

# Alma Memo 454: Total Power Observing with the ALMA Antennas

Wm. J. Welch, UC Berkeley

March 2000

Originally appended to an ASAC meeting report  
Distributed as an ALMA memo in April 2003

## 1 Introduction

Particularly at the shorter wavelengths, the ALMA will need to do mosaic observing to cover large fields of view. Along with the mosaic pointing, there will need to be total power maps to fill in the interferometric short spacings and produce complete images. It is well known that this is best done with a single antenna that is two to three times the diameter of the interferometer antennas (Vogel, S. *et al.*, ApJ, 1984, 283, 655). However, that will not be possible for ALMA; there are no 24m - 36m antennas available that will work well to 0.35mm wavelength. As long as a mosaic of pointings is employed in the interferometry, a single antenna map made with one of the interferometer antennas will suffice in principle (Ekers, R. and Rots, A., 1979, In Image Formation, etc., Dordrecht, Reidel). This is rarely done, largely because the interferometer antennas are not equipped to do it. Tests done at the VLA at cm wavelengths (Cornwell, T. 1988, A&A, 202, 316.) indicate that it should work, and at mm wavelengths in the CO(1-0) line, Marc Pound made a good map of the Eagle Nebula combining a Mosaic interferometer map made with the BIMA array and a single antenna map made with the Bell Labs 7m antenna (Pound, 1998, ApJ, 493L, 113). This capability must be in place for the ALMA antennas. How it is best done may be studied with the prototype antennas.

## 2 Candidate Schemes

There are five schemes that are usually considered for this purpose. The simplest is the on/off pointing method. Here one points at the source for a short integration, perhaps 10-30 seconds, and then at blank sky for the same time, and then takes the difference. The rest of the map results from a sequence of such measurements. For spectral line observations with narrow band widths, the receiver noise is usually large enough that it dominates both the atmospheric brightness fluctuations and the noise due to receiver gain fluctuations in this method, and it works. The second scheme is to use rapid frequency switching for spectral line observing, and this also works. Neither of these procedures will work for continuum measurements. That's obvious for the second method. For the first, the wider bandwidth means that the receiver noise is lower than that due to either the atmospheric brightness fluctuations or the effects of receiver gain fluctuations.

For continuum total power observations, there are three schemes that can be used. The most common method is to employ a nodding secondary mirror. A related alternative is the focal plane chopper. The third idea is On-The-Fly mapping (Emerson, Klein, and Haslam, 1979, A&A, 76, 92).

The nodding secondary works well, except that it is difficult to get a throw of more than a few arc minutes. There are situations where one needs to chop to an "off" position that is 10-20 (or more) minutes away. This is especially the case at the shorter wavelengths where, in the Milky Way, the background dust emission is bright.

The focal plane chopper, on the other hand, can only throw large angles, typically 10 minutes or more. Other disadvantages for our application are that it is often difficult to have a good balance between the "on" and "off" and the mechanism would probably have to be mounted on each receiver separately, which could be an annoying complication for the ALMA antennas with their many receivers.

The On-The-Fly (OTF) method looks to be the most flexible and simplest, and we summarize its properties and requirements below.

## 3 OTF Mapping

The prospects for doing OTF mapping at the Chajnantor site have been discussed in detail by Holdaway, Owen, and Emerson (1995, MMA #137) (HOE). The basic idea is that a raster scan of the object under study will

be made with a very rapid turn-around of the scan at the end of each row in a region that is off the source. During the scan across the source, the receiver power is read out at a rate which corresponds to at least the Nyquist sampling of the source structure. That is, at least as often as twice per beam width. Thus, there are many "on" observations across the source with an "off" observation at the end of each row. The "off" observations last about one second during the turn-around at the end of each row. The time on each "on" observation is much smaller.

HOE used the path length fluctuations as measured by the site testing interferometer at Chajnantor to infer the expected atmospheric brightness fluctuations. They were able to work out the magnitude of the fluctuations as functions of both the time and pointing angle with respect to the source. Under the assumptions that (1) the antenna could slew as rapidly as  $1^\circ/\text{second}$ , (2) the antenna could accelerate and decelerate between normal tracking and full slew in one or two seconds, and (3) the correlator could dump the spectral data every .003s, they concluded that OTF mapping should work well at the Chajnantor site. Their Figure 2 shows that the expected receiver noise and atmospheric noise contributions will be about equal at 230 GHz 80% of the time for a scan that is as large as  $1^\circ$ . For smaller scans the situation is even better.

At the time of the HOE memo, it was not clear whether their assumptions about the antenna and correlator would be met. We now have more information about the array components. The present NRAO design for the correlator will allow correlator read-out at the rate of once every .001 second, which is fast enough to permit OTF mapping of both continuum and line observations. The planning for the antenna prototype has included studies of the capability of the antenna to carry out the OTF observing. It appears that if feed forward is used in the drive servo design, it will be possible to turn the antenna around at the end of an OTF scan in about one second as assumed by HOE. The maximum smooth scan rate will be at least about  $0.5^\circ/\text{sec}$ , comparable to the  $1^\circ/\text{sec}$  rate assumed by HOE.

One further point that needs to be considered is the required receiver gain stability for the OTF scheme to work. The planned continuum bandwidth of 8 GHz calls for unusually good gain stability. The time between any of the "ons" and the off at the end of the scan is about one second. The gain must be stable over that time interval. The fractional total power noise for one of the "on" measurements is:  $\Delta T/T = 2/\text{SQRT}(Bt_s)$ . B is the bandwidth, and  $t_s$  is the time on each source. The 2 is the usual factor due to switching. Here the long "off" time reduces the noise in the subtraction, but it is also

about twice as long as the total "on" source observing time. The fractional total power fluctuation due to gain variations is:  $\Delta T/T = \Delta G/G$ . If we take the scan time to be always one second, then  $t_s$  depends on the scan length and the beam width. For scan lengths between 5' and 60' and beam widths between 25'' (220 GHz) and 6'' (800 GHz) the time on source varies between .08 sec and .002 sec. For B=8 GHz, and equating the receiver noise fluctuation to that due to the gain fluctuation, we find a necessary gain stability in the range of  $0.8 \times 10^{-4}$  to  $5 \times 10^{-4}$ . Thus, a receiver gain stability of about  $1 \times 10^{-4}$  over a time scale of about 1 second is required for the receiver. This level of stability can certainly be achieved, but it requires careful attention to the construction of the receiver.

Another question concerns the number of antennas that must be used to achieve the necessary sensitivity in the single antenna measurements to equal the corresponding array sensitivity. For approximately equal sensitivity in OTF measurements, the same amount of time must be spent on the single dish map as on any of the array baselines. That means about the same amount of time in the single dish mode as in the array mode. The only difference is in the factor of 2 in the OTF (switched) mode. That implies that a measurement with 4 antennas for the same duration as the array observation will suffice. If all the antennas have the good gain stability discussed above,  $\leq 1 \times 10^{-4}$  for 1 second and all were employed in the single antenna mode observation, only about 1/15 of the time would be needed in the latter mode. Alternatively, when the sky noise is sometimes worse, using more antennas will permit averaging that noise out.

## 4 Summary

Among all the possible methods to obtain the total power data for the array, the OTF scheme is the most attractive, and it appears that it should work. The main requirement is a fractional receiver gain stability of about  $1 \times 10^{-4}$  in a one second time interval. There should be no difficulty in achieving this. The other schemes, a nodding secondary or focal plane chopper will be more expensive and less flexible. It is important that the OTF method be tested with the Prototype antennas.