 33 25	1118 1127 1082 1086 1719 1873 1787	10 7 4 6 29 16 15 18	1052 1146 1043 1074 1766 1949 1796 1882	6 5 5 31 16 17 20	1237 1166 1200 1210 1777 1696 1650 1737	6 6 2 1 20 16 9	1154 1167 1111 1160 1751 1888 1736 1697	9 6 3 2 19 17 8	9 555665 10 555665 9 655665 12 555665 5 666666 5 665666 3 666666	22 25 24 00 45 41 03 05 19 05 15 43 22 26 30 00 46 26 03 06 25 05 16 58
14972 SD NRAU91 15005 SD NRAU91 14972 XD NRAU91 15005 XD NRAU91	-03 26 000000 02 02 000000 -03 26 000000 02 03 000000	3727 6 3690 -4 2600 9 2619 -13	3979 3859 2781 2704	-4	4016 3695 2819 2578	5 -5 8 -13	3972 3845 2772 2697	-5 9 -14	3951 3840 2790 2862	1 0 2	3970 3810 2710 2804	1 0 3	7 655665 7 655665 7 666666 7 666666	22 36 23 04 05 57 22 36 53 04 06 27
14973 SD 3C119 14987 SD 3C119 15006 SD 3C119 14973 XD 3C119 14987 XD 3C119 15006 XD 3C119	-05 44 000000 -03 24 000000 -00 14 000000 -05 43 000000 -03 24 000000 -00 14 000000	5807 -3 5622 -2 5215 3 2493 -9 2420 -10 2161 6	5526 5492 5095 2402 2416 2110	-2 3 -8 -10		-7 -6 -1 -19 -21 -3	5605 5542 5120 2280 2583 2111	-7 -6 -1 -19 -22 -2	5453 5553 4999 2394 2516 1828	4 4 8 12 10	5646 5571 5068 2392 2482 1925	4 4 3 8 12 9	11 656665 9 555665 7 666665 4 666666 8 665666 7 666666	22 45 48 01 05 51 04 15 56 22 47 00 01 05 51 04 16 26
14974 SD P2149-28 14981 SD P2149-28 14974 XD P2149-28 14981 XD P2149-28	01 06 000000 02 15 000000 01 07 000000 02 15 000000	1944 4 1838 -26 870 1 880 -91	810		869	10 -20 30 -73	1906 1904 836 785	-20 25 -68	1933 1939 1002 895	-7 -6 -17 -16	1963 1881 955 819	-7 -6 -18 -18	4 665665 10 666666 4 666666 5 776676	22 57 25 00 06 20 22 57 55 00 06 20
14975 SD 0V080 14975 XD 0V080	03 17 000000 03 17 000000	1349 -7 1024 -26	1298 974	-7 -27	1360 956	-0 -16	1300 965	-1 -16	1338 947	-6 -7	1249 912	-7 -4	10 655665 5 665666	23 05 55 23 06 40
14976 SD BLLAC 14976 XD BLLAC	01 14 000000 01 14 000000	6560 1 7075 5	5910 6668		5960 6801	-0 3	5860 6544	0	6029 6380	0	5920 6730	0	8 666665 6 665666	23 15 57 23 15 57
14977 SD 3C454.3 14990 SD 3C454.3 14997 SD 3C454.3 15004 SD 3C454.3 14977 XD 3C454.3 14990 XD 3C454.3 14997 XD 3C454.3 15004 XD 3C454.3	00 32 000000 02 43 000000 03 52 000000 05 02 000000 00 33 000000 02 44 000000 03 52 100000 05 04 001000	10154 -4 9458 2 10581 4 11174 -3 11622 12 12333 19 13268 9 13976 -9	10176 10777 10758 10813 11616 13664 13616 13755	2 1/ 3 1 -3 1 11 1 19 1 8 1	0186 0742 1030 1293 1181 3590 3846 3607	-3 1 2 -6 15 17 6	10209 10952 10779 10982 11100 13733 13174 13360	-4 1 2 -5 15 17 6 -11	10540 10371 11140 11582 11518 13870 14200 14748	-1 1 1 -4 1 -0 -6	10391 10790 10910 10895 11450 13644 13781 14587	-1 0 2 -4 1 -1 5	8 655665 10 655665 12 655665 12 666666 7 666666 4 665666 3 666666 2 666666	23 25 35 01 35 53 02 45 25 03 55 36 23 26 27 01 37 01 02 45 25 03 57 28
SCAN M SQURCE	HA RMS/100	AMP1R2RPHI	AMPIL2L		MP1R3RI		AMP 1L 3		AMP2R3				NREC TPOWER	LST
SCAN M SOURCE 14978 SD PO114-21 14983 SD PO114-21 14989 SD PO114-21 14978 XD PO114-21 14983 XD PO114-21 14989 XD PO114-21	HA RMS/100 -01 39 000000 -00 48 000000 00 10 000000 -01 39 000000 -00 48 000000 00 10 000000	AMPIRZRPHI 2163 15 2396 -23 2350 0 660 2 784 -46 766 -12	2207	14 -22	2192	20 -15 5 20 -27	AMP 1L 3 2180 2233 2258 592 760 771	21 -15 5 22 -27	2248 2332 2382 651 765 836	-5 -8 -6 -21 -17 -15	2258 2261 2291 588 765 800	-5 -8 -6 -18 -20 -18	8 655665 6 555665 8 655665 7 776777 6 665666 7 665666	LST 23 36 05 00 26 41 01 26 05 23 36 05 00 27 11 01 26 05
14978 SD P0114-21 14983 SD P0114-21 14989 SD P0114-21 14978 XD P0114-21 14983 XD P0114-21	-01 39 000000 -00 48 000000 00 10 000000 -01 39 000000 -00 48 000000	2163 15 2396 -23 2350 0 660 2 784 -46	2207 2206 2290 631 777	14 -22 -1 5 -44 -9	2192 2338 2310 639 764	20 -15 5 20 -27	2180 2233 2258 592 760	21 -15 5 22 -27	2248 2332 2382 651 765	-5 -8 -6 -21	2258 2261 2291 588 765	-5 -8 -6 -18 -20	6 655665 6 555665 8 655665 7 776777 6 665666	23 36 05 00 26 41 01 26 05 23 36 05 00 27 11
14978 SD P0114-21 14983 SD P0114-21 14989 SD P0114-21 14978 XD P0114-21 14983 XD P0114-21 14989 XD P0114-21 14982 SD CYGX-3	-01 39 000000 -00 48 000000 00 10 000000 -01 39 000000 -00 48 000000 00 10 000000	2163 15 2396 -23 2350 0 660 2 784 -46 766 -12	2207 2206 2290 631 777 851	14 -22 -1 5 -44 -9 10 35 11 11 6 13 11 7 10 10 11 11 11 11 11 11 11 11 11 11 11	2192 2338 2310 639 764 800	20 -15 5 20 -27 3	2180 2233 2258 592 760 771 3812	21 -15 5 22 -27 3	2248 2332 2382 651 765 836	-5 -8 -6 -21 -17 -15	2258 2261 2291 588 765 800	-5 -8 -6 -18 -20 -18	8 655665 6 555665 8 655665 7 776777 6 665666 7 665666	23 36 05 00 26 41 01 26 05 23 36 05 00 27 11 01 26 05 00 16 28
14978 SD P0114-21 14983 SD P0114-21 14989 SD P0114-21 14978 XO P0114-21 14983 XO P0114-21 14983 XO F0114-21 14982 XD CYGX-3 14982 XD CYGX-3 14982 XD CYGX-3 14982 XD CYGX-3 14984 SD 3C147 15000 SD 3C147 15000 XD 3C147 15000 XD 3C147 15000 XD 3C147	-01 39 00000 -00 48 000000 00 10 000000 -01 39 000000 00 10 000000 03 45 000000 03 46 000000 -04 43 000000 -02 24 000000 02 24 000000 02 24 000000 -04 43 000000 -02 23 000000 -02 23 000000 -00 14 000000 -00 13 000000	2163 15 2396 -23 2350 0 660 2 784 -46 766 -12 3911 10 2180 35 14199 11 13457 6 13258 13 12587 7 5536 39 5109 17 4653 23	2207 2206 2290 631 777 851 3844 2099 12838 12643 12425 12371 5163 4987 4762 4883	14 -22 -1 5 -44 -9 10 35 11 13 13 11 7 10 10 10 11 12 13 14 14 16 17 18 18 18 18 18 18 18 18 18 18	2192 2338 2310 639 764 800 3949 2178 4195 2833 2509 5674 4427 4737 5068	20 -15 5 20 -27 3 7 28 4 1 8 5 21 4 8	2180 2233 2258 592 760 771 3812 2097 13725 12662 11958 12362 5403 5221 4504	21 -15 5 22 -27 3 8 28 4 1 7 5 5 22 -27 3	2248 2332 2382 651 765 836 3940 2121 13215 12752 12091 12486 5344 4872 4336	-5 -8 -6 -21 -17 -15 1 6 7 5 4 2 19 12 14	2258 2261 2291 588 765 800 3790 2108 13181 12710 11988 12474 5519 5101 4375	-5 -8 -6 -18 -20 -18 0 8 7 5 4 2 20 13 14	8 655665 6 555665 7 776777 6 655665 7 665666 8 655665 7 65665 7 65665 7 65666 7 65666 7 66666	23 36 05 00 26 41 01 26 05 00 27 11 01 26 05 00 17 43 00 16 28 00 17 43 00 56 31 03 56 02 08 05 25 00 56 46 03 16 33 05 26 03
14978 SD P0114-21 14988 SD P0114-21 14989 SD P0114-21 14978 XD P0114-21 14983 XD P0114-21 14983 XD P0114-21 14982 XD CYGX-3 14982 XD CYGX-3 14982 XD CYGX-3 14982 XD CYGX-3 14982 XD CYGX-3 15003 SD SC147 15003 SD SC147 15022 SD SC147 15022 SD SC147 15023 XD SC147 15030 XD SC147	-01 39 00000 -00 48 000000 00 10 000000 -01 39 000000 00 10 000000 03 45 000000 03 46 000000 -04 43 000000 -02 24 000000 -02 24 000000 -04 43 000000 -05 14 000000 -06 43 000000 -07 24 000000 -08 25 000000 -09 13 000000 -02 21 000000 -02 22 000000	2163 15 2396 -23 2350 0 600 2 784 -46 766 -12 3911 10 2180 35 14199 11 13457 6 12328 13 12587 7 5536 39 1755 23 4859 23	2207 2206 2290 631 777 851 3844 2099 1283 1245 1251 1251 1271 4883 5079 4151	14 -22 -1 5 -44 -9 10 35 11 11 12 6 11 13 1 13 1 10 18 24 24 -5 -25 -25 -25 -25 -25 -27 -27 -27 -27 -27 -27 -27 -27	2192 2338 2310 639 764 800 3949 2178 4195 2833 2143 21509 5674 5674 4427 4737 5068 1831	20 -15 5 20 -27 3 7 28 4 1 8 5 21 4 8 17	2180 2233 2258 592 760 771 3812 2097 13725 12662 11958 12362 5403 5221 4504 4818	21 -15 5 22 -27 3 8 28 4 1 7 5 22 -27 3	2248 2332 2382 651 765 836 3940 2121 13215 12752 12091 12466 5344 4872 4376 4376 4376 5049	-5 -8 -6 -21 -17 -15 1 6 7 5 4 2 19 12 14 4	2258 2261 2291 588 765 800 3790 2108 13181 12710 11988 12474 5519 5101 4375 4702	-5 -8 -6 -18 -20 -18 0 8 7 5 4 2 20 13 14 6	8 655665 6 555665 7 776777 6 655666 7 665666 8 655665 7 665665 7 665665 7 665665 7 665665 7 665665 7 665666 8 655665	23 36 05 00 26 41 01 26 05 23 36 05 00 27 11 01 26 05 00 17 43 00 17 43 00 16 28 00 17 43 00 26 02 00 8 05 25 00 3 16 33 05 26 22 00 56 46 03 16 33 05 26 32 08 05 57
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Fig. III-18. INTSCRIB display, with PARM='LIST,SORT', of the scan averages, sorted in order of frequency, for all the data on the CALTAPE.

```
HA RMS/100 AMPIRZRPHI AMPILZLPHI AMPIRZRPHI AMPILZLPHI AMPZRZRPHI AMPZLZLPHI NREC TPOWER LST
 SCAN M SOURCE
                                                   2592 -2 2373 -3 2319 -9 2363 -11
2631 -9 2583 -10 2551 -14 2590 -14
15010 XD 3C138
15021 XD 3C138
                            -00 23 000000
01 28 000000
                                                                                                                          2305 7 2347 7 6 776776 04 56 26
2557 7 2666 6 5 666666 06 47 36
                                                                                                                          4927 3
11687 11
15014 SD DAZ67
15014 XD DAZ67
                                                 4760 -1 4690 -0
12558 2 11749 0
                                                                                       5049 -4
12228 -9
                                                                                                        4820 -4
12282 -10
                                                                                                                                              4939 3 7 555665 05 36 30
11988 12 6 665666 05 36 30
15015 50 P1116+12
15020 50 P1116+12
15015 KD P1116+12
15020 KD P1116+12
                            -05 31 000000
-04 41 000000
-05 31 000000
-04 41 000000
                                                   1874 9
1940 0
1695 22
1711 2
                                                                                                           1874
1810
1422
1516
                                                                                                                    11
0
29
5
                                                                                                                             1980
1850
1635
1462
                                                                                                9
1
28
6
                                                                                                                                     -2
-1
-5
-3
                                                                              9
0
19
2
                                                                                                                            3391 -5
3925 -17
15016 SD P1055+01
15016 XD P1055+01
                           -05 01 000000
-05 01 000000
                                                   3494 -28
3942 -78
                                                                      3095 -28
3409 -80
                                                                                       3441 -23
3453 -62
                                                                                                          3230 -23
3358 -64
                                                                                                                                                3361 -5 12 666666 05 55 33
3939 -16 5 666666 05 55 33
                                                                      2775 -9
2013 -33
                                                                                                          2718 -5
1897 -18
15017 SD P0859-14
15017 XD P0859-14
                            -02 55 000000 2536 -10
-02 54 000000 1966 -34
                                                                                      2790 -5
1839 -16
                                                                                                                                                2853 -6 8 655665 06 05 43
2043 -17 8 666666 06 06 13
                                                                       939 -58
                                                                                       984 176
                                                                                                           938 -60 0
                                                                                                                                               1025 1 17 555665 08 31 51
0 17 555665 08 31 51
15023 H 1216+48
15023 H 1216+48
                            1115 24
                                                                                                           1079 20
                                                                                                                                                1280 2 14 555665 08 40 33
0 14 555665 08 40 33
15024 M 1242+41 -04 02 0 0 0
15024 M 1242+41 -04 02 0 0 0
15025 M 1244+49
15025 M 1244+49
                            -03 57 0 0 0
-03 57 0 0 0
                                                                       753 152
0
                                                                                                                                                 844 -6 14 555665 08 48 35
0 14 555665 08 48 35
                                                   193 108
                                                                                         225 117
                                                                                                                              455 -20
                                                                       494 24
15026 H 1315+34
15026 H 1315+34
                                                                                                            522 20
                                                                                                                                                519 4 17 555665 08 57 27
0 17 555665 08 57 27
                                                                      438 -2
0
                                                                                                            333 2
15027 M 1317+52
15027 M 1317+52
                            -04 11 0 0 0 0 0 0 -04 11 0 0 0 508 54
                                                                                                                                                997 12 13 555665 09 06 45
0 13 555665 09 06 45
                            -04 14 0 0 0 0 9847 -4 0 10363 -4
-04 14 0 0 0 6144 -19 0 5861 -16 0
                                                                                                                            0 10380 -1 17 556665 09 15 48
5501 -4 0 17 556665 09 15 48
15028 H 3C286
15028 H 3C286
END
```

Fig. III-18 continued.



#### (b) INTBCAL

#### (1) Determination of Baselines

Most of the time, the user need not worry about baseline calibration because NRAO staff will always determine the appropriate corrections after each telescope move. However, occasionally the user may want to determine them himself because he needs better than average phase calibration. In addition, the user should be aware of what is involved because, at the very least, some residual phase errors in his data will be due to imperfections in the assumed baselines.

A program called INTBCAL is used to determine accurate baselines. Using data for all LL and RR correlators, it takes phase calibrator data at the stage where the visibility function is described by

$$g_D^g g_A^g A'' \exp [i(\phi'' + \Delta \phi_P + \Delta \phi_C)]$$

so the final calibrated phase,  $\Phi,$  differs from  $\phi''$  +  $\Delta \phi_P$  +  $\Delta \phi_C$  such that

$$\Phi = \phi'' + \Delta \phi_P + \Delta \phi_C + \Delta \phi_B - \phi_S + NOISE.$$

Since, for calibrators observed at the reference position,  $\Phi$  = 0, one solves for  $\Delta \phi_B$  =  $2\pi$   $\Delta B$  •  $\infty$  and  $\phi_S$ , in a least squares sense, using the equation

$$\phi'' + \Delta \phi_P + \Delta \phi_C + 2\pi \Delta B \cdot S_O - \phi_S + NOISE = 0$$
 III-(13)

The program INTBCAL that performs this least squares solution is controlled by INCLUDE/EXCLUDE cards and requires input in the form of scan averaged phases. There are a number of PARM options that can be used, the most important of which are PARM='NOK', and PARM='NOBASE'. Under circumstances requiring exceptional accuracy, one includes in Equation III-(13) the so-called k, & and m terms which correct for errors introduced by telescope geometry (see Wade, C. M., Ap. J., 162, 381, 1970). We will, however, discuss only the case where determination

of  $\triangle_X^B = (\triangle_X^B, \triangle_y^B, \triangle_z^B)$  and  $\phi_S$  are sufficient. For further details consult the Users Guide.

To illustrate the use of INTBCAL, let us apply it to the phase calibrators used in the scan range 14969-15028 that we have been using in our examples. Because most of the sources are phase calibrators, we can determine baselines using the following program:

```
//_EXEC_INTAVG,INTAPE=3086,INNAME=CORRTAPE
//SYSIN_DD_*
INCLUDE_14969_15028
EXCLUDE_1216+48
EXCLUDE_1242+41
EXCLUDE_1244+49
EXCLUDE_1315+34
EXCLUDE_1317+52
//_EXEC_INTBCAL,PARM='NOK'
//SYSIN_DD_*
INCLUDE
```

(results shown in Figures III-19-24)

Under most circumstances one simply uses an INCLUDE card for every good phase calibrator observed. In this case we have excluded the few

sources that are not standard phase calibrators.

Note that INTBCAL requires the input of the scan averages calculated by INTAVG. The resulting output from INTBCAL contains all the information needed to evaluate the solution obtained. As seen in Figure III-19, one first gets a listing of the original baselines which we will need to correct. The solutions for  $\Delta B_x$ ,  $\Delta B_y$ ,  $\Delta B_z$ , the baseline corrections, the improved baselines, the phase centers ( $\phi_S$ ) and the rms fits of the solution are then printed out for all correlators and all frequencies (Figures III-20 and 21). Because the RR and LL correlators

# INITIAL BASELINES ARE AS FOLLOWS:

		вх	ВҮ	BZ	K
SBAND	BL12	-4785.5898	-15086.9443	6421.5098	0.0
	BL13	-4533.3594	-14292.7246	6083.5498	0.0
	BL23	-252.2295	-794.2197	337.9600	0.0
	42FT	40491.0791	74762.6895	-55965.2793	58.7998
XBAND	BL12	-14356.7695	-45260.8330	19264.5293	0.0
	BL13	-13600.0781	-42878.1738	18250.6494	0.0
	BL23	-756.6385	-2382.6592	1013.8799	0.0
	42FT	121473.2373	224288.0684	-167895.8379	0.0

Fig. III-19. First part of INTBCAL output showing the initial baselines before solution is obtained from phase calibrator data on the CORRTAPE (PAC only).

BASELINE PARAMETERS FOR 85-1.2 S RR

THREE SOLUTION FIT PARAMETERS ARE 1.2699 136.8572 1.2699. SOLUTION 3 CHOSEN.

YTITMAUP	CHANGE	NEW VALUE	ERROR	
PHASE CENTER	-73.	-73.	4.	DEGREES
BX	-0.0100	-4785.5998	0.0155	
84	0.0259	-15086-9184	0.0062	
BZ	0.0251	6421.5349	0.0086	
K	0.0	0.0	0.0244	
L	0.0	0.0	0.0244	
H	0.0	0.0	0.0244	

BASELINE PARAMETERS FOR 85-1.2 S LL

THREE SOLUTION FIT PARAMETERS ARE 112.4070 1.2128 1.2127. SOLUTION 3 CHOSEN.

QUANTITY	CHANGE	NEW VALUE	ERROR	
PHASE CENTER	-161.	-161.	4.	DEGREES
BX	-0.0089	-4785.5988	0.0150	
ву	0.0268	-15086-9175	0.0059	
82	0.0262	6421.5359	0.0084	
K	0.0	0.0	0.0236	
K.	0.0	0.0	0.0236	
M	0.0	0.0	0.0236	

BASELINE PARAMETERS FOR 85-1.3 S RR

THREE SOLUTION FIT PARAMETERS ARE 112.9693 1.0724 1.0725. SOLUTION 2 CHOSEN.

YTITMAUP	CHANGE	NEW VALUE	ERROR	
PHASE CENTER	-163.	-163.	4.	DEGREES
ВX	-0.0076	-4533-3670	0.0142	
BY	0.0167	-14292.7080	0.0057	
BZ	0.0039	6083.5537	0.0079	
K	0.0	0.0	0-0224	
L	0.0	0.0	0.0224	
4	0.0	0.0	0.0224	

BASELINE PARAMETERS FOR 85-1.3 S LL

THREE SOLUTION FIT PARAMETERS ARE 1.1264 1.1264 SOLUTION 3 CHOSEN.

O11117174	russär.		500.00	
QUANTITY	CHANGE	NEW VALUE	ERROR	
PHASE CENTER	-29.	-29.	4.	DEGREES
BX	-0.0100	-4533.3694	0.0144	
BY	0.0179	-14292-7068	0.0057	
8 Z	0.0016	6083.5514	0.0081	
K	0.0	0.0	0.0228	
L	0.0	0.0	0.0228	
M	0.0	0.0	0.0228	

BASELINE PARAMETERS FOR 85-2+3 S RR

THREE SOLUTION FIT PARAMETERS ARE 0.0492 0.0480 0.0492. SOLUTION 2 CHOSEN.

YTITMAUQ	CHANGE	NEW VALUE	ERROR
PHASE CENTER	-93.	-93.	1. DEGREES
BX	0.0043	-252.2251	0.0031
BY	0.0077	-794.2120	0.0013
BZ	0.0233	337-9833	0.0017
K	0.0	0.0	0.0048
L	0.0	0.0	0.0048
м	0.0	0.0	0.0048

BASELINE PARAMETERS FOR 85-2,3 S LL

THREE SOLUTION FIT PARAMETERS ARE 0.0478 0.0478 0.0478. SOLUTION 3 CHOSEN.

QUANTITY	CHANGE	NEW VALUE	ERROR
PHASE CENTER	47.	47.	1. DEGREE
BX	0.0028	-252.2266	0.0031
BY	0.0074	-794-2124	0.0012
BZ	0.0240	337.9840	0.0017
K	0.0	0.0	0.0047
L	0.0	0.0	0.0047
4	0.0	0.0	0.0047

Fig. III-20. Part of INTBCAL output showing the properties of the solutions for SBAND correlators.

BASELINE PARAMETERS FOR 85-1,2 X RR

THREE SOLUTION FIT PARAMETERS ARE 9.4462 9.4462 313.5977. SOLUTION 2 CHOSEN.

QUANTITY	CHANGE	NEW VALUE	ERROR	
PHASE CENTER	45.	45.	11.	DEGREES
BX	0.0011	-14356.7685	0.0423	
BY	0.0744	-45260.7586	0.0167	
BZ	0.0815	19264.6108	0.0247	
K	0.0	0.0	0.0666	
L	0.0	0.0	0.0666	
H	0.0	0.0	0.0666	

BASELINE PARAMETERS FOR 85-1,2 X LL

THREE SOLUTION FIT PARAMETERS ARE 9.4178 48.6568 39.5340. SOLUTION 1 CHOSEN.

QUANTITY	CHANGE	NEW VALUE	ERROR	
PHASE CENTER	0.	0.	11.	DEGREES
8X	-0.0090	-14356.7785	0.0427	
BY	0.0730	-45260.7600	0.0171	
BZ	0.0739	19264.6032	0.0249	
K	0.0	0.0	0.0671	
L	0.0	0.0	0.0671	
H	0.0	0.0	0.0671	

BASELINE PARAMETERS FOR 85-1,3 X RR

THREE SOLUTION FIT PARAMETERS ARE 8.0785 8.0785 305.3679. SOLUTION 2 CHOSEN.

QUANTITY	CHANGE	NEW VALUE	ERROR	
PHASE CENTER	77.	77.	10.	DEGREES
BX	-0.0062	-13600.0843	0.0391	
BY	0.0485	-42878.1254	0.0155	
BZ	0.0194	18250.6688	0.0228	
K	0.0	0.0	0.0616	
L	0.0	0.0	0.0616	
M	0.0	0.0	0.0616	

BASELINE PARAMETERS FOR 85-1,3 X LL

THREE SOLUTION FIT PARAMETERS ARE 8.2383 8.2383 49.7666. SOLUTION 2 CHOSEN.

QUANTITY	CHANGE	NEW VALUE	ERROR	
PHASE CENTER BX	108.	108.	0.0399	DEGREES
BY	0.0465	-42878.1273	0.0160	
BZ K	0.0141	18250.6635	0.0233	
î	0.0	0.0	0.0627	
M	0.0	0.0	0.0627	

BASELINE PARAMETERS FOR 85-2,3 X RR

THREE SOLUTION FIT PARAMETERS ARE 0.4199 0.4199 0.4187. SOLUTION 3 CHOSEN.

YTITMAUQ	CHANGE	NEW VALUE	ERROR	
PHASE CENTER	150.	150.	2.	DEGREES
BX	0.0074	-756.6811	0.0088	
BY	0.0270	-2382.6322	0.0035	
BZ	0.0588	1013.9387	0.0049	
K	0.0	0.0	0.0139	
Ĺ	0.0	0.0	0.0139	139
H	0.0	0.0	0.0139	

BASELINE PARAMETERS FOR 85-2,3 X LL

THREE SOLUTION FIT PARAMETERS ARE 0.2647 0.2647 156.2890. SOLUTION 2 CHOSEN.

CHANGE	NEW VALUE	ERRUR	
71.	71.	2.	DEGREES
0.0002	-756.6882	0.0071	
0.0265	-2382.6326	0.0028	
0.0682	1013.9481	0.0039	
0.0	0.0	0.0111	
0.0	0.0	0.0111	
0.0	0.0	0.0111	
	71. 0.0002 0.0265 0.0682 0.0	71. 71. 0.0002 -756.6882 0.0265 -2382.6326 0.0682 1013.9481 0.0 0.0	71. 71. 2. 0.0002 -756.6882 0.0071 0.0265 -2382.6326 0.0028 0.0682 1013.9461 0.0039 0.0 0.0 0.0111 0.0 0.0 0.0 0.0111

Fig. III-21. Part of INTBCAL output showing the properties of the solutions for the XBAND correlators.

	3) AND CLOSURE	RR, S AND (X/	ERAGED USING LL AND	AVERAG	PARAMETERS	OBASELIN
DIFF	BASELINE 2,3	BASELINE 1,3	BASELINE 1.2			
-0.0027	-252.2271	-4533.3655	-4785.5952	вх	ASELINE FOR	AVERAGE
0.0000	-252.2271	-4533.3668	-4785.5939		ASELINE	CLOSED
0.0007	-794.2115	-14292.7081	-15086.9189	ВУ	SELINE FOR	AVERAGE
0.0000	-794.2115	-14292.7077	-15086.9192		ASELINE	CLOSED
-0.0008	337.9824	6083.5540	6421.5356	BZ	SELINE FOR	AVERAGE

Fig. III-22. Part of INTBCAL output showing the baseline solutions obtained, averaging the results for both frequencies and using the closure condition.

6421.5360 6083.5536 337.9824

0.0000

CLOSED BASELINE

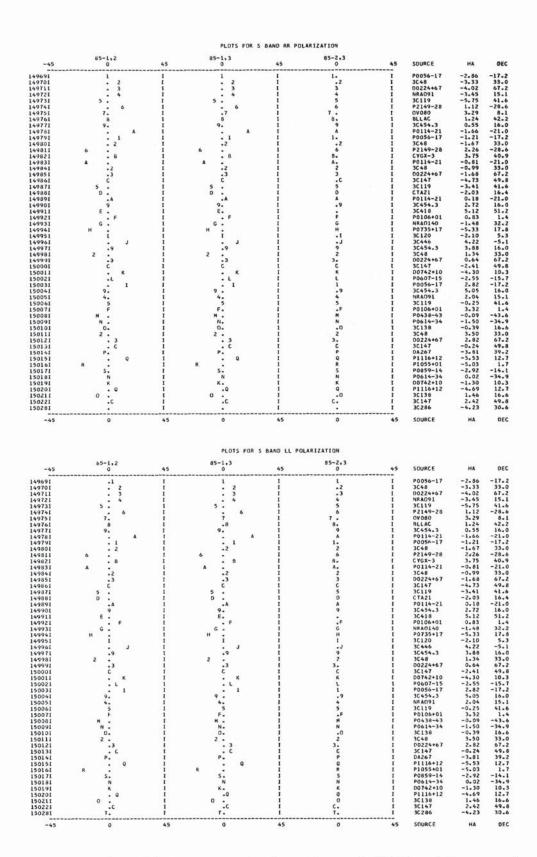


Fig. III-23. Part of INTBCAL output showing plots of SBAND calibrator phases as a function of time, after the new baseline solutions have been applied.

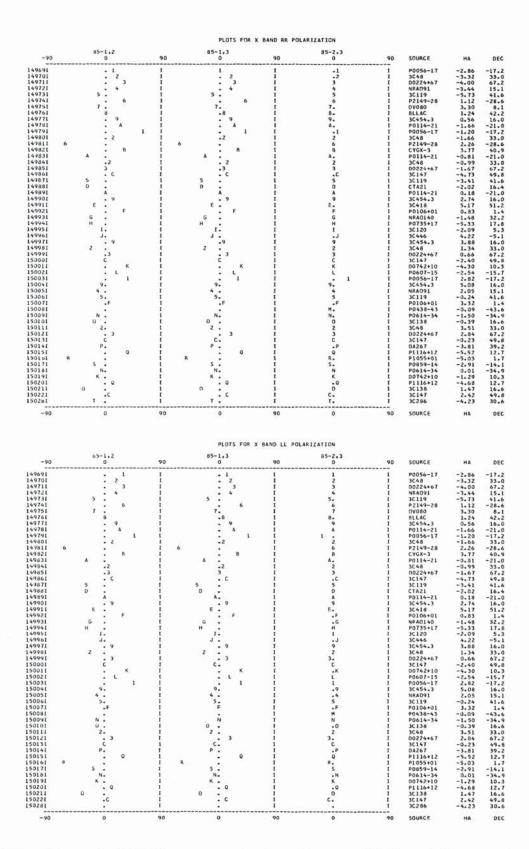


Fig. III-24. Part of INTBCAL output showing plots of XBAND calibrator phases as functions of time, after the new baseline solutions have been applied.

should have identical baseline errors, and because the errors for the same correlators should differ by only a factor of three for XBAND and SBAND, one can improve the solutions by averaging, with results as shown in Figure III-22. One additional constraint is that of closure, e.g.,  $B_{\rm x}(12) = B_{\rm x}(13) + B_{\rm x}(23)$ . Using these conditions one obtains the best averaged and closed baselines as shown in Figure III-22 (for SBAND only, to get XBAND multiply by 3).

INTBCAL then applies the baseline corrections to each correlator individually, corrects for the phase center, and then plots the resulting phases as shown in Figures III-23 and 24. We see that the fits for this set of data are very good; one seldom sees less phase noise. Note that phase noise scales roughly with baseline length and frequency.

With the results on  $\Delta B_x$ ,  $\Delta B_y$ ,  $\Delta B_z$ , one can use INTEDIT or INTCORR to generate the CORRTAPE where data are in the stage V' = A' exp (i $\phi$ ').

## (2) Determining Phase Centers with INTBCAL

It is best not to use the phase center  $(\phi_S)$  determined by INTBCAL at the same time the baseline solutions are obtained. This is because the accuracy is greatly improved when one uses the baselines determined from all the data and then solves only for the phase centers. This is easily done using INTBCAL with the PARM='NOBASE' option. In this case the program as listed above is modified so that: (1) PARM = 'NOBASE' is on the EXEC card; (2) one adds a //BASLINES\_DD\_\* card which says baselines are to be read in; and (3) one adds a set of 8 cards punched in the format  $^4F(15.3)$ , with each card giving  $^8$ ,  $^8$ ,  $^8$ ,  $^8$  and  $^8$  for the appropriate pair. The eight cards are in the order S12, S13, S23, a card with four zeroes, X12, X13, X23 and another card with four zeroes\*. We will not show an example of the results, since they are the same as for Figures III-19-24, except better phase centers are obtained.

Obviously INTBCAL, when used only to determine  $\boldsymbol{\varphi}_S$  for each correlator, is useful whenever one is using INTEDIT to calibrate data.

<sup>\*</sup> A vestige of an old system involving a pair between 85-1 and a remote 42-foot telescope.

## (c) INTCLEAN to Diagnose and Partially Clean Data.

The first step in automatic data processing is use of INTCLEAN to obtain

- (1) A listing of diagnostic messages of varying severity based upon fault information noted on tape; and
- (2) A summary of available diagnostic messages, their severity and the number of times each fault was found.

A sample of diagnostic messages for real data is given in Figure III-8; and a sample of the diagnostic summary for the same data is given in Figure III-9.

In addition to the diagnostic features of INTCLEAN, the program will also automatically delete (flag as bad) all data with faults with severity code of 3 (number of asterisks) or more.

Examining Figure III-8, we see that the data diagnostics always give the following for each scan: scan number, LST at time header is written, source name, right ascension and declination of reference position precessed to date of observation, and the mode. In addition, whenever a fault was detected by system monitors or the DDP116, details concerning the fault are recorded and INTCLEAN gives a display of the following for each occurrence of such faults: the LST, the severity code, the correlator, telescope, or receiver involved, a description of the fault, the word in the data record where the faulty data are located and finally the contents of that word.

In doing partial cleaning of the data, INTCLEAN automatically deletes all data with fault messages at severity level 3 or greater. It also flags data records where correlators rms' are in excess of 1000 for high gain settings and 200 for medium or low gain settings.

In many cases INTCLEAN will accomplish all the cleaning that is desired, but there are many possible problems for which no automatic cleaning is possible. When this occurs, one does manual cleaning with

INTEDIT starting with either the raw data tape or the output subjected to partial cleaning by INTCLEAN. Any problem where bad data (particularly headers) must be replaced by good data must be solved with INTEDIT. In addition, one frequently needs to delete data for reasons that cannot be written into a program.

INTCLEAN has a default input specification of a temporary disk data set '&&OUTNAME' so it will accept the default output of INTCOPY, but one usually specifies its output characteristics. One may also alter the severity threshold for automatic deletion by the PARM option, PARM='DELETE=...' (default=3) and the maximum allowable rms for high gain, PARM='MAXRMS=...' (default=1000). MAXRMS/5 is used for medium and low gain settings.

```
As an example,

//_EXEC_INTCLEAN,INTAPE=3085,INNAME=RAWTAPE,

//_OUTUNIT=DISK,OUTNAME='&&CLEAN',

//_PARM='DELETE=3,MAXRMS=1000'

(results shown in Figures III-8 and 9)
```

will pass the diagnosed and partially cleaned data on to a temporary disk data set '&&CLEAN'. If further use of INTEDIT is needed, it can take input from '&&CLEAN', otherwise the '&&CLEAN' data can then be processed by INTCORR.

The place of INTCLEAN in the data processing is shown in the flow diagram in Figure III-1.

## (d) INTCORR to Apply Automatic Corrections

INTCORR is a program that can be used to apply all the automatic corrections, in particular the corrections associated with PHASE, CLOCK, AMPCOR, and BASELINE in INTEDIT. In this case, the CLOCK correction is based upon a predicted clock error derived from a formula in the program. The constants for AMPCOR are the standard values of 0.07 at SBAND and 0.19 at XBAND.

BASELINE corrections, however, are applied only if new baselines are supplied. The PHASE, CLOCK and AMPCOR corrections are applied by default. To suppress them one must specify PARM='NOPHASE,NOCLOCK, NOAMPCOR'.

The following program, applied to the segment of data that we have been using in the examples, illustrates the usual use of INTCORR:

```
//_EXEC_INTCORR,INUNIT=DISK,INNAME='&&CLEAN,
//_OUTTAPE=3086,OUTNAME=CORRTAPE,OUTDISP=NEW
//BASLINES_DD_*
-4785.5938 -15086.9192 6421.5360 0.0
-4533.3667 -14292.7077 6083.5536 0.0
- 252.2271 - 794.2115 337.9823 0.0
(results shown in Figure III-25)
```

where  $B_x$ ,  $B_y$ ,  $B_z$ , and k have been supplied (Format 4F15.0) for the SBAND pairs 12, 13, and 23, respectively (XBAND assumed larger by a factor of three) and the final corrected output is written on CORRTAPE.

As we see from Figure III-25, the output describes what corrections have been applied with what parameters. In addition, when baselines have been up-dated, both the old and new baselines are listed.

Next the INTCORR output gives for each scan the following information derived from each scan header and the adjacent A/D record: scan number, source name, LST, RA and DEC precessed to time of observation, temperature (in °C), dew point, vapor pressure, the LO index, the predicted clock error, PACB indicating that PHASE,AMPCOR,CLOCK, and BASELINE corrections have been applied to the data, partial information about the contents of word 22 (where bits 9 through 12 record whether P, A, C, or B have been applied, bit 14 contains 1 if INTCORR has been applied, and bit 16 is a 1 if the header is bad and a 0 if it is not), the year and the Julian day and fractions of a day. In the WD22 column the last symbol gives the contents of bits 14 and 16.

INTCORR

```
FUNCTIONS BEING APPLIED ARE:
     AMPCOR (SBAND=0.070 XBAND=0.190)
   PHASE
CLOCK
BASELINE - UPDATED BASELINES ARE:
                                                                                                                                                                                                                  -252.2271
-794.2115
337.9323
0.0
   INTCORR INPUT DATA SET ATTRIBUTES
  TAPE BASELINES ARE
   RX -4785.5098 -4533.3594
BY -15030.9443 -14292.7246
RZ 6421.5098 6383.5498
K 0.0 0.0
                                                                                                                                                                                   -252.2295 -14356.7695
-794.2197 -45260.8330
137.9600 19264.5293
0.0 0.0
                                                                                                                                                                                                                                                                                                                                                   -13600.0781
-42878.1738
18250.6494
0.0
SPACINGS 19 18 1
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       300 PACE MOZZ YEAP

55 PACE 00F4 1972 2441590.61560

55 PACE 00F4 1972 2441590.62297

55 PACE 00F4 1972 2441590.62297

55 PACE 00F4 1972 2441590.62297

65 PACE 00F4 1972 2441590.6390

65 PACE 00F4 1972 2441590.6390

65 PACE 00F4 1972 2441590.65718

65 PACE 00F4 1972 2441590.65718

65 PACE 00F4 1972 2441590.6703

65 PACE 00F4 1972 2441590.7703

65 PACE 00F4 1972 2441590.7803

65 PACE 00F4 1972 2441590.3803

66 PACE 00F4 1972 2441590.3803

67 P
                                                                                                                                                                                                                                                                                                                   TEMP DEW PT VP
                                                                                                                                                                                                                                                                                                                                                                                                                              LO GLOCK PACE WD22 YEAR
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              JULIAN DATE
                                                                                                                                                                                                                                                     DEC
       SCAN SOURCE LST
                                                                                                                                                                             S.A
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                                                                                                                                                                                                                                                                                                                                                                                                                              7500031.
           65 HEADERS
892 DATA
61 A/U
0 ITY
0 AVE
0 PTING
                    O JAKAGAN
       INTCORR DUTPUT DATA SET ATTRIBUTES
```

Fig. III-25. Display of the automatic data processing that has been applied to scans 14969 through 15028 by INTCORR.

Finally, at the end there is a summary of the number of records of all types that have been written on the OUTUNIT. In Figure III-25, there were 60 headers, 817 data records, 56 A/D records, no operator message (TTY, typed in by operator while observing), no averaged records, no pointing data records, and no unidentifiable types of records.

If BASELINES had not been available, we would have used the output CORRTAPE (with only PAC applied) as input to INTBCAL to determine baselines; however, once baselines have been updated the CORRTAPE output lacks only gain and phase center calibration—which can be accomplished either as discussed earlier by INTEDIT or by use of INTCAL. The final result of INTCORR is data in the CORRTAPE stage  $[V' = A' \exp (i\phi')]$ .

The place of INTCORR in the data processing is shown in the flow diagram in Figure III-1.

## (e) INTCAL to Calibrate LL and RR Correlators

INTCAL determines the system gains and phase centers ( $g_S$  and  $\phi_S$ ) from data which has been cleaned and corrected, then applies these to the data. In other words, starting with data in the CORRTAPE stage, it determines  $g_S$  and  $\phi_S$  and then produces the data in the CALTAPE stage, for LL and RR correlators only, from

$$V = g_S A' \exp (i\phi' - i\phi_S)$$

(see Figure III-1).

For obvious reasons, INTCAL operates on a number of assumptions. In particular, it may not work properly if: (1) serious faults remain in the data, particularly bad calibrator data; (2) not enough gain and phase calibrators with names identifiable by the program are included in the data; or (3) the gains and/or phase centers are anything but slowly varying or discontinuous functions of time.

INTCAL reads the input data and searches for data on a standard list of phase calibrators and a standard list of flux calibrators. It

assumes that the phase calibrators have been observed at the reference position and that they have names as listed in Figure III-26. A shorter list of flux calibrators, also shown in Figure III-26, with S and X-BAND flux densities and weights, is also assumed to have some members amongst the data to be processed by INTCAL. Finally, the gains and phase centers are evaluated as running means over specified convolution times which are also listed in Figure III-26. Whenever INTCAL is used, the lists of phase calibrators, flux calibrators, and convolution times are printed out as in Figure III-26.

INTCAL reads the input data and stores the CPFU's and phases of the calibrators as a function of time. Up to seven days of data can be processed at a single pass. Given the stored calibrator data, the program calculates smooth curves for  $g_{\varsigma}$  and  $\phi_{\varsigma}$ , evaluated at every sidereal half hour, using a weighted average of the calibrator observations and specified convolution times. The weights are computed from a combination of those specified (for the flux calibrators) and the length of time which separates the calibrator observations from the current time. The default convolution times are four hours for  $\boldsymbol{\varphi}_{\boldsymbol{S}}$  and six hours for gg; they can be changed by specifying PARM='PCONV=..., GCONV=...' in the EXEC cards of INTCEN. The corrections are graphically displayed (asterisk curves in Figure III-27) and applied to all the data to form a completely calibrated data set in the CALTAPE  $[V = A \exp (i\Phi)]$  stage. Corrections that are applied to LL correlators are also applied to the LR and RL channels of the same correlator and frequency.

Input to INTCAL consists of the uncalibrated data in the CORRTAPE stage and the usual INCLUDE/EXCLUDE cards. Also, a list of phase calibrators (up to 100) and a list of flux calibrators (up to 30 with their SBAND and XBAND fluxes and relative weights) can be entered if the default lists are not adequate. An optional list of times at which discontinuities occurred can also be specified.

INTCAL

#### INTERFEROMETER GAIN AND PHASE CALIBRATION

#### INPUT FLAGS

DO THE PHASE CALIBRATION
DO THE GAIN CALIBRATION
APPLY THE PHASE AND/OR GAIN CORRECTION TO THE OBSERVATIONS
INCLUDE THE CALIBRATION ERRORS

#### PHASE CALIBRATORS

P0056-00	P2134+00	P0106+01	P0114-21	3C48
NRAD91	D0224+67	P0229+13	P0237-23	CTA21
NRAD140	NRAO150	P0403-13	P0413-21	P0420-01
30119	3C120	P0438-43	NRA0190	P0451-28
30138	3C 147	P0556+28	P0605-08	P0607-15
P0614-34	DA207	01318	D0727-11	P0735+17
P0736+01	01363	D0742+10	P0743-00	30191
P0834-20	P0859-14	P0906+01	DA267	3C222
A0952+17	3C232	30236	P1015-31	P1055+01
P1116+12	30256	P1127-14	P1148-00	P1151-34
NRA0389	3C268.3	P1237-10	P1245-19	30279
3C287	3C 286	P1345+12	09323	3C298
30309.1	P1508-05	P1510-08	D1548+05	01555+00
P1607+26	DA406	3C343	3C343.1	3C 345
NRAD530	3C 3 7 1	3C 395	0000	3C418
P2127+04	P2128-12	P2145+06	P2149-28	BLLAC
P2203-18	3C 446	CTA102	3C454	3C454.3
P2345-16				

#### FLUX DENSITY CALIBRATORS

SOURCE	SBAND	XRAND	WT
3C48	9.000	3.300	1.00
CTA21	5.000	1.700	0.80
NRAU140	2.700	2.100	0.60
P0413-21	1.600	0.850	0.50
P0420-01	1.300	1.500	0.70
30119	5.400	2.200	0.50
P0451-28	2.200	2.000	0.50
3C138	5.600	2.800	0.60
3C147	12.700	5.000	0.80
00727-11	2.600	4.800	0.50
P0834-20	2.500	2.600	0.60
DA267	4.800	10.700	0.70
P1015-31	2.200	1.000	0.50
P1116+12	1.700	1.200	0.50
P1127-14	6.400	4.500	0.70
30287	4.600	2.200	0.70
3C286	10.100	5.200	1.00
P1345+12	3.800	2.400	0.60
30309.1	5.300	2.500	0.50
DA406	2.400	2.100	0.70
NRA0530	3.900	4.600	0.60
3C395	3.200	2.200	0.90
3C418	4.000	3.300	0.80
P2128-12	1.700	1.600	0.80

## CONVOLUTION TIMES IN HOURS FOR SMOOTHING

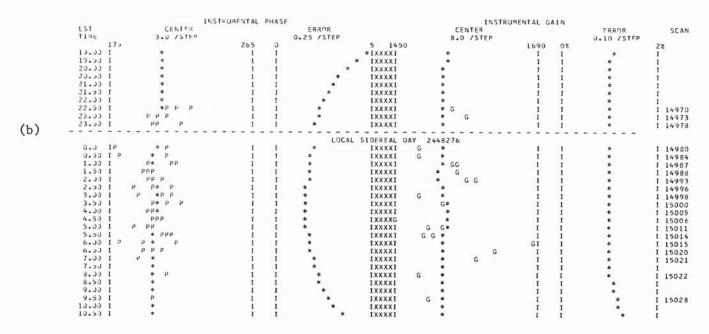
CORRE	ATOR	PHASE	GAIN
1R2R	SBAND	4.00	6.00
1L2L	SBAND	4.00	6.00
1933	SBAND	4.00	6.00
1L3L	SBAND	4.00	6.00
2R3R	SBAND	4.00	6.00
2L3L	SBAND	4.00	6.00
1R42	SBAND	4.00	6.00
1L42	SBAND	4.00	6.00
1R2R	XBAND	4.00	6.00
1L2L	XBAND	4.00	6.00
1R3R	XBAND	4.00	6.00
1L3L	XBAND	4.00	6.00
2R3R	XBAND	4.00	6.00
2L3L	XBAND	4.00	6.00
1R42	XBAND	4.00	6.00
1L42	XBAND	4.00	6.00

Fig. III-26. First page of the INTCAL output showing names and assumed properties of gain and phase calibrators, together with the convolution times to be used for gain and phase calibration.

1R2R SBAND FOR INITIAL LSD 2448275

			INSTRUMENTAL	PHASE				INSTRU	MENTAL G	AIN		
	LST	CENTER		1.11	ERROR		CENTER				FPRCR	SCAN
	TIME	3.0 /STEP			0.20 /STEP		14.0 /ST	EP			0.15 /STEP	
	-95	3.0 /3.2.	~5	0		5 1390	16155 350		1810	02		3%
	19.33 1		í	t		*IXXXXI			1	1		1
	19.50 I		i	i		IXXXXI			1	1	*	1
	20.00 1		i	i		IXXXXI			1	1		I
	20.00 1		i i	i		IXXXXI			1	1	*	1
	21.30 [		i	i		IXXXXI			Ţ	1		1
	21.50 1		i	i		IXXXXI			1	1		1
		1		÷		IXXXXI			1	Î		1
	22.JJ I	* 44 6				IXXXXI	*G		1	1	*	1 14970
	22.50 I 23.00 I	p p*p			*	IXXXXI	# G		i	î		1 14973
		P*P P	1			IXXXXI	*		1	í		1 14978
/ \	23.50 1	P*P P										
(a)					LOCAL	SIDEREAL DAY	2448276					
	0.J P	ø P	11	1	de	IXXXXIG			1	I		I 14980
	J. 20 IP	* P	i	1		IXXXXI	G*		1	1		1 14984
	1.30 I	P# PP	i i	1		IXXXXI	* G	G	1	I	*	1 14987
	1.23 1	р рр	i	î		IXXXXI G			I	1		1 14988
	2.J0 I	P*P	Ť	Ť		IXXXXI	G *G		1	1		1 14993
		p p* p	i	i		IXXXXI			I	1		1 14996
	3.33 [	4 44 4	i	1		IXXXXIG	*		1	1	•	1 14998
	3.53 I	P* P P	i	ì		IXXXXI	* G		1	1		I 15000
		PP#	i	÷		IXXXXI			1	1	*	1 15005
	4.33 T	PPP	1	- 1		IXXXXI	G •		1	1	*	I 15006
	4.53 I	944	1	÷		IXXXXI	G #G		1	1		1 15011
	5.30 I	* P P		- 1		IXXXXI	GG		1	1	*	1 15014
	5.50 [	2 4 9	- 1	- 1		IXXXXI		G	1	1		1 15015
	6.03 IP	PPP		- 7		IXXXXI			G 1	1		1 15020
	0.53 [	P &	1	i	*	IXXXXI	* G		1	i	*	1 15021
	7.JO I			- 1		IXXXXI			1	ī		1
	7.50 I	2 4		4		IXXXXI	6.		1	1		1 15022
	8.33 1	, r	1	1		IXXXXI			i	i	*	1
	8.53 I	*	1	- 1		IXXXXI			i	î	*	i
	9.JJ I	*	1	1		IXXXXI			í	ř		1
	1 (د.و	*		1		IXXXXI			i	î		i
	13.33 1		1	1		IXXXXI			i	i		Ī
	10.00 1	*	1	1		144441	•					-

1L2L SBAND FOR INITIAL LSD 2448275

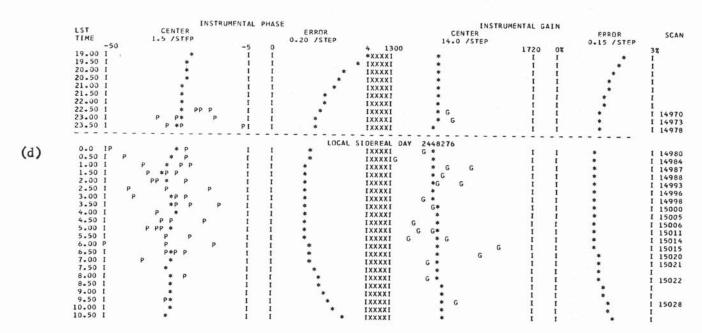


Figs. III-27a-%. Portion of INTCAL output where the gain and phase calibration solutions that have been obtained are plotted as a function of LST, together with the data points used to obtain the solutions.

1R3R SBAND FOR INITIAL LSD 2448275

			INSTRUMENT	AL PHASE				INSTRUME	NTAL GA	IN		
	LST	CENTER			ERROR		CENT				ERROR	SCAN
	TIME	1.5 /STEP			0.20 /STEP		14.0 /	STEP			0.15 /STEP	
	175		22	0 0		4 1210			1630	0.8		3%
	19.00 I	,	<b>K</b>	I I		*XXXXI	*		1	1		I
	19.50 I			1 1		IXXXXI			I	1		1
	20.00 I		•	1 1		IXXXXI	*		1	I		I
	20.50 1			1 1	•	IXXXXI	*		1	1		I
	21.00 I	*		I I	*	IXXXXI	*		1	1		I
	21.50 I			I I	*	IXXXXI	*		1	I		I
	22.00 I	*		I I		IXXXXI	*		1	1	*	I
	22.50 I		PP P	I I	*	IXXXXI	*G		1	I		1 14970
	23.00 I	P P#	P	I I		IXXXXI	* G		1	1		I 14973
	23.50 I	РР		P I	*	IXXXXI	•		I	I	•	I 14978
(-)					LOCAL	SIDEREAL DAY	2448276					
(c)	0.0 I P	* 1		1 1	*	IXXXXI G			1	1		I 14980
	0.50 I P	* 1	,	1 1		IXXXXG			1	1		I 14984
	1.00 I	P * P !	•	I I		IXXXXI	G	G	1	1		1 14987
	1.50 I	P *P P		I I		IXXXXI	*G	3376	1	1		1 14988
	2.00 I	P # 6	)	1 1		IXXXXI	# G G		I	1	*	I 14993
	2.50 I	P P	P	1 1		IXXXXI	*		1	1		I 14996
	3.00 I	P # PP		1 1	*	IXXXXI G	*		1	1		I 14998
	3.50 1	PF	р р	1 1		IXXXXI	*G		I	1		1 15000
	4.00 I	PP *		1 1	*	IXXXXI	*		1	1	*	I 15005
	4.50 I	P P*	P.	1 1		IXXXXIG			1	ī		I 15006
	5.00 1	PP P *		I I	*	IXXXXI G	*G		1	1		I 15011
	5.50 I	ρ	P	I I		IXXXXI G			1	1		I 15014
	6.00 I P	P.	P	I I		IXXXXI		G	1	T		I 15015
	6.50 I	P*P P		I I		IXXXXI	*	G	1	1		I 15020
	7.00 [	P *		1 1		IXXXXI	G *		1	1	*	I 15021
	7.50 I			i i		IXXXXI	*		Ť	ī		1
	8.00 I	* P		1 1		IXXXXI	G *		ī	ī		I 15022
	8.50 I			î î		IXXXXI			ī	T		I
	9.00 1			î î		IXXXXI			Ť	î		i
	9.50 1	*		i i		IXXXXI			i	i		i
	10.00 I			i i		IXXXXI			î	i		i
	10.50 I			i i		IXXXXI			i	i		i
	******				57.75	********	0.77.0					•

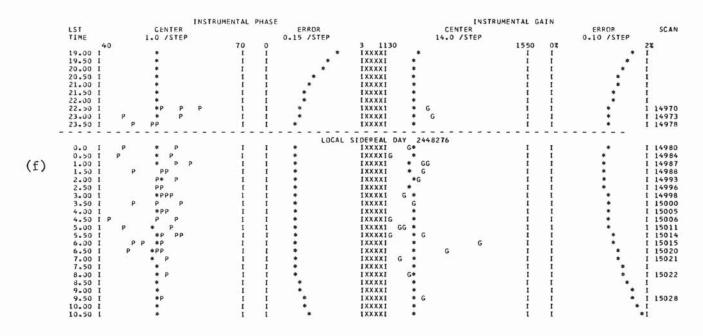
1L3L SBAND FOR INITIAL LSD 2448275



2R3R SBAND FOR INITIAL LSD 2448275

			INSTRUMENTAL	PHASE				INSTRU	JMENTAL G	NIA		
	LST	CENTER			ERROR			CENTER			ERROR	SCAN
	TIME	1.0 /STEP			0.15 /STEP		1	4.0 /STEP			0.15 /STEP	
	-100		-70	0		3 115			1570	0%		3%
	19.00 I		1	1		IXXXXI			1	1	*	1
	19.50 I	*	1	1	*	IXXXXI			I	1		I
	20.00 I		1	I	*	IXXXXI	*		1	I	*	I
	20.50 I		1	1	*	IXXXXI			1	1	*	I
	21.00 I		I	1	*	IXXXXI	*		ī	1		i
	21.50 I		I	ī	*	IXXXXI	*		ī	1		i
	22.00 I		1	I		IXXXXI			i	1		i
	22.50 I	* P P P	ī	ī		IXXXXI	* G		i	ī		I 14970
		PP # P	1	I		IXXXXI	*G		í	1		I 14973
	23.50 I	P P*	î	Ť		IXXXXI			î	i		1 14978
					LOCAL	SIDEREAL		76				
	0.0 I	P # P	I	ī	*	IXXXXI	G *		I	I	*	I 14980
	0.50 I P		1	1	*	IXXXXI	G *		I	1	*	I 14984
/ \	1.00 I	* PPP	1	1		IXXXXI	* GG		1	1	*	I 14987
(e)	1.50 I	P PP	1	1		IXXXXI	*G		1	1		I 14988
	2.00 I	P* P	1	I		IXXXXI	* G		I	1	*	1 14993
	2.50 I	PP	1	1		IXXXXI	*		1	I	*	I 14996
	3.00 I	*PPP	1	1		IXXXXI	G*		I	1	*	I 14998
	3.50 I	PPP	1	I	•	IXXXXI	*G		I	I	*	I 15000
	4.00 I	* P	1	1	*	IXXXXI			I	I		I 15005
	4.50 I P	РР	1	1	*	IXXXXG			1	1		I 15006
	5.00 I	P * P	1	I		IXXXXI	G G*		1	I	*	I 15011
	5.50 I	#P PP	1	1		IXXXXI	G +G		I	I	*	I 15014
	6.00 I	PP	1	1	*	IXXXXI		G	1	I	*	1 15015
	6.50 I	P *P	1	1		IXXXXI		G	1	1	*	I 15020
	7.00 1	* P	1	1		IXXXXI	G*		1	1	*	1 15021
	7.50 I		1	1	*	IXXXXI			1	I		ī
	8.00 I	# P	Î	1		IXXXXI	G *		ī	ī		I 15022
	8.50 I		Í	Ī		IXXXXI			i	Ī		1
	9.00 I		ī	ī	*	IXXXXI			Ĩ	1		î
	9.50 1		Ĭ.	i		IXXXXI			i	1		1
	10.00 1		î	ī		IXXXXI			ī	ī		i
	10.50 I		i	î	*	IXXXXI			i	i		i
	77.500										373	3.0

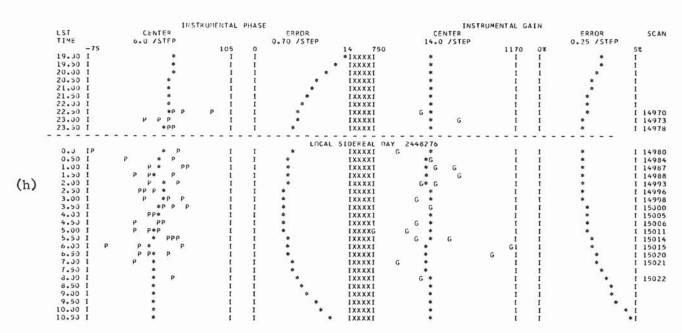
#### 2L3L SBAND FOR INITIAL LSD 2448275



1R2R XBAND FOR INITIAL LSD 2448275

		INSTRU	MENTAL PHASE			INSTRUME	NTAL GAIN		
	LST	CENTER		ERROR		CENTER		EPROR	SCAN
	TIME	6.0 /STEP		0.70 /STEP		20.0 /STEP		0.25 /STEP	
	-30		150 0		14 840		1440 0%		5%
	19.30 1		I I		* IXXXXI *		I I		I
	19.50 I		1 1		* 1XXXXI		1 1		ī
	20.00 I	*	1 1	*	IXXXXI *		1 1		1
	20.50 I		I I	*	IXXXXI *		1 1		1
	21.00 I		1 1		* IXXXXI		1 1		1
	21.50 I		1 1	*	IXXXXI *		I I		1
	22.00 I		I I	*	IXXXXI *		1 1		I
	22.50 I	*P P	P 1 1		IXXXXI G *		I I		I 14970
	23.00 1	P PP	I I		IXXXXI *	G	I I		I 14973
	23.50 1	PPP	1 1		* IXXXXI		1 1		1 14978
				LOCAL	SIDEREAL DAY 244	8276			
	0.0 IP	* P	1 1		IXXXXIG *		1 1	*	1 14980
	0.50 I	P * P	i i		IXXXXI *G		1 1		I 14984
(g)	1.00 I	P * PP	1 1		* IXXXXI	GG	1 1		1 14987
(8)	1.50 I	P P * P	1 1		IXXXXI *G		I I		I 14988
	2.00 I	PP * P	1 1	*	IXXXXI G*		1 1		1 14993
	2.50 1	P PP *	1 1		* IXXXXI		1 1		I 14996
	3.00 I	P * P P	1 1		IXXXXI G *		1 1	*	1 14998
	3.50 I	PPP	1 1		IXXXXI *G		1 1		1 15000
	4.00 I	PP#	1 1		* IXXXXI		1 1		1 15005
	4.50 I	PPP	I I	*	IXXXXI G		t t		I 15006
	5.00 I	P PP	1 1		IXXXXG G *		1 1	*	I 15011
	5.50 I	* PP P	1 1		IXXXXI G *	G	1 1		I 15014
	6.00 I P	P * P	1 1		IXXXXI *	G	I I	*	I 15015
	6.50 I	P P* P	1 1		IXXXXI *	G	1 1		I 15020
	7.00 I	P *	1 1	*	IXXXXI G *		I I		I 15021
	7.50 I		1 1	*	IXXXXI *		1 1		1
	8.00 I	* P	1 1	*	IXXXXI G*		I I	*	1 15022
	8.50 I		1 1		IXXXXI	•	1 1		1
	9.00 1		I I	*	IXXXXI	•	1 1		I
	9.50 1	P*	1 1	*	IXXXXI	* G	I I		I 15028
	10.00 I	•	1 1		IXXXXI	*	1 1	*	1
	10.50 I	•	1 1	*	IXXXXI	•	1 1		1

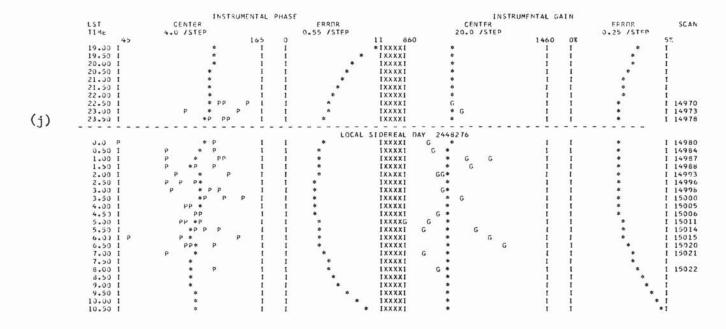
#### 1L2L XBAND FOR INITIAL LSD 2448275



#### 1R3R XBAND FOR INITIAL LSD 2448275

			INSTRU	MENTAL	PHASE						IN	STRUMENTAL C	AIN		
	LST	CENTER				ERROR				CE	NTER		157.W.1.00.	ERROR	SCAN
	TIME	4.0 /STEP				0.55 /STEP					/STEP			0.25 /STEP	
	10			130	0		11 70	00				1300	0%	0025 / 0121	5%
	19.00 I			1	Ť		*IXXXXI	275				1	1		1
	19.50 I		*	1	1		* IXXXXI		*			1	1		Ī
	20.00 1		*	1	ī		IXXXXI		*			Ŷ	î		ī
	20.50 I		*	1	1		IXXXXI		*			1	1		î
	21.00 I			1	1		IXXXXI		*			i	ī		i
	21.50 I		*	1	1	*	IXXXXI		*			Ĩ	Ī		ī
	22.00 I			1	1	*	IXXXXI		*			ī	1		i
	22.50 I		* PP	PI	1	*	IXXXXI		G			Î	ī		I 14970
	23.00 I	p	*	PI	ī	*	IXXXXI		*	G		i	ī		1 14973
(:)	23.50 1		#P PP	1	i		IXXXXI		*	-		i	1		1 14978
(i)			:						-						
						LOCAL	SIDEREAL	DAY	24	48276					
	0.0 IP		р	I	1	*	IXXXXI	G	*			1	I		1 14980
	0.50 1	P #	P	1	I	*	IXXXXI	G	*			1	1		I 14984
	1.00 I	p e	pp	1	I		IXXXXI		*	G		I	1	•	1 14987
	1.50 1	P *P	P	1	1		IXXXXI		*	G		Ī	1		I 14988
	2.00 I	P *	P	1	1		IXXXXI	G	G			1	1		1 14993
	2.50 I	P P P *		I	1	*	IXXXXI		*			1	1		1 14996
	3.00 [	P #	P P	1	1		IXXXXI	G				I	1		I 14998
	3.50 I		PP	PI	1		IXXXXI			G		1	1		1 15000
	4.00 I	p p+		1	1		IXXXXI		*			1	I		1 15005
	4.50 1	PP		1	1		IXXXXI	G	*			I	1		I 15006
	5.00 I	PPP*		1	I		IXXXXG	0	. *			1	1		1 15011
	5.50 I	PP	P	1	1	*	IXXXXI	G		C		I	I		1 15014
	6.00 I P	P*		PI	ī		IXXXXI		*		G	1	1		1 15015
	6.50 I	PP	P	1	1	*	IXXXXI		*			G 1	1	•	1 15020
	7.00 I	P *		1	1		IXXXXI	G				1	1		I 15021
	7.50 I	*		1	1		IXXXXI		- 9	•		1	I		1
	8.00 I		P	1	1	*	IXXXXI			•		1	1		I 15022
	8.50 I	*		1	1	*	IXXXXI		- 1			1	1		1
	9.00 I			1	1	*	IXXXXI		-			I	1		1
	9.50 I	P*		1	I	*	IXXXXI			<ul><li>G</li></ul>		1	1		I 15028
	10.00 1	*		1	I	*	IXXXXI		1	*		1	1		I
	10.50 I	*		1	1		IXXXXI		1			1	1		1 *

#### 1L3L XBAND FOR INITIAL LSD 2448275



2R3R XBAND FOR INITIAL LSD 2448275

			INSTRUMENTAL	PHASE					12		STRUME	NTAL GA	NIN	22222	*****
	LST	CENTER			ERROR					ENTER				ERROR	SCAN
	TIME	3.0 /STEP			0.30 /STEP				20.	O /STEP		90.70	72.2	0.30 /STEP	
	135		225	0		6	66	0				1260	0.8		6%
	19.00 I	*	I	I		* IXX						1	1		1
	19.50 I	*	1	1		IXX						1	1	•	1
	20.00 I	*	I	I		IXX						1	1	*	1
	20.50 I	*	1	1		1 XX						1	1		ı
	21.00 I	*	1	1		IXX		*				1	1	*	1
	21.50 I	*	1	1		IXX		*				1	1	*	1
	22.00 I		1	1		IXX						1	I	*	1
	22.50 I	PPP	1	1	*	IXX	XXI	G				1	1		1 14970
		* P	1	1		IXX	IXX		G			1	1	*	1 14973
	23.50 I P	PP	1	1		IXX	IXX	*				1	1	*	I 14978
					LOCAL	SIDER			48276	9					I 14980
	0.0 I P	* P	1	1	*	IXX						:		1	I 14984
	0.50 I P	* P	1	1	*	IXX		G *							1 14987
(k)	1.00 I	* PPP	I	1	*	IXX			GG			1		2	1 14988
(2)	1.50 I P	PP	1	1	* "	IXX		*.	G			1	1	1	I 14993
	2.00 I	P *PP	I	1	*	IXX		G*	G				1	*2	1 14996
	2.50 I	pp*	I	1	*	IXX		*				1	1	1	1 14998
	3.00 I	PP P	1	1	*	IXX		G				1	1		
	3.50 I P	PP	1	ı	*	IXX		G*				1	1		1 15000
	4-00 I	P *P	I	1	*	IXX		*				1	1		1 15005
	4.50 IP	P P	1	1	*	IXX		*				1	I	*.	I 15006
	5.00 I P	* P P	1	1	*		XXG	G *				1	1		1 15011
	5.50 I	* PPP	1	1	*		1XX	G *	G			1	1		1 15014
	6.00 I PP	*P	1	1	*	IXX		*			G	1	1	*	1 15015
	6.50 I P	PP	1	1	*	IXX		*		G		I	ī	*	I 15020
	7.00 I	* P	1	I	*	IXX		G *				1	1	*	1 15021
	7.50 I		1	1	*	IXX	1XX	*				ı	1	*	1
	1 00.8	*P	1	I	*	IXX	IXX	G *				1	1	*	1 15022
	8.50 1		1	1		IXX	XXI	*				1	1		1
	9.30 I		1	1		IXX	IXX	*				1	1		1
	9.50 I	P	1	1		IXX	IXX	*	G			I	1	*	1 15028
	10.00 I		1	1			XXI					1	1		1
	10.20 I		1	T		IXX	YYT					1	1		1

2L3L XBAND FOR INITIAL LSD 2448275

					INSTRUMENTA	L PHAS	E				IN	STRUMENTAL G	AIN		
	LST		CE	NTER			ERROR			CE	NTER			ERROR	SCAN
	TIME			/STEP			0.30 /STEP			14.0	/STEP			J.30 /STEP	
		55			145	0		6 7	10			1130	0%		64
	19.00 1		*		1	1		* IXXXXI		*		1	1	*	1
	19.50 1				î	i		IXXXXI				I	Ī	*	I
	20.00				i	1		IXXXXI		*		1	1		1
	20.50				i	i		IXXXXI		*		1	Ī	*	1
	21.00 1				i	1		IXXXXI				1	1		1
	21.00				i	i		IXXXXI		*		i	î		1
	22.00 1				i	i	*	IXXXXI		*		i	i		I
	22.50 1		MP P	P	i	i	*	IXXXXI				i	1		1 14970
	23.00 1		P * P		i	i		IXXXXI			G	i	Ť		1 14973
	23.50		PP		i	i		IXXXXI		*		i	î		1 14978
(2)	000						LOCA	L SIDEREAL		3276				4.4	
(X)	0.0 1		* P		I	1	*	IXXXXI	G	*		1	1	*	1 14980
	0.50 1		* P		1	1	*	IXXXXI	G •			1	1	*	1 14984
	1.00 1			PP	1	1	*	IXXXXI		k	GG	1	1	*	1 14987
	1.50		PP		1	- 1	*	IXXXXI			G	1	1		1 14988
	2.00 1		P*PP		1	1	*	IXXXXI	G *	G		1	I	*	1 14993
	2.50 1	I .	PP		1	- 1	*	IXXXXI				1	1	*	I 14996
	3.00 1	T .	PPP		1	1	*	IXXXXI		,*		1	1	*	1 14998
	3.50 1	I P	*P	P	1	1	*	IXXXXI		*G		1	I		1 15000
	4.00 1	1	* P		1	1		IXXXXI				1	1		1 15005
	4.50 1	P	PP		1	1	*	IXXXXI	G			1	1	*	1 15006
	5.00 1	I P	* PP		1	1	*	IXXXXG	G	*		1	1		1 15011
	5.50 1		* P P	P	1	1	*	IXXXXI	G		G	1	1		1 15014
	6.00 1		*P		i	1	*	IXXXXI				G1	1		1 15015
	6.50 1		*P P		1	1		IXXXXI				G 1	1	*	1 15020
	7.JO I		* P		Ī	1		IXXXXI	G 4			1	1	*	1 15021
	7.50 1				1	1	*	IXXXXI		*		1	1		1
	8.00 1		* P		1	1	*	IXXXXI	G	*		I	1		1 15022
	8.50 1		*		i	1		IXXXXI				1	1		T
	9.00 1				i	i	*	IXXXXI		*		1	I		I
	9.50 1				i	Ī		IXXXXI				1	1	*	1
	10.00 1				i	i		IXXXXI		*		1	1		1
	10.50 I		*		ì	i		* IXXXXI		*		1	1		1

	DATA FOR CONFIGURATI								1-18-19					
SCAN M SOURCE	HA RMS/100		AMP1L2		AMP1R3		AMP 1L 3		AMP2R3				NREC TPOWER	LST
14969 SD P0056-17 14979 SD P0056-17 15003 SD P0056-17 14969 XD P0056-17 14979 XD P0056-17 15003 XD P0056-17	-02 51 000000 -01 12 000000 02 49 000000 -02 51 000000 -01 11 000000 02 49 000000	610 2 660 3 610 18 117 20 127 45 178 52	700 640 648 125 136 193	2 17 29 36 69	691 661 698 80 120 148	3 4 13 7 42 48	690 612 601 89 98 150	2 6 15 27 45 53	820 844 840 190 120 237	-2 -6 -1 3 -5 22	800 774 750 130 107 170	-1 -6 -2 -4 -22 -3	8 665665 9 655665 8 655665 7 666666 9 776777 3 666666	22 06 07 23 45 18 03 47 08 22 06 07 23 45 48 03 47 08
14970 SO 3C48 14980 SO 3C48 14984 SO 3C48 14998 SO 3C48 15011 SO 3C48 14970 XO 3C48 14980 XO 3C48 14984 XU 3C48 14998 XO 3C48 15011 XU 3C48	-03 19 000000 -01 40 000000 -00 59 000000 01 20 000000 -03 19 000000 -01 39 000000 -00 59 000000 01 20 000000 03 30 000000	8783 9 8089 8 8494 6 8088 -4 9033 6 3432 25 3113 23 3654 25 3360 5 3477 34	8971 8679 8663 8653 8904 3316 3060 3428 3261 3174	9 7 7 -3 7 22 21 23 2	9048 8595 8205 8561 9220 3273 3012 2994 3110 3121	7 3 5 -8 -1 17 13 16 -9 13	9053 8601 8070 8629 8810 3450 3137 3182 3285 3088	6 3 4 -8 -1 16 11 14 -11	9282 8850 8767 8962 9047 3360 3073 3049 3295 3156	5 6 6 8 6 12	9377 8900 8532 8875 8839 3310 3029 3203 3321 3239	3 4 6 6 7 13	7 655665 6 66666 7 65665 7 65665 7 65666 6 66666 6 66666 6 66566 7 665666 4 676666	22 16 15 23 55 48 00 36 30 02 56 21 05 06 22 22 16 45 23 56 18 00 36 30 02 56 51 05 06 55
14971 SD D0224+67 14985 SD 00224+67 14999 SD 00224+67 15012 SD D0224+67 14971 XD 00224+67 14985 XD 00224+67 14995 XD 00224+67 15012 XD 00224+67	-04 01 000000 -01 40 000000 06 38 000000 02 49 000000 -04 00 000000 -01 40 000000 00 39 000000 02 50 000000	983 17 1170 11 1045 13 996 18 1862 54 2077 33 2008 45 1878 55	1103 1123 1081 1034 1896 1911 1887 1772	18 12 14 17 54 33 45 53	1098 1102 1085 1092 1697 1841 1775	10 4 6 12 34 15 26 35	1032 1112 1007 1049 1825 1998 1842 1920	9 4 7 11 35 14 28 36	1234 1156 1202 1222 1785 1678 1642 1724	5 6 4 16 15 16	1159 1157 1103 1162 1783 1892 1763 1710	7 6 5 4 15 16 15	9 555665 10 555665 9 655665 12 555665 5 666666 5 665666 5 665666 3 666666	22 25 24 00 45 41 03 05 19 05 15 43 22 26 30 00 46 26 03 06 25 05 16 58
14972 SD NRAO91 15005 SD NRAO91 14972 XD NRAO91 15005 XD NRAO91	-03 26 000000 02 02 000000 -03 26 000000 02 03 000000	3572 5 3646 3 2792 13 2899 16	3928 3821 2879 2806	6 5 12 14	3998 3720 2792 2587	5 0 13 4	3892 3780 2873 2783	5 0 12 3	3980 3890 2823 2863	1 -3 11	4000 3808 2761 2863	0 4 -2 12	7 655665 7 655665 7 666666 7 666666	22 36 23 04 05 57 22 36 53 04 06 27
14973 SD 3C119 14987 SD 3C119 15006 SD 3C119 14973 XD 3C119 14973 XD 3C119 15306 XD 3C119	-05 44 000000 -03 24 000000 -00 14 000000 -05 43 000000 -03 24 000000 -00 14 000000	5577 -5 5418 -8 5160 5 2696 -8 2575 -20 2403 19	5462 5420 5056 2484 2449 2193	-4 -7 6 -8 -21	5658 5385 4950 2398 2432 2043	-7 -11 1 -14 -30 3	5499 5404 5040 2360 2625 2171	-7 -11 0 -15 -31 2	5504 5559 5070 2421 2477 1819	2 3 5 2 9	5685 5556 5089 2442 2496 1969	2 3 5 2 8 14	11 656665 9 555665 7 666665 4 666666 8 665666 7 666666	22 45 48 01 05 51 04 15 56 22 47 00 01 05 51 04 16 26
14974 SU P2149-28 14981 SD P2149-28 14974 XD P2149-28 14981 XO P2149-28	01 06 000000 02 15 000000 01 07 000000 02 15 000000	1857 11 1755 -18 936 30 943 -63	1910 1872 823 797	12 -17 29 -60	1974 1959 857 828	15 -14 49 -53	1854 1860 863 801	16 -15 43 -50	1945 1951 1004 891	-4 -2 -10 -9	1964 1874 965 831	-4 -4 -10 -10	4 665665 10 666666 4 666666 5 776676	22 57 25 00 06 20 22 57 55 00 06 20
14975 SD 0V080 14975 XD 0V080	03 17 300000 03 17 000000	1284 5 1104 16	1275 1001	14	1342 933	8 13	1270 988	7 11	1340 960	-2 2	1241 924	-3 6	10 655665 5 665666	23 05 55 23 06 40
14976 SD BLLAC 14976 XD BLLAC	01 14 000000 01 14 000000	6303 8 7654 34	5835 6896	32	5930 6748	5 22	5751 6794	5 21	6066	3 8	5945 6867	3 9	8 666665 6 665666	23 15 57 23 15 57
14977 SD 3C454.3 14990 SD 3C454.3 14997 SD 3C454.3 15004 SD 3C454.3 14977 XD 3C454.3 14997 XD 3C454.3 14997 XD 3C454.3	00 32 000000 02 43 000000 03 52 000000 05 02 000000 00 33 000000 02 44 000000 03 52 000000 05 04 000000	9763 1 9117 8 10300 14 11041 10 12590 35 13247 46 14538 49 15529 36	10065 10628 10629 10729 12007 13951 14103 14314	2 9 15 11 32 45 47 34	10130 10660 11029 11388 11090 13304 13776 14400	0 4 9 4 29 31 32 20	10010 10687 10561 10794 11523 14012 13559 13786	-0 3 9 5 28 30 32 20	10614 10430 11241 11749 11575 13633 14196 14818	2 5 5 2 11 12 5	10441 10794 10923 10922 11677 13680 14048 14976	1 5 6 2 12 12	8 655665 10 655665 12 655665 12 666666 7 666666 4 665666 3 666666 1 666666	23 25 35 01 35 53 02 45 25 03 55 36 23 26 27 01 37 01 02 45 25 03 57 28
SCAN M SOURCE	HA RMS/100	AMPIR2RPHI	AMP1L2	LPHI	AMP193	Інчя	AMP1L3	LPHI	AMP2R3	RPHI	AMP2L3	LPHI	NREC TPOWER	LST
SCAN M SOURCE 14978 SD P0114-21 14983 SD P0114-21 14989 SD P0114-21 14978 XD P0114-21 14983 XD P0114-21 14989 XD P0114-21	HA RMS/100 -01 39 000000 -00 48 000000 -01 39 000000 -01 39 000000 -01 48 000000 00 10 000000	AMPIR 2RPHI 2064 15 2292 -24 2260 -0 698 9 838 -39 801 -4	2166 2167 2250 639 784 860	LPHI -22 -0 10 -38 -3	2170 2307 2293 626 739 771	20 -16 -3 -25 -23	2136 2171 2191 604 773 770	21 -16 2 24 -25 0	2266 2336 2383 648 740 808	-4 -7 -3 -20 -16 -9	2247 2258 2274 582 771 790	-5 -7 -4 -16 -19 -13	NREC TPOMER 8 655665 6 555665 8 655665 7 776777 6 665666 7 665666	LST 23 36 05 00 26 41 01 26 05 23 36 05 00 27 11 01 26 05
14978 SD P0114-21 14983 SD P0114-21 14989 SD P0114-21 14978 XD P0114-21 14983 XD P0114-21	-01 39 000000 -00 48 000000 -01 10 000000 -01 39 000000 -00 48 000000	2064 15 2292 -24 2260 -0 698 9 838 -39	2166 2167 2250 639 784	15 -22 -0 10 -38	2170 2307 2293 626 739	20 -16 3 25 -23	2136 2171 2191 604 773	21 -16 2 24 -25	2266 2336 2383 648 740	-4 -7 -3 -20 -16	2247 2258 2274 582 771	-5 -7 -4 -16 -19	8 655665 6 555665 8 655665 7 776777 6 665666	23 36 05 00 26 41 01 26 05 23 36 05 00 27 11
14978 SD P0114-21 14983 SD P0114-21 14989 SD P0114-21 14989 XD P0114-21 14983 XD P0114-21 14983 XD P0114-21 14983 XD CYOX-3 14982 XD CYOX-3 14982 XD CYOX-3 14985 SD 3C147 15000 SD 3C147 15013 SD 3C147 15022 SD 3C147 15022 SD 3C147 15025 XD 3C147	-01 39 000000 -00 48 000000 00 10 300000 -01 39 000000 00 10 000000 03 45 000000 03 45 000000 -04 43 000000 -02 24 000000 -02 14 000000 -04 10 000000 -04 10 000000 -04 23 000000 -04 23 000000 -04 23 000000 -04 23 000000 -04 23 000000 -04 25 000000	2064 15 2292 -24 2260 -0 698 -9 838 -39 801 -4 3755 20 2335 74 13689 4 13218 4 12258 13 12718 14 5944 28 5633 18 5944 28 5633 18	2166 2167 2250 639 784 860	15 -22 -0 10 -38 -3 21 72 5 4 14 15 27 16 25 44	2170 2307 2293 626 739 771	20 -16 3 25 -23 3 14 54 -0 -1 7 9 13 4 8 30	2136 2171 2191 604 773 770 2164 13440 12431 11809 12233 5539 4600 4913	21 -16 2 24 -25 0	2266 2336 2383 648 740 808	-4 -7 -3 -20 -16 -9	2247 2258 2274 582 771 790	-5 -7 -4 -16 -19 -13	8 655665 6 555665 7 776777 6 665666 7 665666	23 36 05 00 26 41 01 26 05 23 36 05 00 27 11 01 26 05 00 16 28
14978 SD P0114-21 14983 SD P0114-21 14989 SD P0114-21 14989 SD P0114-21 14989 XD P0114-21 14989 XD P0114-21 14989 XD P0114-21 14982 XD CYCX-3 14982 XD CYCX-3 14982 XD CYCX-3 14988 SD SC147 15010 SD SC147 15013 XD SC147 15000 XD SC147 15000 XD SC147 15000 XD SC147 15000 XD SC147 15000 XD SC147	-01 39 00000 -00 48 000000 00 10 300000 -01 39 000000 00 10 000000 03 45 000000 -04 43 000000 -02 24 000000 -02 24 000000 02 23 000000 -00 14 300000	2064 15 2292 -24 2260 -0 698 -9 838 -39 801 -4 3755 20 2335 74 13689 4 13218 4 13218 4 13218 13 12718 14 5944 28 5633 18	2166 2167 2250 639 784 860 3790 2150 12675 12534 12331 12239 5268 5193 4926	15 -22 -0 10 -38 -3 21 72 5 4 14 15 27 16 25	2170 2307 2293 626 739 771 3919 2128 14120 12900 12304 12674 5554 5251 4464	20 -16 3 25 -23 3 14 54 -0 -1 7 9 13	2136 2171 2191 604 773 770 3730 2164 13440 12431 11809 12233 5539 5394 4600	21 -16 2 24 -25 0 15 53 -0 -1 7 9	2266 2336 2383 648 740 808 3949 2112 13270 12891 12279 12698 5305 4891 4303	-4 -7 -3 -20 -16 -9 4 15 5 5 5 5 5 13 12 15	2247 2258 2274 582 771 790 3775 2129 13161 12727 12061 12573 5564 5218 4439	-5 -7 -16 -19 -13 3 17 5 5 5 5 14 13 15	8 655655 6 555665 8 655665 7 776777 6 665666 8 655665 3 665566 7 656665 7 666665 4 555665 7 65666 7 665666	23 36 05 00 26 41 01 26 05 23 36 05 00 27 11 01 26 05 00 17 43 00 17 43 00 16 03 05 26 02 08 05 25 00 56 46 03 16 33 05 26 32
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Fig. III-28. INTSCRIB display of scan averages for all data on CALTAPE generated with INTCAL.

SCAN	М	SOURCE	н	A :	RMS/100	AMP IR	1Hqas	AMP1L2	LPHI	AMPIR:	BRPHI	AMP1L3	LPHI	AMP2R3	RPHI	AMP2L3	LPHI	NREC	TPOWER	. 1	ST	
15010	XD	3C138	-00	23	000000	2346	-9	2292	-6	2310	-12	2304	-13	2311	6	2312	6	6	776776	04	56	26
15021	XD	3C138	01	28	000000	2531	-23	2510	-22	2514	-21	2549	-22	2581	2	2641	2	5	666666	06	47	36
15014	SD	DA267	-03	48	000000	4786	5	4738	5	4980	0	4889	0	4856	5	4910	5	. 7	555665	05	36	30
15014	XD	DA267	-03	48	000000	11260	17	11362	18	12103	1	12026	2	11761	17	11824	18	6	665666	05	36	30
15015	50	P1116+12	-05	31	000000	1892	16	1862	15	1855	13	1908	14	1950	0	1980	1		666666		45	
15020	50	P1116+12	-04	41	000000	1952	6	1791	6	1936	5	1843	4	1830	1	1840	1		655665		36	
15015	XD	P1116+12	-05	31	000000	1521	39	1535	39	1438	38	1404	40	1652	3	1563	4		676676		46	
15020	XD	P1116+12	-04	41	000000	1546	19	1459	21	1572	16	1500	16	1494	4	1437	6	6	665666	06	36	30
15016	SD	P1055+01	-05	01	000000	3500	-22	3132	-22	3405	-19	3273	-19	3353	-3	3342	-2		666666		55	
15016	XD	P1055+01	-05	01	000000	3536	-61	3316	-60	3415	-51	3296	-52	3950	-9	3894	-9	5	666666	05	55	33
15017	SD	P0859-14	-02	55	000000	2548	-5	2809	-5	2760	-1	2760	-1	2814	-3	2839	-5		655665		05	
15017	XO	P0859-14	-02	54	000000	1769	-21	1967	-17	1829	-6	1876	-8	2059	-13	2032	-13	8	666666	06	06	13
15023	н	1216+48	-03	45	000		0	949	-54		0	946	-56		0	1015	3		555665		31	
15023	M	1216+48	-03	45	0 0 0	930	-164		0	951	-173		0	1065	9		0	17	555665	08	31	51
15024	H	1242+41	-04	02	000		0	1125	29		0	1088	24		0	1268	3		555665		40	
15024	M	1242+41	-04	02	000	612	74		0	650	59		0	596	16		0	14	555665	08	40	33
15025	н	1244+49	-03	57	000		0	761	157		0	775	163		0	835	-5		555665		48	
15025	М	1244+49	-03	57	000	170	122		0	219	128		0	456	-15		0	14	555665	08	48	35
15026		1315+34	-04	18	000		0	500	29		0	526	24		0	515	5		555665			27
15026	М	1315+34	-04	18	0 0 0	529	74		0	535	57		0	529	16		0	17	555665	08	57	27
15027	н	1317+52	-04	11	000		0	443	2		0	335	5		0	987	13		555665		06	
15027	M	1317+52	-04	11	000	447	69		0	455	51		0	539	19		0	13	555665	09	06	45
15028	н	3C286			000		0	9950	0		0	10430	-0		0	10270	1		556665		15	
15028	м	3C286	-04	14	000	5400	-4		0	5653	-5		0	5492	2		0	17	556665	09	15	48

Fig. III-28 continued.

## Data File Inputs to INTCAL

Name of File	Required or Optional	Information	Max. No. of Cards	Format
SYSIN	Required	INCLUDE/EXCLUDE Cards	40	FREE
DATA.AMPCALS	Optional*	Source Name XBAND Flux XBand Flux WEIGHT	30	A10,3F10.3
DATA.PHICALS	Optional*	Source Name	100	8A10
DATA.JUMPS	Optional	Correlator Number**	12	212,5(18,IX,F5.2)

\* If not supplied, a default list is used.

\*\*Correlator No. 1-6: SBAND; 1R2R 1L2L 1R2R 1L3L 2R3R 2L3L 9-14: XBAND; 1R2R 1L2L 1R2R 1L3L 2R3R 2L3L

e.g., sample input card:

14 2 2448248 5.75 2448249 7.53

meaning that XBAND 2L3L underwent two jumps, one at LST =  $5^h40^m$ , LSD = 2448248 and another at LST =  $7^h32^m$ , LSD = 2448249.

The following program was used to obtain an example of INTCAL output:

```
//_EXEC_INTCAL,INTAPE=3086,INNAME=CORRTAPE,
//_OUTTAPE=3087,OUTNAME=CALTAPE,OUTDISP=NEW
//_SYSIN_DD_*
INCLUDE_14969_15028
//_EXEC_INTAVG,INTAPE=3087,INNAME=CALTAPE,
//_PARM='ARITH'
```

//SYSIN\_DD\_\*
INCLUDE\_SBAND
END\_REWIND
INCLUDE\_XBAND
//\_EXEC\_INTSCRIB,PARM='LIST,SORT'
 (results shown in Figures III-26, 27 and 28).

In Figure III-26 the lists of phase calibrators, flux calibrators, and convolution times are shown. In Figure III-27 we see, for each correlator and frequency, plots of the following as functions of LST: (1) a plot of the phase center solution ( $\phi_S$ ) obtained from the phase calibrators; (2) a plot of the individual scan average phase (P) for each phase calibrator, (3) a plot of the gain solution (CPFU) obtained from the flux calibrator data; and (4) a plot of the individual scan average gains (CPFU) for the flux calibrators.

In the example being used so many calibrators are involved that the solutions are unusually good. We also see that there were negligible drifts with time.

Finally, the INTSCRIB display of all the results in Figure III-28 gives us the scan average amplitude (A) and phase ( $\Phi$ ) for each scan and correlator. Note that, indeed, all the phases are close to zero and the indicated flux densities are, on the average, as they should be.

The place of INTCAL in the data processing is shown in the flow diagram in Figure III-1.

## (f) INTRED to Completely Process Interferometer Data

The aim of the automatic programs like INTCLEAN, INTCORR, and INTCAL is to make it possible to process interferometer data as quickly as possible. Under many circumstances they can be coupled together to complete all data processing during a single run on the 360/50. Because of this there is a program called INTRED (referring to interferometer

data reduction) which is used to automatically process the data on all interferometer data tapes when they arrive in Charlottesville. INTRED is automatically run by the computer operators and accomplishes the following purposes.

- (1) A copy of all the data on each 7-track telescope tape (headers, A/D records, data records, etc.) is written on a 9-track archive tape that serves as back-up raw data storage in case something happens to other copies of the data.
- (2) Another copy of all the raw data is written on another 9-track magnetic tape which is assigned to a particular observer. This tape corresponds to the RAWTAPE discussed in this chapter; however, it will be assigned a name consisting of the word RAW and letters identifying a particular observer, e.g., RAWRMHJ.
- (3) Another copy of the raw data is written on a disk data set named INTERF.DUALFREQ.TODAYDTA. Every run of INTRED causes the contents of this data set to be replaced by the contents of the new telescope tape.
- (4) A listing of record type, scan number and LST for data which have been flagged as bad by the DDP116 is produced. The usual listing of the numbers of the different types of records written on the data tapes is also given.
  - (5) An INTINDEX display of the data is obtained.
- (6) An INTSCRIB display, with PARM='LIST', is given for all 30-second data records on the data tape.
- (7) INTCLEAN is run on the raw data and the output is passed to a temporary disk data set (&&CLEAN). This provides the user with a diagnostic message listing and summary. Partial cleaning is also carried out, with a record of the deletions being a part of the data diagnostics.
- (8) INTCORR is run on the output from INTCLEAN. The output of INTCORR, with either PHASE, AMPCOR, and CLOCK corrections applied, or

these plus BASELINE corrections, is written on a 9-track magnetic tape that we have called CORRTAPE in this chapter; however, it will be assigned a name consisting of the word CORR and letters identifying a particular observer, e.g., CORRRMHJ. The observer should note that INTCORR will not process the scans in which baseline parameters are fouled up; it simply passes the data with only PAC applied. The INTINDEX-like output of INTCORR will inform the user when such situations occur.

- (9) INTCAL is run on the output of INTCORR, and the results are written on a tape that is called CALTAPE in this chapter; however, it will be assigned a name consisting of the word CAL and letters identifying a particular observer, e.g., CALRMHJ. Since INTCAL is fairly prone to failure because of data problems that cannot be cured with INTCLEAN and INTCORR, sometimes this step will not be executed and the observer will have to run a judicious combination of INTEDIT and INTCAL to obtain a proper CALTAPE.
- (10) To facilitate the capability of the user to get rapid access to his CALTAPE output, a copy of this output is written on a disk data set called INTERF.DUALFREQ.TODAYCAL. Each separate run of INTRED causes the contents of this data set to be replaced.
- (11) INTSCRIB with CPFU, PLOT, SORT, NOGRID, and RANGE = 2000 options is run on scan averaged (using INTAVG) INTCAL output so one can evaluate whether the CPFU are close to 1000 and the phases are near zero for all calibrators.
- (12) Finally, an INTSCRIB is run with LIST and SORT options on all INTCAL output which has been scan averaged and separated by frequency. From this the user can quickly evaluate many of the results obtained for all of the sources.
- (13) Finally an INTCORAV display is given for all calibrated data scans.

Given the INTRED output, with the data processing results recorded on RAWTAPE, CORRTAPE and CALTAPE, the user can evaluate whether

the results are satisfactory for all stages. If they are not, he can go back to the last stage at which he is satisfied (or the RAWTAPE) and carry out his own data processing with appropriate combinations of all the available interferometer programs.

If polarization calibration is desired, the user will still need to use INTPCAL and INTPCOR to carry the LR and RL correlators from the CORRTAPE stage to the CALTAPE stage. Obviously the first CALTAPE generated is applicable only to LL and RR correlators and a second CALTAPE must be generated with calibrated LR and RL correlators.

## (g) Calibration of LR and RL Correlators

Earlier in this chapter we discussed the theoretical principles underlying polarization observations and polarization calibration for the interferometer. The calibration of LR and RL correlators is, in practice, accomplished by a combination of two programs: INTPCAL to determine the instrumental polarization constants and INTPCOR to apply these constants to the calibration of LR and RL correlators.

## (1) INTPCAL to Determine Instrumental Polarization Parameters

The polarization calibration of LR and RL correlators begins with the data at a stage where LL and RR correlators are fully calibrated ( $V_{\rm LL}$  and  $V_{\rm RR}$ ), but LR and RL correlators are in the  $V_{\rm LR}^{\prime}$  and  $V_{\rm RL}^{\prime}$  states. That is, all cleaning and correcting has been accomplished.\*

It is assumed that all the dual-mode data was liberally interspersed with at least 15 or 20-minute observations of polarization calibrators (see Appendix 2) with known values of m (degree of linear

<sup>\*</sup> The LR and RL visibilities functions have also been multiplied by  $g_{\mbox{S}}$  exp (- $\phi_{\mbox{S}}$ ) for the associated LL correlators.

polarization) and  $\chi$  (position angle). It is also assumed that all sources have negligible circular polarization so that the assumption by which three complex gains per correlator were reduced to two is valid. INTPCAL solves for complex constants (not functions of time) designated GG and DD for a particular correlator. In terms of the known m and  $\chi$  and Equations III-12, the GG's and DD's are determined from

$$\frac{v_{LR}}{v_{LL}} = m \exp (2i\chi) = GG_{LR} \cdot \frac{v_{LR}^{\dagger}}{v_{LL}} + DD_{LR}$$
and
$$\frac{v_{RL}}{v_{LL}} = m \exp (-2i\chi) = GG_{RL} \cdot \frac{v_{RL}^{\dagger}}{v_{LL}} + DD_{RL}.$$

Comparing with Equation III-(12), this means that

$$GG_{LR} = G'_{LR}$$

$$GG_{RL} = G'_{RL}$$

$$DD_{LR} = G'_{LR, I}/G'_{LL}$$

$$DD_{RL} = G'_{RL, I}/G'_{LL}$$

Once the GG's and DD's have been determined for each LR and RL correlator, Equation III-(13) can be used to calibrate all data taken in dual-mode during the same time period.

For a complete discussion of polarized data processing, the user should consult the documentation written by J.F.C. Wardle concerning the use of INTPCAL. We will now present a very brief discussion of this usage.

There are two critical problems that must be solved in order to calibrate polarization data: (1) You need regular interspersed observations of good polarization calibrators; and (2) you must decide what segments of the observations are to be considered to have the same

values for the complex gains, e.g., jumps and drifts of parameters must be represented by successive segments of time during each of which constant parameters are assumed. Unfortunately, there are only about half a dozen SBAND calibrators with polarization parameters that are generally agreed upon; and only 2 or 3 XBAND calibrators have the same status. As if this were not enough of a problem, because of the relatively poor signal-to-noise it is difficult to identify changes in the instrumental polarization parameters. Perhaps the situation may improve considerably in the near future, but at the moment it is a difficult problem.

Aside from these difficulties, the calibration of LR and RL correlators is quite straightforward. Let us consider an example whereby scans 17257 through 17313 have been taken in dual mode; furthermore, observations of 3C48, 3C286, and 3C147 have been liberally interspersed throughout. The program INTPCAL can be used to determine the GG's and DD's for all LR and RL correlators for both frequencies using the following program:

```
//_EXEC_INTPCAL,INTAPE=3087,INNAME=TCALTAPE
//DUMP.SYSIN_DD_*
INCLUDE_17257_17313_3C48
INCLUDE_17257_17313_3C286
INCLUDE_17257_17313_3C147
//POLAR.SYSIN_DD_*
INCLUDE_17257_17313
//CALTABLE_DD_*
```

11	3	0	0	1	4	2	0	0	1
3C48		2.09		60.0		1.0			
3C286		9.23		30.9		1.0	SBAND		
3C147		0.66		46.75		1.0			
3C48		5.7		-70.0		1.0 }	XBAND		
3C286		11.5		32.0		1.0			

where the first card read into CALTABLE specifies desired parameters for the solution and its output while the remaining cards give the sources, their values of m and  $\chi$ , and their relative weights.

The five parameters to be specified for each frequency for which one desires solutions are:

- (i) LAMBDA = wavelength involved, specified as 11 if 2695 MHz is involved and 4 if 8085 MHz is involved.
- (ii) NUMBER = number of calibrators for which data is to be supplied for a particular frequency.
- (iii) CARDS = -2 if you want no punch output
  - = -1 if you want solution according to weights assigned calibrators, resulting GG's and DD's to be punched out on cards.
  - = 0 if you want solution with equal weight to all calibrators, resulting GG's and DD's being punched on cards.
- (iv) CYCLE ≠ 0 if you want the solution repeated successively leaving out one calibrator at a time (useful if you are unsure about quality of some calibrators).
  - = 0 if you want only one solution using all calibrators.
- (v) DELAY = 0 if you want a solution for each of the ten delay steps.
  - = 1 if you want results for all delay steps averaged together.
  - = 2 if you want a solution with two delay steps, one averaging all delay steps before crossover and one averaging all delay steps after cross-over.

In the sample program the first card read into CALTABLE has

- 11 so that 11-cm data is processed first
- 3 because data for 3 SBAND calibrators will be read in
- 0 so that unweighted solution is obtained and associated GG's and DD's punched on cards
- O so that only one solution is obtained
- 1 so that all delay steps are averaged together

then

- 4 so that 3.7-cm data is processed next
- 2 because data for 2 XBAND calibrators will be read in, with the remaining XBAND options chosen to be the same as for SBAND.

In practice, it has not yet been conclusively shown that there is any advantage to considering solutions for the ten delay steps separately. Therefore, use of DELAY = 1 is recommended. The other options are up to the user, and one usually tries a number of combinations in the process of obtaining a final solution.

The present version of INTPCAL contains many more options and many more pages of output than the observer usually needs; therefore, we will not show examples of the output in figures. However, we can summarize what is obtained:

- (i) A listing of the assumed parameters for each calibrator.
- (ii) A tabulation of the number of data records, and the amplitude and phase for  $V_{LL}$ ,  $V_{LR}^{'}/V_{LL}$ ,  $V_{RL}^{'}/V_{LL}$ , and  $V_{RR}^{'}/V_{LL}$  for each correlator, and the delay steps chosen. With a page devoted to each calibrator, this data shows the input to the solutions for the GG's and DD's.
- (iii) A table giving the real and imaginary parts, the amplitude and phase, the number of data records, and the rms error of the amplitudes for solutions for LR and RL correlators for each delay combination chosen. The GG's and DD's are described as "GAIN" and "DEFLECTION".

- (iv) Another page in which
  - (A) All delay steps are averaged whether or not they had previously.
  - (B) Closure is checked.
  - (C) Average closure differences are shown.
- (v) A presentation of the calibrated results for each source, i.e.,  $V_{LL}$ ,  $V_{LR}/V_{LL}$ ,  $V_{RL}/V_{LL}$ , and  $V_{RR}/V_{LL}$  are tabulated in detail for each correlator and chosen delay steps. In addition, for each source the assumed values of m,  $\chi$ , |Q|, and |U| are listed together with what their values are if obtained after the solution is applied to the data. In addition, the rms (for m) and  $|m_{ORS}-m_{CAL}|$  are calculated.
- (vi) Finally, tables of polarization parameters as functions of hour angle and declination are presented so that unusually bad data points may be detected.

When two frequencies are evaluated, this output is repeated for the second frequency.

The format for (LAMBDA, NUMBER, CARDS, CYCLE, DELAY) for first 11 then 4 centimeter data is (1015).

After the options are read in by the first card supplied to CALTABLE, one reads in: source name, m,  $\chi$ , and a relative weight for each calibrator in the format(A10,3F10.2). When two frequencies are to be processed, first the cards for SBAND calibrators are provided, then those for XBAND calibrators.

Note that INTPCAL does not write the calibrated data on tape or disk data set.

## (2) INTPCOR to Apply Polarization Calibration

Given the cards for the GG's and DD's punched out by INTPCAL, INTPCOR is used to apply the polarization calibration to both calibrators and other sources, writing the results on tape. For example,

where the first card in the INSTRPOL data file gives LAMBDA and DELAY for both frequencies in format (415), and the GG's and DD's are then read in. After INTPCOR has written  $V_{LL}$ ,  $V_{RR}$ ,  $V_{LR}$ , and  $V_{RL}$  on the CALTAPE, so that on this tape all data is in the form  $V = A \exp(i\phi)$ , INTAVG, INTSCRIB (with XPOL option) and INTPOLAV are used to obtain information about the final calibrated LR and RL data.

APPENDIX 1\*

POSITIONS AND FLUX DENSITIES<sup>†</sup>FOR AMPLITUDE AND PHASE CALIBRATORS

Source	<sup>α</sup> 1950	δ1950	σ(α)	σ(δ)	S <sub>2695</sub>	S <sub>8085</sub>	Weight For Fluxes
P0056-00	00 <sup>h</sup> 56 <sup>m</sup> 31.76	-00°09'18"4	0.02	0"5	1.8	1.1	0.2
**P0106+01	01 06 04.48	+01 19 01.0	0.04	1.0	2.6	4.1	0.4
P0114-21	01 14 25.91	-21 07 53.4	0.03	1.0	2.3	0.7	0.3
****3C48	01 34 49.82	+32 54 20.7	0.01	0.2	9.0	3.3	1.0
***NRAO91	02 02 07.41	+14 59 50.5	0.01	0.3	3.8	2.7	0.4
D0224+67	02 24 41.13	+67 07 39.9	0.03	0.1	1.2	1.9	0.1
*P0237-23	02 37 52.77	-23 22 04.8	0.02	0.7	5.1	2.1	0.2
*****CTA21	03 16 09.12	+16 17 40.3	0.04	0.7	5.0	1.7	0.8
****NRA0140	03 33 22.40	+32 08 36.8	0.01	0.2	2.7	2.1	0.6
*NRA0150	03 55 45.25	+50 49 20.6	0.02	0.1	5.9	9.7	0.1
P0403-13	04 03 14.02	-13 16 20.8	0.04	1.2	2.7	1.7	0.2
**P0413-21	04 13 53.65	-21 03 52.0	0.03	1.1	1.6	0.85	0.5
***P0420-01	04 20 43.53	-01 27 28.1	0.02	0.7	1.3	1.5	0.7
***3C119	04 29 07.88	+41 32 08.6	0.05	0.7	5.4	2.2	0.5
<b>*3</b> C120	04 30 31.62	+05 14 59.2	0.03	0.5	6.7	12.8	0.1
**P0438-43	04 38 43.24	-43 38 56.2	0.03	0.7	5.8	2.7	0.2
NRAO190	04 40 05.30	-00 23 20.6	0.05	1.2	2.6	2.0	0.2
***P0451-28	04 51 15.14	-28 12 29.9	0.02	0.6	2.2	2.0	0.5
****3C138	05 18 16.52	+16 35 27.3	0.01	0.2	5.6	2.8	0.6
****3C147	05 38 43.50	+49 49 42.9	0.02	0.1	12.7	5.0	0.8
P0556+28	05 56 30.94	+28 18 09.9	0.01	0.2	0.45	0.20	0.1
*P0605-08	06 05 35.97	-08 34 18.4	0.03	1.0	3.1	3.7	0.2
P0607-15	06 07 26.02	-15 42 04.2	0.03	0.9	1.5	2.7	0.1
P0614-34	06 14 48.81	-34 55 08.6	0.02	0.5	1.7	0.9	0.3
DA207	06 21 41.88	+32 06 47.1	0.01	0.2	1.0	0.44	0.3
01318	07 11 05.62	+35 39 52.6	0.01	0.2	1.8	1.2	0.2
**D0727-11	07 27 58.13	-11 34 53.5	0.03	0.9	2.6	4.8	0.5
**P0735+17	07 35 14.12	+17 49 09.5	0.01	0.3	2.0	1.8	0.4
**P0736+01	07 36 42.51	+01 44 00.3	0.02	0.4	2.1	1.6	0.4
*01363	07 38 00.17	+31 19 02.5	0.01	0.2	2.3	1.9	0.2
*D0742+10	07 42 48.46	+10 18 32.9	0.01	0.3	3.9	3.0	0.3
**P0743-00	07 43 21.04	-00 36 55.3	0.02	0.4	1.3	1.6	0.4
***P0834-20	08 34 24.65	-20 06 31.4	0.03	0.8	2.5	2.6	0.6
**P0859-14	08 59 54.96	-14 03 38.6	0.03	0.9	2.7	1.7	0.4
**P0906+01	09 06 35.19	+01 33 48.1	0.02	0.5	0.98	1.1	0.4
***DA267	09 23 55.29	+39 15 24.3	0.01	0.2	4.8	10.7	0.7
3C232	09 55 25.39	+32 38 23.4	0.01	0.2	0.90	0.66	0.3
***3C236	10 03 05.39	+35 08 48.1	0.01	0.2	2.1	0.95	0.4
**P1015-31	10 15 53.44	-31 29 12.5	0.02	0.6	2.2	1.0	0.5
*P1116+12	11 16 20.74	+12 51 06.6	0.06	1.2	1.7	1.2	0.5
***P1127-14	11 27 35.69	-14 32 54.9	0.03	0.9	6.4	4.5	0.7
*P1148-00	11 48 10.10	-00 07 12.9	0.05	0.9	2.4	1.3	0.4
P1151-34	11 51 49.42	-34 48 46.4	0.02	0.7	4.2	2.2	0.2
*3C268.3	12 03 54.08	+64 30 18.7	0.03	0.1	2.0	0.60	0.4

<sup>\*</sup> The number of asterisks reflect overall reliability as both amplitude and phase calibrators,

<sup>†</sup> Except for 3C48 and 3C286, none of the flux densities listed here are to be relied upon, since most either change with time or are poorly determined.

Source	<sup>α</sup> 1950	<sup>δ</sup> 1950	σ(α)	σ(δ)	S <sub>2695</sub>	S <sub>8085</sub>	Weight For Fluxes
P1237-10	12 <sup>h</sup> 37 <sup>m</sup> 07 <sup>s</sup> 29	-10°07'00"6	0.03	1.0	1.4	0.85	0.2
**P1245-19	12 45 45.22	-19 42 57.6	0.03	0.8	3.6	1.5	0.5
*3C279	12 53 35.82	-05 31 07.4	0.02	0.6	13.0	12.5	0.1
****3C287	13 28 15.96	+25 24 37.0	0.01	0.2	4.6	2.2	0.7
****3C286	13 28 49.68	+30.45 58.3	0.01	0.2	10.1	5.2	1.0
***P1345+12	13 45 06.19	+12 32 20.0	0.01	0.3	3.8	2.4	0.6
OQ323	14 13 56.29	+34 58 29.5	0.01	0.2	1.6	0.88	0.2
3C298	14 16 38.86	+06 42 19.4	0.03	0.7	2.6	1.0	0.3
***3C309.1	14 58 56.61	+71 52 11.3	0.04	0.1	5.3	2.5	0.5
P1508-05	15 08 14.97	-05 31 49.4	0.02	0.4	2.7	2.0	0.2
*P1510-08	15 10 08.88	-08 54 46.7	0.03	1.0	2.5	2.6	0.2
D1548+05	15 48 06.90	+05 36 12.4	0.02	0.4	2.3	2.2	0.1
D1555+00	15 55 17.68	+00 06 44.2	0.02	0.7	1.4	1.5	0.3
*P1607+26	16 07 09.29	+26 49 18.7	0.01	0.2	3.0	0.95	0.2
***DA406	16 11 47.92	+34 20 20.0	0.01	0.2	2.4	2.1	0.7
***3C345	16 41 17.61	+39 54 11.3	0.01	0.2	8.7	10.6	0.3
***NRA0530	17 30 13.48	-13 02 45.6	0.07	1.6	3.9	4.6	0.6
**3C371	18 07 18.55	+69 48 57.0	0.03	0.1	1.8	2.1	0.2
****3C395	19 01 02.29	+31 55 14.2	0.01	0.2	3.2	2.2	0.9
*0V080	19 47 40.13	+07 59 36.9	0.02	0.4	1.3	0.9	0.2
****3C418	20 37 07.41	+51 08 36.0	0.06	0.8	4.0	3.3	0.8
***P2128-12	21 28 52.76	-12 20 23.3	0.04	1.2	1.7	1.6	0.7
P2145+06	21 45 36.05	+06 43 40.4	0.06	1.3	3.9	3.0	0.2
P2149-28	21 49 10.57	-28 42 36.5	0.02	0.6	1.9	0.8	0.1
*3C446	22 23 11.02	-05 12 17.3	0.02	0.4	5.2	3.8	0.2
BLLAC	22 00 39.37	+42 02 08.8	0.01	0.2	6.0	6.2	0.1
3C454.3	22 51 29.52	+15 52 53.7	0.02	0.3	11.0	10.0	0.1
P2345-16	23 45 27.61	-16 47 50.1	0.03	1.0	3.2	3.6	0.1

 $\label{eq:appendix 2} \text{LIST OF POLARIZATION CALIBRATORS}^\dagger$ 

Source	m	χ	m	Х
	2695	MHz	808	5 MHz
****3C48	2.09	60.0	5.74	<b>-</b> 70.5
****3C147	0.70	44.0	1.45	- 7.5
****3C286	9.20	30.9	11.0	31.7
*3C309.1	2.0	84.0		
*P0237-23	2.1	137.0	4.6	-30.2
*P1127-14	2.4	29.0	3.2	-38
*CTA102	5.3	17.1		
*3C287	3.1	-75.5		

The asterisks next to each source name denote the extent to which different observers agree on the polarization constants.

APPENDIX 3

NAMES OF DEFAULT INPUT AND OUTPUT DISK DATA SETS FOR STANDARD PROGRAMS

Program	Input Name	Output Name
INTLOOK	&&OUTNAME	
INTSCRIB	&&OUTNAME	
INTCOPY	&&OUTPUT	&&OUTNAME
INTAVG	&&OUTPUT	&&OUTNAME
INTINDEX	&&OUTNAME	
INTCORAV	&&OUTNAME	
INTPOLAV	&&OUTNAME	
INTBCAL	&&OUTNAME	
INTCLEAN	&&OUTNAME	&&CLEAN
INTCORR	&&CLEAN	&&CORR
INTCAL	&&CORR	&&CAL
INTMAP	&&OUTNAME	&&OUTMAP

#### APPENDIX 4

# PEOPLE TO TALK TO ABOUT PROBLEMS OR TO OBTAIN INFORMATION

#### IN GREEN BANK

Name

Type of Problem

Jane Gordon

Dorm room assignments, transportation on

site.

Operator On Duty

Operating status of instrument, recent

problems.

Len Howell

Over-all problems with mechanical opera-

tion of instrument.

Jim Coe

William Shank

James Oliver

Electronics problems.

Ron Weimer

Digital problems involving DDP116.

Ed Fomalont

Observers "friend" for interferometer, instructions concerning observing procedures, scientific considerations

involved in observing.

Dave Hogg

Scheduling of interferometer time, changes in observing programs.

#### IN CHARLOTTESVILLE

Name

Type of Problem

Donna Beamer

Obtaining user number for 360/50.

Phyllis Jackson

Arrangements concerning NRAO's share of

publication page charges and pre-

prints for NRAO files.

#### Name

## Type of Problem

Ann Jackson (or Computer Operators) Checking out magnetic tapes.

Linda Blankenship

Problems involved in setting up and running standard interferometer programs, aid in solving data processing problems.

Bill Meredith

Serious data processing problems where detailed knowledge of contents and algorithms of standard interferometer programs is needed, documentation on program contents.

George Conant

On-line programs for DDP116.

Bob Hjellming

Observers "friend" for interferometer data processing, interferometer documentation, scientific considerations involved in data processing.

#### APPENDIX 5

## CHECK LIST OF THINGS TO BE DONE BEFORE, DURING AND AFTER OBSERVING

## Months Ahead of Observing Time

- 1. Prepare observing request specifying
  - a) Scientific justification for program.
  - b) Sources to be observed.
  - c) Amount of time and LST range desired.
  - d) Desired configuration or configurations.
  - e) Special equipment needed. (If special equipment is involved, consultation with Green Bank personnel considerably ahead of time is absolutely necessary.)
- 2. Send copies of observing request to
  - a) D. E. Hogg (Green Bank).
  - b) D. S. Heeschen (Charlottesville).
  - c) W. E. Howard (Charlottesville).

## Weeks Ahead of Observing Time

- Make arrangements with W. E. Howard concerning NRAO subsidy for travel to Green Bank.
- Arrange for lodging and transportation needs on Green Bank site (Jane Gordon).
- 3. Take care of detailed planning of observing program with schedule of observing time in hand (will be sent to you by D. E. Hogg). Be sure scientific objectives are compatible with practical details of scheduling (see Chapter II).

## Day Ahead of Observing Time

- Inform Wade Davis (head computer operator) or Ann Jackson in Charlottesville concerning disposition of daily INTRED output.
- 2. Check with Ed Fomalont (Green Bank), George Grove (Green Bank), Linda Blankenship (Charlottesville), or Ann Jackson (Charlottesville) about status of accurate baselines and whether the good baselines will be read in by either the DDP116 in Green Bank or during INTRED processing in Charlottesville.
- Check with Ed Fomalont (Green Bank) or George Grove (Green Bank) concerning accuracy of pointing solutions being used.
- 4. Punch out program deck, where possible keeping at least 12 hours and preferably 24 hours ahead of the observing. Check for hour angle and mountain limitations. Assign dump times for disk to tape transfer by DDP116 (see Chapter II).

#### While Observing

- Be present, if possible, whenever program decks are loaded into DDP116 (at beginning of program and after each dump). Errors may be detected that need immediate fixing by the observer before the observing can commence again.
- Keep operators informed of your location and telephone extension at all times.
- 3. Initial the form kept by the operators indicating the name of the observing program, the observers involved, their home institutions, and which observers are students (if any).
- 4. Inform operator concerning your wishes about disposition of: teletype output, analog records, and observing logs.

- 5. Periodically throughout the program acquaint yourself with status of equipment and possible problems.
- 6. Periodically examine the on-line data display (see Chapter II) for all sources, but most importantly calibrators. Even if you are not interested in evaluating your scientific results on-line, you can detect many mal-functions simply by noting that the data does not look "right".
- 7. Changes in the observing program can be made within minutes, if desired (a key punch machine is in the building), with the only price being a few minutes loss of observing time during the reloading process.

## After Observing (or Interspersed with Observing Where Possible)

- 1. Evaluate your data output through examination of at least the INTRED output.
- 2. Carry out data processing for each successive day of observing. INTRED will always be applying INTCLEAN, INTCORR, and INTCAL to the data for each day. With a little bit of work, evaluating the data and taking care of problems not solvable with these automatic programs, the user can usually keep the data processing no more than one day out of step with the observing. This is very useful both for learning about problems early and for keeping track of whether desired scientific objectives are being obtained.
- 3. The observer may chose to produce synthesis maps of day to day results. This is the simplest and most complete way of obtaining most scientific results.

## Weeks to Months After Observing

- 1. Complete analysis of data.
- When writing scientific papers involving data taken on NRAO instruments the authors must fulfill one of the conditions under which they are granted observing time. They must acknowledge the extent to which NRAO equipment is involved and either by footnote or acknowledgement include the sentence: "The National Radio Astronomy Observatory is operated by Associated Universities, Inc. under contract with the National Science Foundation".
- 3. After papers are written and submitted to a journal, the authors should discuss arrangements concerning NRAO's payment of part of the page charges, and pre-prints for the NRAO files, with Phyllis Jackson in Charlottesville.
- 4. When magnetic data tapes are no longer needed, inform Ann Jackson so they can be re-used.
- 5. Finally, the observer is cautioned that most people find it most convenient, if not absolutely necessary, to carry out all data reduction and analysis in Charlottesville. Those attempting to do so on computers at their own institutions face many difficult problems.