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Subject: Where do we go from here  
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1) EXTEND THE PROTOTYPE!

Most of our effort in this prototype has been put into making self-consistent sub-systems. Very little effort has gone into making sure these subsystems can interact with one another in a simple and clear manner. It is my opinion that we need to push this "exercise" further. While I understand the time constraints on the report, we are really writing the report before we have finished the object of the report. And the last steps of putting it all together are by no means just "academic"...they are fundamental, and will tell us what is wrong with the class design.

2) A BROADER DEEPER 2ND PROTOTYPE!

Our feet are wet. Lets go for a more intense system that has more than one TelModel and possibly more than one Imaging Model. Multiple models are needed to test the "associators" scheme. Also, this enters into the realm of "detailed instrumental requirements": we could have one imaging model for the VLA and one for a linear array like AT or WSRT; we could try to do polarization calibration for the VLA and WSRT. [I am actually a bit worried about polarization.]

And finally, I think that we NEED to get some spectral line stuff into the prototype. One of the biggest fears in Socorro is that AIPS++ would not be much better than AIPS at dealing with spectral line data. We NEED to get spectral line on board as early as possible!

If we break everything down into YEGS, we need to be damn clever at reconstructing the QUADS and the SPECTRA.

3) A BROADER SYSTEM REQUIRES OBJECT PERSISTENCE!

We at least need to be able to write out images, visibility data sets.....so that we don't fall into the ONE MAIN PROGRAM syndrom. (Bob Sault suggests FITS readers and writers. This would also enable us to work with some real data sets. Performance could be tested against SDE which has a very flexible timer.)

4) GET THE REAL PROGRAMERS ONBOARD!

We should get Mark S and Bob P involved in THIS prototype...so we can test out their wares, so we don't have to design vector classes, so we can tell them what is useful and what is hard to use. Also, the last two points dealt with "associators" and object persistence. This would be a good place to deal with the DATABASE and get Chris onboard.

5) MORE INTER\_GROUP COMMUNICATION!

In the past, systems such as this one were designed by 1 or 2 people working in close cooperation. While communication inside each group seems to be fine, communication among groups is not good. I think shifting the group lines will only change the lines accross which communication does not easily flow. It may help, but wont solve.

It is my feeling that the more complicated and realistic a system we are dealing with, the more complicated and realistic problems we will uncover. There will always be hacks and fixes that can be applied to these problems, but that is EXACTLY what broke old AIPS. If AIPS++ is to be the best system we can write

at the present time, we need to program the next prototype as much like a real (but limited in some particular ways) system as we can.

Here is my suggestion for a timescale:

Spend 2.5 months designing, building, and evaluating the next prototype. Work on the current prototype would wind down as work on PROTO++ winds up.

By June 1, we need to have evaluated this prototype and be in a position to start AIPS++. I imagine a good deal of code will be reused from PROTO++ to AIPS++ if PROTO++ is designed with polarization and spectral line in mind. If the code cannot be reused, then we must consider ourselves lucky for doing such a broad prototype.

By July 1, we will have the bones of the real system. We will know how polarization and spectral line data and images fit together. It is difficult enough to convince colleagues that there is a problem when we talk to each other FACE-TO-FACE! If there are still major design flaws after July 1, we will have a LOT OF TROUBLE WORKING THEM OUT! Hence, I support a very ambitious PROTO++.

-Mark Holdaway