

VLBI ARRAY COMPUTER USAGE
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VLBI ARRAY MEMO No. 4

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4 I. Introduction5
6 Both computing hardware and data analysis are developing sufficiently
7 rapidly that accurate predictions for the computing needs of the VLB
8 array are not possible. This report will, instead, examine the requirements
9 of a ten antenna array on computing facilities currently available in
10 Charlottesville.
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12 II. Post-correlation Processing.

13 A. Continuum

- 14 1) In the current Charlottesville system the first post-correlation step
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- 15 is to correct the data for peculiarities in the processor and to
-
- 16 pre-average the 0.2 second integrations from the correlator to
-
- 17 several seconds in order to reduce the volume of the data. In newer
-
- 18 correlators such as those at Cal-Tech and Haystack much of this
-
- 19 step is done on-line by the correlator/computer. In Charlottes-
-
- 20 ville this is done in the IBM 360.
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- 21
-
- 22 2) Following pre-averaging is the fringe fitting step which results
-
- 23 in the estimates of the complex correlation coefficient, group
-
- 24 delay and fringe delay rate from data coherently averaged for several
-
- 25 minutes. This step is also done in the IBM 360 in Charlottesville.
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- 26
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- 27 3) After fringe fitting the data is edited, removing bad data.
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- 29 4) Current practice is to calibrate the correlation amplitudes
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- 30 to Janskys using measured system temperatures and antenna
-
- 31 sensitivities. Except in certain phase referencing experiments
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- 32 phase calibration is considered hopeless at this stage and is
-
- 33 ignored.
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- 34
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- 35 5) Finally the phases are iteratively calibrated and the map
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- 36 produced by a technique known as self calibration or hybrid
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- 37 mapping. In this technique the current model of the source
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- 38 (CLEAN point components or the initial guess) is used to
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- 39 calibrate the phases relative to an arbitrary position in the
-
- 40 sky. This technique makes use of the fact that the number
-
- 41 of calibration phases needed is
- $N-1$
- and the number of observed
-
- 42 phases is
- $N*(N-1)/2$
- where
- N
- is the number of antennas involved.
-
- 43 Similar amplitude calibration is also possible and likely
-
- 44 necessary for 1.3 cm observations. For VLBI observations this
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- 45 step is currently done on the Charlottesville VAX using the

46 Cal-Tech VLBI package but in the future the VLA package will
47 almost certainly be used. Thus the Fred Schwab's self-calibration
48 program was used for timing purposes for this report.
49

50 B. Spectral Line

- 51 1) Program DECODE preaverages the correlator output.
52
53 2) Program AVERAGE corrects clock drifts, residual phase delay
54 rates and makes instrumental phase corrections; then averages
55 both the cross and auto correlations.
56
57 3) Program BOG transforms the auto correlations to obtain source
58 spectra and then corrects auto and cross correlations for
59 effects of the bandpass
60
61 4) Program CVEL corrects the data for the Earth's motion.
62
63 5) Program CAL calibrates the cross correlations using the
64 total power spectra obtained from the autocorrelations.
65
66 6) Program PHSREF calibrates phases relative to a reference feature.
67
68 7) Program SWAMP, used in editing the data, displays coherent fits
69 to each spectral channel; usually used several times.
70
71 8) Programs SWAMP, JANET and DUNE produce a fringe rate map
72 prior to aperture synthesis.

73
74 After the above programs are run, the data are fully calibrated
75 and can be analysed by VLA spectral line software.
76

77 III. Computing requirements

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79 A. Continuum

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81 Computing requirements for various stages of processing were determined
82 from timing the processing of sample data in the appropriate computer.
83 Correction, preaveraging and fringe fitting were done in the IBM 360;
84 the CPU time requirements for these steps are shown in Table 1.
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Table 1

95 Continuum: pre - Mapping (IBM 360 CPU times)

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97 Step	Baseline hour	Array hour (10 ant.)
98		
99 correction and		
100 preaveraging	0.80 min.	36.1 min.
101 fringe fitting	0.45 min.	20.5 min.
102		
103 Total	1.25 min.	56.6 min.

104

105 Editing and initial amplitude calibration use so little CPU time
 106 that their requirements are negligible compared to the uncertainty in
 107 the other steps and are thus ignored. However, editing and calibration
 108 are the stages which require the most user interaction and are normally
 109 repeated several times. If in the future amplitude calibration is
 110 done using VLA software initial amplitude calibration may become non-
 111 trivial in the computing budget (see the self calibration description
 112 for a crude estimate of the time requirements).

113 To determine the time requirements for self calibration, a VLA data set
 114 using 10 antennas with 35,763 data points was used. This is approximately
 115 the amount of data in 12 hours of 1 minute integrations from a ten
 116 antenna array. For this test, Fred Schwab's self calibrations program
 117 was used to do both amplitude and phase self calibration.
 118 The REAL run times for the MODCOMP were recorded and the results are
 119 summarized in Table 2. For comparison IBM 360 CPU times for the same
 120 mapping and CLEANing tasks are also shown in Table 2.

121 It is not clear how many iterations through the self calibration
 122 procedure will be necessary for 10 antenna data but 10 is probably a
 123 safe guess.

124

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TABLE 2

126 Continuum: Mapping and CLEANing

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128 Step	MODCOMP real time	IBM 360 CPU time
129		
130 Mapping 256X256 cells	5.5 min.	6.2 min.
131 CLEAN 127X127 500 comp.	8.3 min.	8.2 min.
132 Self calibration	17.2 min.	
133 (full complex)		
134		
135 Total (1 pass)	31.0 min.	
136		
137 Per source (10 passes)	310. min. = 5.2 hrs.	

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139 B. Spectral Line.

140 The CPU time required for programs 1-8 were determined from sample data
 141 processed on the IBM 360. These results are summarized in Table 3.

142

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TABLE 3.

144 Spectral Line: pre - Mapmaking (IBM 360 CPU times)

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146

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149 AVERAGE

150 BOG

151 CVEL

152 CAL

153 PHSREF

154 SWAMP

155 SWAMP, JANET, DUNE

156

157 TOTAL

158

159 Since VLA spectral line software is not yet available, an estimate
 160 of the computing requirements must be made from the continuum test. The
 161 mapping and CLEANing could be done as for continuum maps but separately
 162 for each frequency channel. In the following estimates 256 spectral
 163 channels were assumed; Table 4 shows these estimates.

164

165

TABLE 4

166

Spectral line: MODCOMP real time.

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173 Total

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176 IV. Hardware and Software Development.

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A. Continuum

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If VLA software is used for editing and calibration then no
 independent software development past the fringe fitting stage will
 be necessary. The speed of the correlator correction, pre-averaging
 and fringe fitting could be improved up to a factor of 10 with the

184 use of an Array Processor. In view of the large amount of CPU time
185 required for these steps, an Array Processor would appear to be vital.
186 In addition, the development of more sophisticated calibration and
187 fringe fitting techniques may be able to take advantage of the large number
188 of baselines to make substantial improvements in sensitivity over the current
189 techniques. However, such techniques are likely to significantly
190 increase the computing requirements.

191 The MODCOMP self-calibration programs described above make limited use
192 of an array processor. These programs will undoubtedly be improved; for
193 instance, an experimental version of a CLEANing program of the type designed
194 by B. Clark did an equivalent CLEAN to the one described in Table 2 in
195 1.4 min. MODCOMP real time.

196

197 B. Spectral Line

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199 Many of the programs described in Section II could be adapted to
200 use with an array processor, reducing the enormous computing load.
201 Past the calibration stage, VLA software will be completely adequate
202 and no independent development is necessary. Since spectral line
203 mapping and CLEANing for VLA data produce similar problems it is likely
204 that a more efficient method than the one discussed here will be
205 developed.

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Appendix to VLBA Memo #4 Computer Usage :

or How much is that in real money?
W. Cotton and J. Benson 28 Aug 1980

The purpose of this appendix is to update VLBA memo #4 and to state the estimated post-correlation computer requirements. As in all such estimates, the numbers quoted here should be viewed with some skepticism.

I. Continuum Fringe Fitting.

The values given in VLBA memo #4 in Table 1 were based on Mk II values and are not entirely relevant to the VLBA. Estimates of Mk III fringe searching are based on values obtained from A. Rogers at Haystack from their experience with the Mk III correlator. One example: 8.5 min of data searched, 2 sec preaveraging, 14 tracks
Disk I/O = 40 sec
mostly FFT search = 120 sec.
search window = 0.8 Hz and 0.5 microsec.

The figures given above were based on a firmware FFT which does a full complex 1024 point FFT in 200 millisecc.; the advertised time for the same operation on an FPS array processor is 6 millisecc. A crude conversion of the above values to the usage on a machine with an array processor is 0.25 CPU-Hr / baseline hour; or 11 such systems to keep up with the processor. It should be noted that the time is 80% disk I/O. This requirement can be reduced in several ways: 1) the fringe search window can be restricted and data preaveraged for longer times. If the amount of I/O can be reduced by a factor of 10 then one computer plus array processor will be sufficient. 2) In the case of strong sources, either the amount of data recorded can be reduced and/or only a subset of the data used for the fringe search.

II. Usage Requirements:

In order to estimate the amount of computing required Table 1A uses the values given above and in VLBA memo #4. The requirements are expressed in units of a minicomputer (such as a VAX) with an array processor.

Table 1A
Total Computer Usage Requirements

Process	No. Minicomputer + Ap
Cont. pre-mapping	1
Cont. mapping	0.5
Spectral pre-mapping *	1
Spectral mapping *	1
Total	3.5

* Spectral line observations assumed 20% of the time.