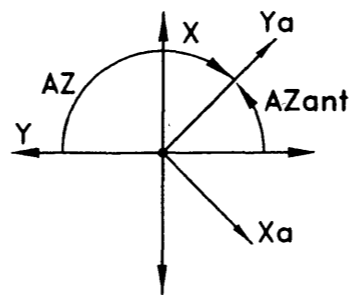
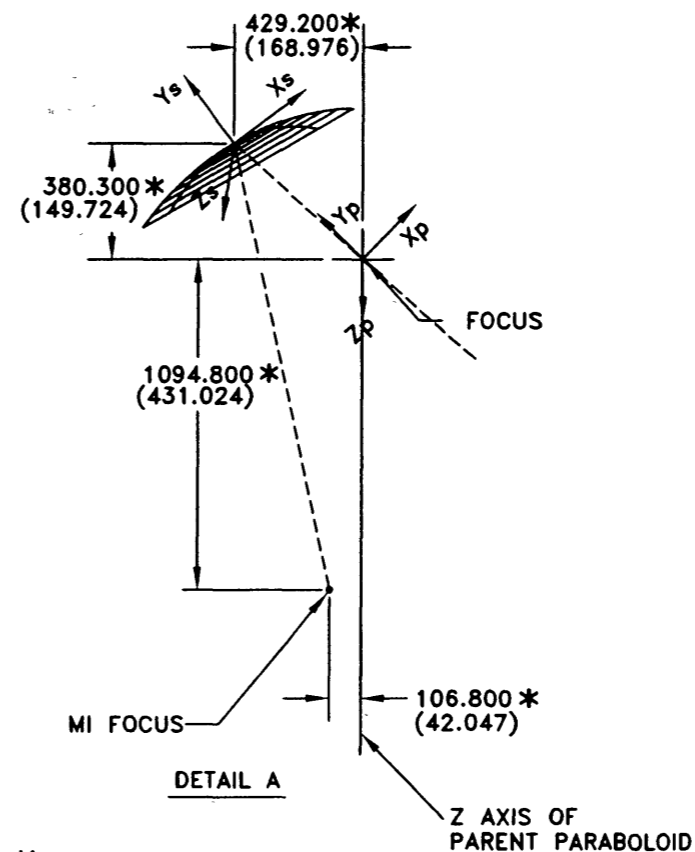
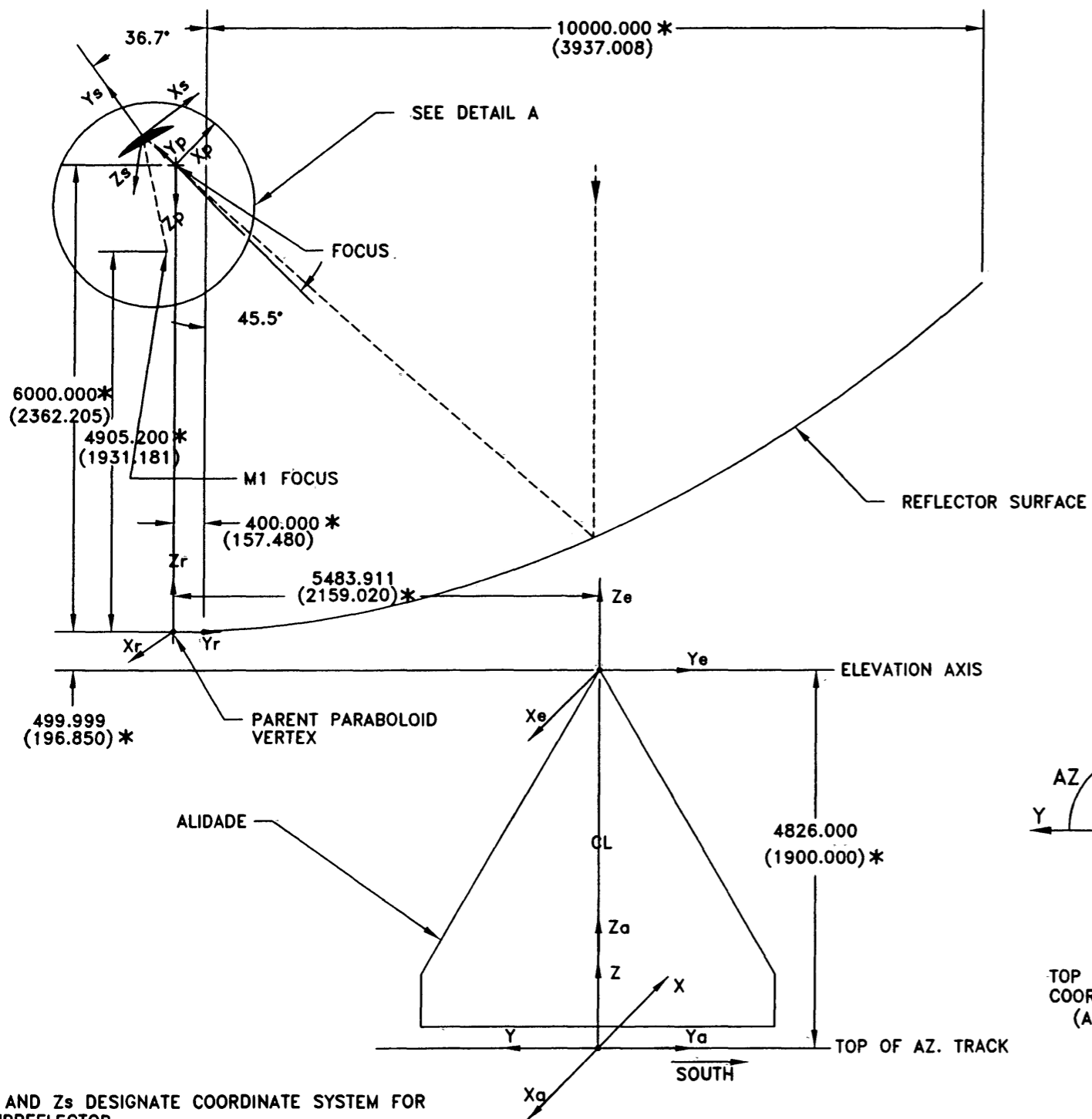


* INDICATES DIMENSIONAL DESIGN

CENTIMETERS
(INCHES)



TOP VIEW OF ALIDADE
COORDINATE SYSTEM
(AZant=0)

COORDINATE SYSTEMS
(AZant=0°
ELant=90°)

NOTES:
Xs, Ys AND Zs DESIGNATE COORDINATE SYSTEM FOR THE SUBREFLECTOR.
Xp, Yp AND Zp DESIGNATE COORDINATE SYSTEM FOR THE PRIME FOCUS.
Xr, Yr AND Zr DESIGNATE COORDINATE SYSTEM FOR THE REFLECTOR STRUCTURE.
Xe, Ye AND Ze DESIGNATE COORDINATE SYSTEM FOR THE ELEVATION STRUCTURE.
Xa, Ya AND Za DESIGNATE COORDINATE SYSTEM FOR THE ALIDADE.
X, Y AND Z DESIGNATE THE BASE COORDINATE SYSTEM.
SEE SHEETS 2 THRU 5 FOR COORDINATE TRANSFORMATION EQUATIONS.

UNLESS OTHERWISE SPECIFIED
DIMENSIONS ARE IN INCHES

TOLERANCES
ANGLES ±
3 PLACE DECIMALS (.xxx)±
2 PLACE DECIMALS (.xx)±
1 PLACE DECIMALS (.x)±
FRACTIONS: ±

MATERIAL:
FINISH:

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TITLE FOCI ARRANGEMENT AND
COORDINATE SYSTEMS
FOR THE GBT

DESIGN		RECOMMENDED BY	
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CHECKED		APPROVED	
SCALE	1:500	SHEET	1 of 5
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Definition of Coordinate Systems:

The Base Coordinate System, (X, Y, Z).

The base coordinate system is fixed to the ground. Its origin is at the intersection of the antenna azimuth axis and the top of the azimuth track.

The positive directions of the axes are defined as follows:

X-axis towards East
 Y-axis towards North
 Z-axis points up

The azimuth angle (AZ) is measured from the Y-axis and is positive in the clockwise direction looking from the positive Z side.

The Alidade Coordinate System, (Xa, Ya, Za).

The alidade coordinate system is attached to the alidade structure. It rotates about the antenna azimuth axis. Its position is defined by the azimuth antenna angle.

The positive azimuth antenna angle (AZant) is measured from the negative Y axis in the counter-clockwise direction. When AZant is zero, the orientations of the axes are:

Xa-axis towards West
 Ya-axis towards South
 Za-axis points up


Therefore, $AZ = 180 \text{ degrees} - AZ_{ant}$. The transformation between the two coordinate systems, (1) and (2), are:

$$\begin{bmatrix} X \\ Y \\ Z \end{bmatrix} = R_{12} \begin{bmatrix} X_a \\ Y_a \\ Z_a \end{bmatrix}$$

where

$$R_{12} = \begin{bmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} \cos(AZ_{ant}) & -\sin(AZ_{ant}) & 0 \\ \sin(AZ_{ant}) & \cos(AZ_{ant}) & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

UNLESS OTHERWISE SPECIFIED DIMENSIONS ARE IN INCHES	
TOLERANCES	
ANGLES ±	
3 PLACE DECIMALS (.000): ±	
2 PLACE DECIMALS (.00): ±	
1 PLACE DECIMALS (.1): ±	
FRACTIONS: ±	
MATERIAL:	
FINISH:	

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3. The Elevation Coordinate System, (Xe, Ye, Ze).

The elevation coordinate system is attached to the elevation structure. It rotates with the elevation structure defined by the elevation and the azimuth antenna angles.

When the elevation antenna is 90°, ELant = 90°, its axes are positioned in the same directions as that of the alidade coordinate system.

The relation between the Elevation and Alidade coordinate systems is given as follows:


$$\begin{bmatrix} X_a \\ Y_a \\ Z_a \end{bmatrix} = R_{23} \begin{bmatrix} X_e \\ Y_e \\ Z_e \end{bmatrix} + T_{23}$$

where

$$R_{23} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & \sin(EL_{ant}) & \cos(EL_{ant}) \\ 0 & -\cos(EL_{ant}) & \sin(EL_{ant}) \end{bmatrix}$$

$$T_{23} = \begin{bmatrix} 0 \\ 0 \\ +1900.000 \end{bmatrix}$$

1900.00 is the height in inches of the elevation axis about the top of the track.

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UNLESS OTHERWISE SPECIFIED
DIMENSIONS ARE IN INCHES

TOLERANCES
ANGLES ±
3 PLACE DECIMALS (.000): ±
2 PLACE DECIMALS (.00): ±
1 PLACE DECIMALS (.0): ±
FRACTIONS: ±

MATERIAL:
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4. The Reflector Coordinate System, (Xr, Yr, Zr).

The reflector coordinate system is obtained by translations of the elevation coordinate system. This is shown in the following equation:

$$\begin{bmatrix} X_e \\ Y_e \\ Z_e \end{bmatrix} = \begin{bmatrix} X_r \\ Y_r \\ Z_r \end{bmatrix} + T_{34}$$

where

$$T_{34} = \begin{bmatrix} 0 \\ -2159.020 \\ 196.850 \end{bmatrix}$$

The offsets of the reflector paraboloid vertex from the elevation axis is given in inches by T34.

5. The Prime Focus Coordinate System, (Xp, Yp, Zp).

The origin of this coordinate system is at the focus of the dish paraboloid, 2362.205 inches from vertex of the paraboloid on the Zr-axis.


Yp-axis is 45.5° from Zr-axis on the ZrYr plane, and the Zp-axis is parallel to the Xr-axis. The transformation is as follows:

$$\begin{bmatrix} X_r \\ Y_r \\ Z_r \end{bmatrix} = R_{45} \begin{bmatrix} X_p \\ Y_p \\ Z_p \end{bmatrix} + T_{45}$$

where

$$R_{45} = \begin{bmatrix} 0 & 0 & 1 \\ \cos(45.5^\circ) & -\sin(45.5^\circ) & 0 \\ \sin(45.5^\circ) & \cos(45.5^\circ) & 0 \end{bmatrix}$$

$$T_{45} = \begin{bmatrix} 0 \\ 0 \\ 2362.205 \end{bmatrix}$$

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TOLERANCES
ANGLES ±
3 PLACE DECIMALS (.000): ±
2 PLACE DECIMALS (.00): ±
1 PLACE DECIMALS (.X): ±
FRACTIONS: ±

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6. The Subreflector Coordinate System, (Xs, Ys, Zs).

The axes of this coordinate system are orientated similarly as that of the prime focus coordinate system. The angle between Ys-axis and Zr-axis is 36.7°. By the same token, we have:

$$\begin{bmatrix} X_r \\ Y_r \\ Z_r \end{bmatrix} = R_{46} \begin{bmatrix} X_s \\ Y_s \\ Z_s \end{bmatrix} + T_{46}$$

where

$$R_{46} = \begin{bmatrix} 0 & 0 & 1 \\ \cos(36.7^\circ) & -\sin(36.7^\circ) & 0 \\ \sin(36.7^\circ) & \cos(36.7^\circ) & 0 \end{bmatrix}$$

$$T_{46} = \begin{bmatrix} 0 \\ -168.976 \\ 2511.929 \end{bmatrix}$$

7. Examples:

a. For a point L from the reflector coordinates to the base coordinates.

$$\begin{bmatrix} X \\ Y \\ Z \end{bmatrix}_L = R_{12} \left[R_{23} \left[\begin{bmatrix} X_r \\ Y_r \\ Z_r \end{bmatrix}_L + T_{34} \right] + T_{23} \right]$$

b. For a point M from the base coordinates to the reflector coordinates.

$$\begin{bmatrix} X_r \\ Y_r \\ Z_r \end{bmatrix}_M = R_{23}^{-1} \left[R_{12}^{-1} \begin{bmatrix} X \\ Y \\ Z \end{bmatrix}_M - T_{23} \right] - T_{34}$$

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 1 PLACE DECIMALS (.0): ±
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