

MEMO # 29

July, 22, 1975

Telephone conversation with John Payne.

Subject - Pointing error from servo control

Measurements on 36-ft and 45-ft showed a 5 bits peak to peak, and 1.25 bit rms tracking error. If the encoder has a ~~24~~<sup>22</sup> bits ( $0.3 \text{ s}^{\circ}$ ), then it is reasonable to conclude that the the servo error is  $1.25 \times 0.3 \approx 0.4 \text{ s}^{\circ}$  and  $0.5 \text{ s}^{\circ}$  is a good round-off figure.

The 36-ft has a  $5 \text{ s}^{\circ}$  pointing during usual operation (peak) and  $2 \text{ s}^{\circ}$  peak at a very good condition. It has a 20-bit encoder. If the 1.25 bit rms is considered a performance at usual condition, then the calculated pointing of the 36-ft is

$$1.25 \times 1.23 = 1.54 \text{ s}^{\circ} \text{ rms} \quad (15)$$

$$= 4.63 \text{ s}^{\circ} \text{ pk} \quad (35)$$

which is ok with the  $5 \text{ s}^{\circ}$  quoted.

J. P. would not speculate the pointing for the future.

Also 36-ft has bad bearings!