# Azimuth Towers for Homelogous 300-Fost

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The present report mainly gives the design data for the complete azimuth structure with two towers. A detailed analysis of its performance will follow soon.

## I. Requirements

#### 1. Size

The size of the 300-ft dish structure is shown in Fig. 1. For the towers we then obtain:

Point 5 must have clearance for the back-up structure of the dish, as shown in Fig. 1.

The azimuth rails are standard railroad (no special foundation). For making the towers tetrahedral (they are shown in Fig.2), we need

#### 2. Loads for Survival

We consider the weight of dish and snow, survival winds, and dumping snow, with the following data:

- points 4: weight of complete dish

  4: maximum snow (20 lb/ft<sup>2</sup> whole area)

  4: wind on dish (85 mph, full side-area, C<sub>s</sub>= 1.3)

  4: additional force from torque (asymmetry)

  4: dumping 6 inch of snow, plus 45 mph wind

  2430 kip = 1100 tons (3)

  1454 kip = 660 tons (4)

  1050 kip = 476 tons (5)

  334 kip = 153 tons (6)

  269 kip = 118 tons (7)
- Since (7) is less than (6), it was omitted. Although (4) is larger than (5), it turned out that (5) always gives larger stresses, we thus emit (4) in the following. The wind force on the tower members is included, using C = 1 for pipes. The stress in each member then is calculated for three different load conditions:
  - 1) Simultaneously a) dead load of tower, b) weight of dish, with 1215 kip each on points 4 and 4a in z direction. Call S. (8)
  - 2) x-wind only; with simultaneously a) 693 kip each on points 4 and 4a,

<sup>\* (</sup>s = shape factor

in x direction, b) 334 kip on point 6, in -x direction, c) wind force on all tower members, in x direction. Call  $S_x$ . (9)

3) Same as above, but replace x by y, and -x by -y. (= y-wind only) Call S $_{\rm v}$ . (10)

The maximum stress, for any wind direction, then is obtained as

$$S_{m} = |S_{1}| + \sqrt{S_{x}^{2} + S_{y}^{2}}$$
 (11)

#### 3. Loads for Wind Deformation

The velocity adopted is 18 mpk (wind is below this value for 3/4 of all time); the total area, face-on, is used, and a shape factor of 1.56. In addition, the maximum torque is added. Two load conditions are calculated:

4) 64.9 kip each on points 4 and 4a, in x direction, and simultaneously
31.3 kip on point 6, in -x direction, plus wind force on all tower members.(12)

The maximum deformation then is simply

$$\Delta_{\mathbf{m}} = \max(\Delta_{\mathbf{x}}, \Delta_{\mathbf{y}}). \tag{14}$$

#### 4. Restraints

We need five different restraints for the following five cases:

case	calculating	assuming	
A	Δ_		
В	Δ	wheels fixed along rails, but seft perpendicular;	
С	s		(15)
D	x S	wheels soft both x and y, all taken up by pintle;	1
	у		
E	-	wheels fixed both x and y.	)

Actually, we calculate only one tower; we thus need some additional restraints for replacing the action of the second tower and for avoiding free retation. All restraints used are shown in Table 1.

To be on the safe side, maximum stresses  $S_m$  were calculated according to (11) for survival wind in all five contraint conditions, and for each member the maximum of the five values  $S_m$  was then adopted.

	1	A	Total Control out of the last		В		1	C			D		1	E	
point	x	y	3	x	У	z	×	У	z	×	у	z	×	У	z
1	r	r	r	r	r	r	r	r	r	r	r	r	r	r	r
2	r		r	r		r	,		r			r	r	r	r
3	ŗ		r	r		r			r	•		r	r	r	r
4	}			r			1			¦ r					
5	; ;						*						1		
6	;	r		ŗ			¥	r		ŗ			**************************************	r	
7	) L	r	r	r		r	ŝ	r	r	i r		r			r
8	1	r	r	·		r	ŧ	r	r	·		r	•		r

Table 1: Five restraint conditions.

#### 5. Wind Deformations

It turned out that  $\Delta_{\mathbf{x}} > \Delta_{\mathbf{y}}$ . We thus give  $\Delta_{\mathbf{x}}$  only:

The vertical distance between points 4 and 6 is 1222 inch. The deformation thus yields a pointing deviation of

$$\alpha = (.202/1222) 2.06 \times 10^5 = 34 \text{ arcsec.}$$
 (17)

Most of (17) stays constant and is corrected by the optical pointing system. For the remaining fraction of (17) we apply two reduction factors:

and the resulting pointing error then is

$$\Delta \alpha = 5.9 \text{ arcsec.}$$
 (19)

This result is acceptable. For the shortest wavelength,  $\lambda = 2$  cm, the beamwidth is 54 arc sec, and (19) then is 1/9 of the beam, for integration times of 1 sec and shorter. For longer integration times, the errors average out. An integration time of 15 sec, for example, will have a pointing error of 1/20 beamwidth.

## II. Design

The design of the towers is done the same way as that of the dish; we use long, pin-ended built-up members. This has two advantages. First, it is economical with respect to stiffness/weight as well as to maximum force/weight. Second, the analysis is broken down in two independent parts; the overall-structure is analysed considering each member as a single red with given area and density, and the member can be analysed separately. Only two types of members will be considered here.

## 1. Data for Overall-Structure

The geometry of the towers is shown in Figures 1 and 2, and the coordinates are given in Table 2. Nominal bar areas (see following section) are given in Table 3, together with the length of each member. The last column gives the type.

Table 2: Coordinates (inch)

peint	x	y	2
•	0	0	o
2	-1039	1800	0
3	1039	1800	0
4	0	1200	.1990
5	0	810	1000
6	0	o	890
7	-2078		0
	2078	0	o

Table 3: Members;  $A_{n} = bar area (inch^{2}),$ L = length (inch), t = type.

	1		Anna arr sec.
points	An	L	t
1-2	70	2078	2
1-3	70	2078	2
1-5	130	1286	4
1-6	30	<b>#9</b> 0	1
1-7	70	2078	1
1-8	35	2078	2
2-3	35	2078	2
2-4	120	2324	2
2-5	50	1749	•
2-7	40	2078	2
3-4	120	2324	2
3-5	50	1749	1
3-8	35	2078	2
4-5	140	1064	1
5-6	40	817	1
6-7	70	2261	•

#### 2. Data for Member Design

The built-up member is shown in Figures 3 and 4. Table 4 gives the length  $b_c$  of the center batten (thickness of member) in terms of the member length L, and the bar area  $A_p$  of the pyramid, area  $A_c$  of the chords,  $A_b$  of the battens,  $A_d$  of the diagonals, and  $A_t$  of the little triangles, all in terms of the nominal member area  $A_n$  as used in Table 3.

Table 4: Design of built-up members.

	b <sub>c</sub> /L	A <sub>p</sub> /A <sub>n</sub>	A <sub>c</sub> /A <sub>n</sub>	A <sub>b</sub> /A <sub>n</sub>	A <sub>d</sub> /A <sub>n</sub>	A <sub>t</sub> /A <sub>n</sub>
type 1	.0557	.421	.2603	•0407	.0444	.0182
type 2	.0808	.411	.2603	.0527	.0424	.0182

Fellowing this precedure then results in a table of bar areas for each bar in each member. All bars are pipes; the actual bar area is taken as the one from the Steel Manual which comes closest (up or down) to the one in the table.

#### 3. Preliminary Data for Foundation

The maximum reactions at the tower legs (point 3 and 3) are about 650 tons downward and 130 tons uplifting. Each tower leg will stand on a support fixed on several cars; support and cars will provide already some counterweight, and the rest may be concrete (or just rocks) in the cars, for balancing the 130 tons. The maximum down force on each leg then is

With a maximum load of 33 tons/axle (see Report 14 of Sept. 1966), we then need 24 axles, or six heavy gendelss of 4 axles each, for each of the four tower legs. They could be arranged on a double railroad as shown in Figure 5.

The maximum forces on the central pintle bearing are about

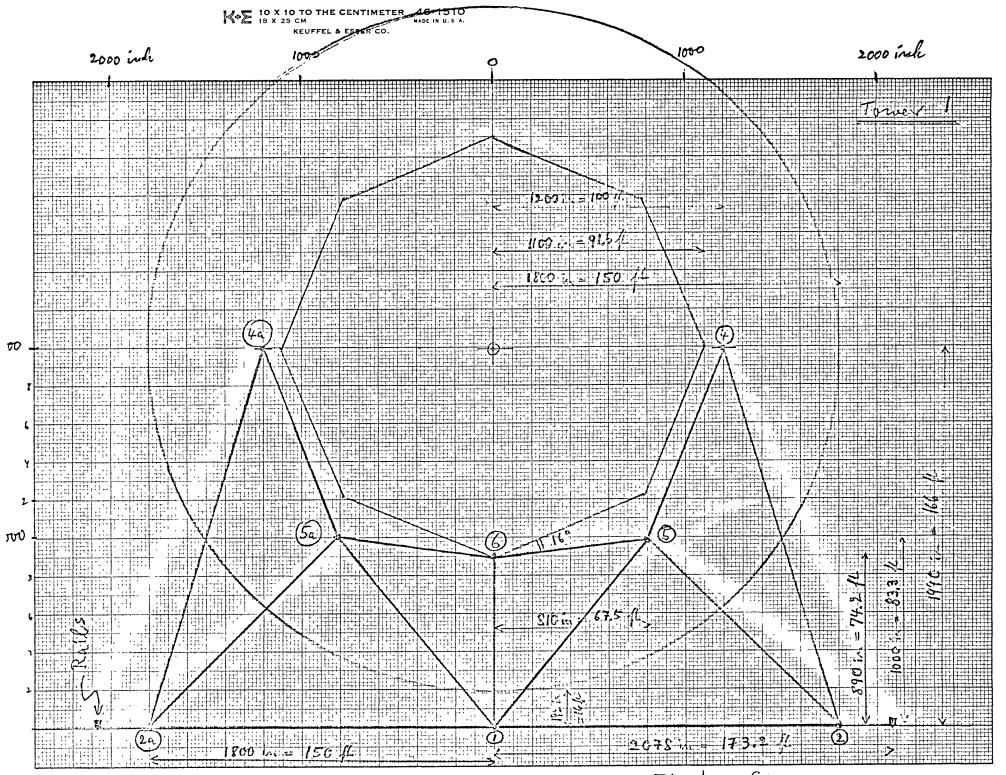
# Changes for Tower

In Report 19 (Oct. 18, 68), please make the following changes:

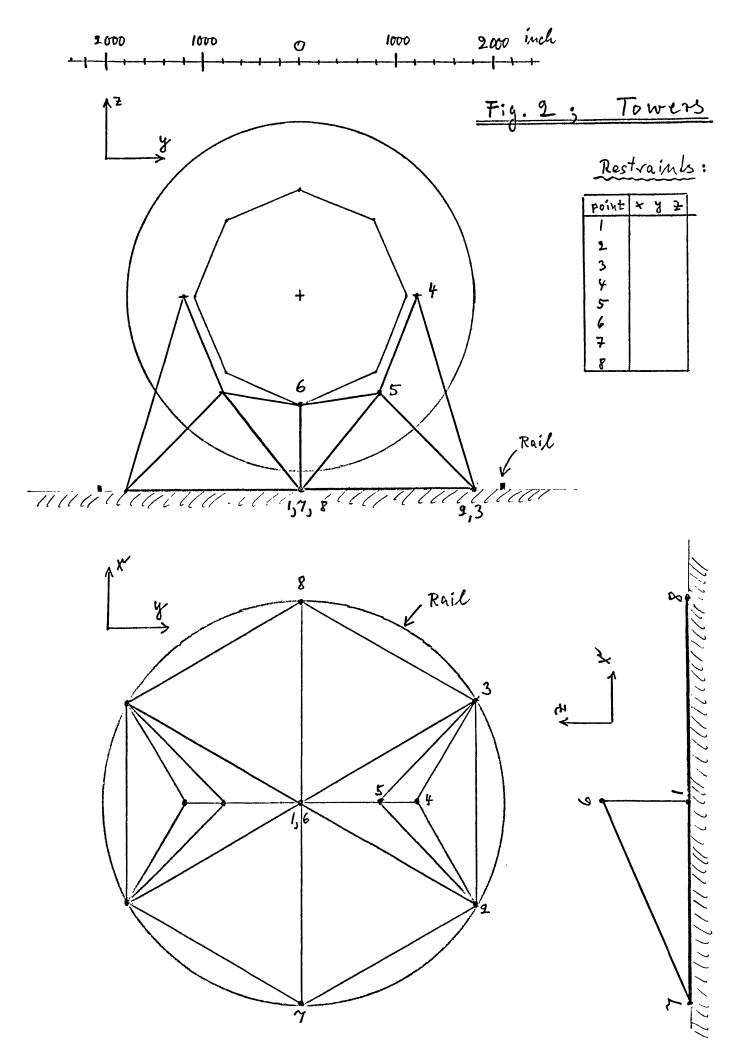
1.	In Table 3:	points	$^{\mathbf{A}}\mathbf{n}$	t
		1-2	75	
		1-6	20	
		1-8	30	
		2-3	30	
		2-4	140	1
		3-4	140	•
		3-8	30	
		5-6	30	

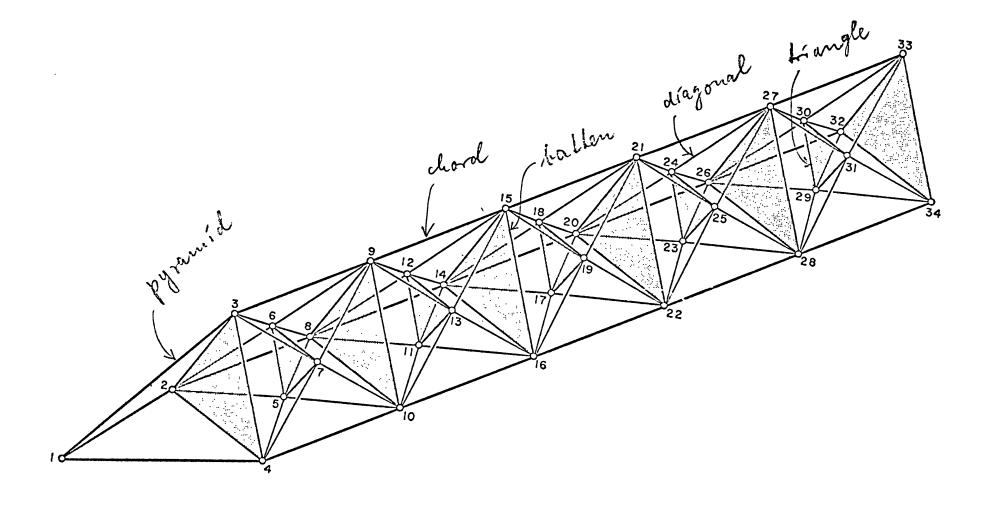
# 2. In Table 41

	Ap/An	$A_{\mathbf{c}}/A_{\mathbf{n}}$	Ab/An	Ad/An	$A_t/A_n$
type *	.430	.2738	.042 <b>8</b>	.0466	•0191
type P	.455	-290 <b>6</b>	•05 <b>89</b>	.0474	.0203



ia. 1: Sizes





Fig, 3
points and connections of 1/2 member.

# Parabolic Shape, m = 12

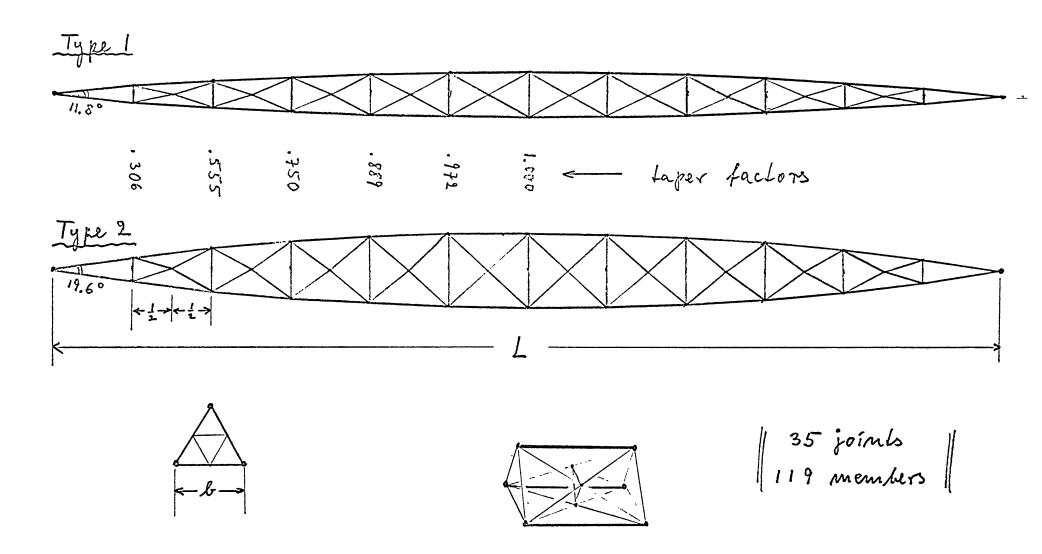


Fig. 4: Geometry of built-up members

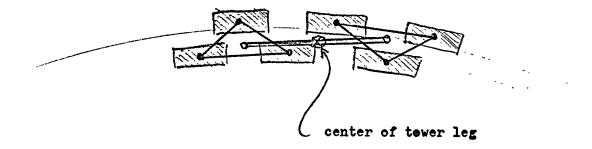


Fig. 5: Support from 6 gondolas for one tower leg.